

NOISY INTERACTIVE QUANTUM COMMUNICATION*

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Abstract. We study the problem of simulating protocols in a quantum communication setting over noisy channels. This problem falls at the intersection of quantum information theory and quantum communication complexity, and it will be of importance for eventual real-world applications of interactive quantum protocols, which can be proved to have exponentially lower communication costs than their classical counterparts for some problems. These are the first results concerning the quantum version of this problem, originally studied by Schulman in a classical setting (FOCS '92, STOC '93). We simulate a length N quantum communication protocol by a length $O(N)$ protocol with arbitrarily small error. Under adversarial noise, our strategy can withstand, for arbitrarily small $\varepsilon > 0$, error rates as high as $1/2 - \varepsilon$ when parties pre-share perfect entanglement, but the classical channel is noisy. We show that this is optimal. We provide extension of these results in several other models of communication, including when also the entanglement is noisy, and when there is no pre-shared entanglement but communication is quantum and noisy. We also study the case of random noise, for which we provide simulation protocols with positive communication rates and no pre-shared entanglement over some quantum channels with quantum capacity $C_Q = 0$, proving that C_Q is in general not the right characterization of a channel's capacity for interactive quantum communication. Our results are stated for a general quantum communication protocol in which Alice and Bob collaborate, and these results hold in particular in the quantum communication complexity settings of the Yao and Cleve–Buhrman models.

Key words. Coding Theory, Communication Complexity, Quantum Computation and Information

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1. Introduction. Quantum information theory is well developed for information transmission over noisy quantum channels, dating back to the work of Holevo in the 1970's [30, 31] for the transmission of classical information [32, 48] and quantum information [39, 50, 22], and even for cases allowing pre-shared entanglement between sender and receiver [7, 8]. It describes the ultimate limits for (unidirectional) data transmission over noisy quantum channels without concern for explicit, efficient construction of codes. Closely related is the area of quantum coding theory, which takes a more practical approach toward the construction of quantum error correcting codes [49, 51] by providing explicit and efficient constructions [17, 51, 28, 16] and by

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providing bounds on their existence [16, 24, 43].

Quantum communication complexity has also been studied in depth since Yao’s paper introduced the field in 1993 [56]. It is an idealized setting in which local computation is deemed free and communication is noiseless but expensive. Two parties want to compute a classical function of their joint input while minimizing the number of qubits they have to exchange. Exponential separations have been shown for some promise problems between their classical and quantum communication complexity [15]—even in cases allowing bounded error [44]. Moreover, for both classical and quantum communication complexity, interaction has been proved to be a powerful resource: exponential separations in the communication complexity of some functions have also been established between protocols restricted to k messages, and protocols with $k + 1$ messages [42, 33]. In 1997, Cleve and Buhrman [18] defined an alternative model for communication complexity in a quantum setting, in which the players are allowed to pre-share an arbitrary entangled state but transmit classical rather than quantum bits. They proved the first separation between such a quantum model and the classical model of communication complexity (for a three party task). This model is at least as powerful as Yao’s (up to a factor of 2), since entanglement can be used to teleport [3] the message qubits with twice as many classical bits. It is still open whether the two models are essentially equivalent, since no good bound on the amount of entanglement required in the Cleve–Buhrman model is known.

With the ubiquity of distributed computing nowadays, it has become increasingly important to develop an information and coding theory for interactive protocols. In the realm of classical communication, Schulman initiated the field with his pioneering works [45, 46, 47], showing that it is possible to simulate any protocol defined over a noiseless channel with a noisy channel with exponentially small probability of error while only dilating the protocol by a constant factor. This multiplicative dilation factor, in the case of a binary symmetric channel, is proportional to the inverse of the capacity, as in the data transmission case. However, the hidden constant of proportionality does not go to 1 asymptotically. For adversarial errors, Schulman also shows how to withstand corruption up to a rate of $\frac{1}{240}$. Recent work by Braverman and Rao [14] shows how to withstand error rates of $\frac{1}{4} - \varepsilon$ in the case of an adversarial channel, and they also show that this is optimal in their model of noisy communication. Even more recently, Franklin, Gelles, Ostrovsky, and Schulman [25] were able to show that in an alternative model in which Alice and Bob are allowed to share a secret key unknown to the adversary Eve, they can withstand error rates up to $\frac{1}{2} - \varepsilon$, which is also shown to be optimal in this model.

All of the above simulations use *tree codes*, which were introduced by Schulman. Tree codes exist for various parameters, but no efficient construction is known. A relaxation of the tree code condition still strong enough for most applications in interactive coding was proposed by Gelles, Moitra and Sahai [26], and they provided an efficient randomized construction for these so-called potent tree codes. Using these in a random error model leads to efficient decoding on average hence to efficient simulation protocols (of course when given black-box access to the original protocol, which might be inefficient in itself). In a worst-case adversarial scenario, the decoding might still take exponential time with potent tree codes. It was only recently that an alternative coding strategy, developed by Brakerski and Kalai [10], was able to address the adversarial error case efficiently. Their strategy is to cleverly split the communication into blocks of logarithmic length in which tree encoding is used. In addition, they send, in between the blocks, some history information that enables efficient decoding. This construction was further improved by Brakerski and Naor [11]. A survey article

by Braverman [13] provides a good overview of results and open questions in the area of classical interactive communication circa 2011, though some of the important questions raised there have been addressed since. In particular, the question of interactive capacity of binary symmetric channels was recently investigated by Kol and Raz [34]. For this channel they find that indeed, in the low noise regime, the communication capacity behaves differently in the asymptotic limit of long interactive protocols than in the data transmission case.

Quantum communication, even more so than classical communication, is prone to transmission errors in the real world. The approach taken in all of the above is inherently classical and does not generalize well to the quantum setting. In particular, the fact that classical information can be copied and resent multiple times is implicitly used, and therefore the fact that the information in the communication register can be destroyed by noise is inconsequential. In contrast, the no-cloning theorem of quantum theory [23, 55] rules out copying of quantum messages. As a result, if the information in some communication register is destroyed, it cannot be resent. A naive strategy, which applies in the quantum as well as the classical case, would be to encode each round separately. However, in a random error model, a constant dilation of each round would not be sufficient to achieve constant fidelity in the worst case of one-qubit transmission per round, and a super-constant dilation leads to a communication rate of zero asymptotically. Moreover, in the case of adversarial errors, no constant rate of error can be withstood with such a strategy unless the number of rounds is constant: the adversary can always disrupt a whole block.

The properties of classical information made it possible for Schulman and his successors to design clever classical simulation protocols that can withstand constant error rates at constant communication rates and that can succeed in simulating classical protocols designed for noiseless channels over noisy channels by reproducing the whole transcript of the noiseless protocol. However, it was not immediately obvious that it is possible, given an arbitrary protocol designed for a noiseless bidirectional quantum channel, to simulate it over noisy quantum channels with constant error rate at a constant communication rate. Even for protocols in the Cleve–Buhrman model, in which the communication is classical, it is not clear whether we can achieve results similar to those for classical protocols. Indeed, a quantum measurement is in general irreversible. If such a measurement is performed on the shared entangled state and the players later realize that the measurement was based on wrong classical information, the naive adaptation of the classical simulation to the Cleve–Buhrman model fails.

2. Overview of Results. We show that despite the above obstacles, it is indeed possible to simulate arbitrary quantum protocols over noisy quantum channels with good communication rates. We consider two models for interaction over noisy channels. One is analogous to Yao’s model, and all communication in it is over noisy quantum channels, but the parties do not pre-share entanglement. The other is analogous to the Cleve–Buhrman model, and all communication in it is over noisy classical channels and parties are allowed to pre-share noiseless entanglement. We call these models the *quantum* and *shared entanglement models*, respectively. We also consider a further variation on the shared entanglement model in which entanglement is also noisy.

Our main focus is on the model with perfect shared entanglement but adversarial noise on the classical communication. In such a context, the number of errors is defined to be the Hamming distance between the transcript of sent messages and

the transcript of possibly corrupted received messages. Messages are over a constant size alphabet, and the error rate is the ratio between the number of errors introduced by the adversary in the worst case and the number of such messages sent, i.e. the transcript length. Note that in this model, it is possible for the honest parties to generate a secret key unknown to the adversary by measuring their shared entanglement. Details about the other models of communication appear in [section 6](#). Most of our technical contributions involve showing the following result, which is stated more formally as [Theorem 12](#) later.

THEOREM 1. *A constant dilation factor on the communication suffices to withstand an adversarial error rate of $\frac{1}{2} - \varepsilon$ in the shared entanglement model, for arbitrarily small $\varepsilon > 0$.*

This is optimal and matches the highest tolerable error rate in the analogous shared secret key model for classical interactive communication [\[25\]](#).

The results in the other models are consequences of this main theorem. For the quantum communication model in which parties do not pre-share entanglement, but have access to a noisy quantum channel, we first distribute a linear amount of entanglement using standard quantum information and coding theory techniques. We can tolerate any adversarial error rate less than $\frac{1}{6}$ in that case ([Theorem 20](#)), close to the best achievable for quantum data transmission with zero error at $\frac{1}{4}$. This is better than the factor of two drop that might be expected if we compare classical interactive coding to unidirectional coding. We can also adapt our techniques for an adversarial error model to the case of a random error model. Then, dilation factors proportional to $\frac{1}{C_Q}$ for a depolarizing channel of quantum capacity C_Q in the quantum model ([Theorem 21](#)), and proportional to $\frac{1}{C}$ for a binary symmetric channel of capacity C in the shared entanglement model ([Theorem 18](#)), are sufficient. We also show that the result in the shared entanglement model is asymptotically optimal: there exists a family of binary functions for which a dilation factor proportional to $\frac{1}{C}$ is necessary ([Theorem 19](#)). We further extend the study in the shared entanglement model to consider noisy entanglement in the form of noisy Einstein-Podolsky-Rosen (EPR) pairs in the so-called Werner states. For any non-separable Werner state, we give simulation protocols with linear noisy classical communication and noisy EPR pair consumption. Perhaps surprisingly, similar techniques can be used to show that the use of depolarizing channels in both directions enables the simulation to succeed whenever the quantum capacity with two-way classical communication, C_Q^2 , is strictly positive ([Theorem 23](#)). For some range of the depolarizing parameter, $C_Q = 0$ but $C_Q^2 > 0$, so this proves that C_Q does not characterize a quantum channel's capacity for interactive quantum communication.

Due to the use of tree codes, the protocols presented in this paper are not computationally efficient. However, it is possible to extend classical results on efficient interactive coding tolerating maximum error to noisy quantum communication. The representation of noisy protocols mentioned above is quite powerful and could be used to adapt classical results on computationally efficient interactive computation over adversarial channels [\[10\]](#) and on the interactive capacity of random noise channels [\[34\]](#) to the quantum regime.

There are two main components that establish our main result.

2.1. First Component: Teleportation and Active Rewinding. First, we need to establish a framework for simulating quantum protocols over noisy channels. To avoid losing quantum information, the approach we take is to teleport [\[3\]](#) the

quantum communication register back and forth. When the register is in some party's possession, this party tries to evolve the simulation by applying one of his unitary operations in the noiseless protocol, or one of its inverses if he realizes at some point he applied it wrongly before. The important point is that all operations on the quantum registers are reversible, being a sequence of noiseless protocol unitary operators and random (but known) Pauli operators. Of particular importance to our work is the notion of tree codes as introduced by Schulman, which the players use to transmit classical information.

As described in a recent paper on efficient interactive coding [11], the high-level logic of all solutions proposed until now for classical protocol simulation can be summarized as follows: the parties try to evolve the protocol, and if they later realize there has been some error, they try to go back to the point where they last agreed (in a protocol tree representation, this would be their least common ancestor). In our approach for quantum protocols, the parties try to follow roughly the same idea, but for two reasons are not able to do this passively. First, there is no underlying transcript (or protocol tree) that the parties try to synchronize, except for their wish to evolve the correct sequence of unitary operations. By the no-cloning theorem [23, 55], the parties cannot restart with a copy of the quantum information received up to some earlier point. Instead they have to actively rewind previous unitary operators and wrong teleportation decodings until a suitable point in the protocol. Second, when they try to synchronize in this manner, they actively teleport, potentially leading to more errors on the joint quantum register.

An important ingredient in our simulation is the representation for noisy quantum protocols that we develop. As said before, in quantum protocols there is no direct analogue of a protocol tree representation that enables one to keep track exactly and explicitly of the evolution of the noiseless protocol simulation. The cleaned-up form (5) of our representation provides in some sense a quantum analogue of a protocol tree representation. As the classical representation, it enables an exact and explicit assessment of the evolution of the noiseless protocol simulation, as well as such an assessment of the departure from it due to noise.

At this point, it might look like we have reduced our problem to the classical case, since the parties only transmit classical information—the teleportation measurement outcomes. This enables us to reuse tools from classical interactive coding, most notably tree codes, but the design of the quantum simulation protocol needs extra care. Unlike in the classical case, agreement by the two parties on a common classical transcript is not sufficient. This transcript consists mostly of random teleportation measurement outcomes and is useless by itself. Additionally, we need to maintain a joint quantum state that eventually evolves according to the original protocol.

Once we realize the importance of teleportation in the context of noisy communication, and carefully design the simulation protocol, it may not come as a surprise that the simulation incurs only a constant factor overhead. The need for backtracking in the quantum simulation, however, seems to impose serious constraints on the tolerable error rate. *A priori* it is entirely unclear whether we could hope to circumvent the low error tolerance seen in simulations with backtracking.

2.2. Second Component: Simulation via Blueberry Codes. The second part of our main contribution is to develop the necessary techniques to prove that we *can* tolerate an error rate as high as $\frac{1}{2} - \varepsilon$. These techniques are indeed novel, and could be used to improve on previously known *classical* results.

Indeed, all recent classical schemes tolerating high error rates have the property

that the parties always go forward with the communication by using the tree structure of classical protocols. In comparison, in the original Schulman scheme based on tree codes there is some form of backtracking, due to which the scheme could only tolerate a much lower adversarial error rate of $\frac{1}{240}$. This is due to the fact that in a protocol with backtracking [47], for the simulation to succeed the fraction of good rounds, in which both players correctly decode the tree code transmission, must be higher than in a protocol that always goes forward by transmitting edges of a pointer jumping problem [14, 25]. There also is some form of backtracking in the outer level of the computationally efficient protocol of Ref. [10], thus limiting the overall error rate that can be tolerated to a fourth of that of the inefficient protocol used at the inner level. Hence, computationally efficient protocols in the shared secret key communication model prior to this work could only tolerate error rates less than $\frac{1}{8}$ [25]. In light of these results, it is clear that previously used techniques would not suffice to tolerate error rates as high as $\frac{1}{2} - \varepsilon$ for our protocol, which requires backtracking. The new techniques we develop are thus necessary.

To achieve higher error tolerance, we follow Ref. [25] and use a *blueberry code* to effectively turn most adversarial errors into erasures. Concatenating such a code on top of a tree code yields a tree code with an erasure symbol. Since general transmission errors are twice as harmful as erasures for the tree code condition, which is stated in terms of Hamming distance, it was shown in Ref. [25] that if the error rate is below $\frac{1}{2} - \varepsilon$, then the large number of rounds in which both parties correctly decode a long enough prefix is sufficient to imply success of the simulation. Once again due to backtracking, this condition is not sufficient for our purpose and in particular blueberry codes by themselves are not sufficient to improve error tolerance up to $\frac{1}{2}$ here. For us, the number of rounds in which both parties correctly decode even the whole string could be high, but if these rounds alternate with rounds in which at least one of the parties makes a decoding error, then the protocol could stall, and simulation would fail. To circumvent this possibility, we need to bound the number of rounds with bad tree code decoding. Previously known bounds on this [47] can be used to show the success of our simulation but are far from enabling us to tolerate error rates up to $\frac{1}{2}$. We develop a new bound on tree codes with an erasure symbol, (see Lemma 16), which might be of independent interest for classical interactive coding. This bound enables us to tightly control the number of rounds with bad decoding. Once we control this quantity, it is also important to ensure that even when there is corruption detected as an erasure in a round, as long as there is no bad decoding, the protocol will not need to spend a good round to correct for this previous erasure round.

In fact, the techniques that we develop are not just powerful enough to prove that our quantum protocol can tolerate the maximum error rate of $\frac{1}{2} - \varepsilon$. Lemma 16 can be used to obtain a strengthening of the theorem of Ref. [25] in the *classical* shared secret key model, and then our techniques can be applied with this strengthened theorem and the techniques of Ref. [10] to obtain computationally efficient simulation protocols in this model that can also tolerate any error rate less than $\frac{1}{2}$ [21]. This demonstrates the power of our techniques. However, this result has been superseded by slightly adapting a result from Ref. [27], which uses different techniques; there the authors obtain computationally efficient simulation protocols at a maximum error up to $\frac{1}{4}$ in the model without a shared secret key.

2.3. Organization. The paper is structured as follows: in section 3, we set up the notation and state the relevant definitions, in particular for the different models

of communication. In [section 4](#), we state and prove a simpler version of our main result for the adversarial case in the shared entanglement model. In [section 5](#), we state and prove our main result for the adversarial case in the shared entanglement model. [Section 6](#) shows how to adapt the result of the previous section to obtain various interesting results, in particular for the quantum model, for the noisy shared entanglement model, and in the case of a random error model. We conclude with a discussion of our results and further research directions.

3. Preliminaries.

3.1. Quantum Mechanics. We briefly review the quantum formalism for finite dimensional systems, mainly to set notation; for a more thorough treatment, we refer the interested reader to the following good introductions in a quantum information theory context [[41](#), Chapter 2], [[53](#), Chapter 2] [[54](#), Chapters 3, 4, 5].

3.1.1. Quantum States and Quantum Evolution. To every quantum system A we associate a finite dimensional Hilbert space, which by abuse of notation we also denote by A . The state of quantum system A is represented by a density operator ρ^A , a positive semi-definite operator over the Hilbert space A with unit trace. We denote by $\mathcal{D}(A)$ the set of all density operators representing states of system A . Composite quantum systems are associated with the (Kronecker) tensor product space of the underlying spaces, i.e., for systems A and B , the allowed states of the composite system $A \otimes B$ are (represented by) the density operators in $\mathcal{D}(A \otimes B)$. We sometimes use the shorthand AB for $A \otimes B$. The evolution of a quantum system A is represented by a completely positive, trace preserving linear map (CPTP map) \mathcal{N}^A such that if the state of the system is $\rho \in \mathcal{D}(A)$ before evolution through \mathcal{N}^A , the state of the system is $\mathcal{N}^A(\rho) \in \mathcal{D}(A)$ after. If the system A is clear from the context, we might drop the superscript. We refer to such maps as quantum channels, and to the set of all channels acting on A as $\mathcal{L}(A)$. An important quantum channel that we consider is the qubit depolarizing channel \mathcal{T}_ε with depolarizing parameter $0 \leq \varepsilon \leq 1$: it takes as input a qubit ρ and outputs a qubit $\mathcal{T}_\varepsilon(\rho) = (1 - \varepsilon)\rho + \varepsilon\frac{1}{2}$, i.e., with probability $1 - \varepsilon$ it outputs ρ , and with complementary probability ε it outputs a completely mixed state. We also consider quantum channels with different input and output systems; the set of all quantum channels from a system A to a system B is denoted $\mathcal{L}(A, B)$. An example of such a channel that we consider is the qubit erasing channel \mathcal{R}_ε with erasing parameter $0 \leq \varepsilon \leq 1$: it takes as input a qubit ρ and outputs a qutrit $\mathcal{R}_\varepsilon(\rho) = (1 - \varepsilon)\rho + \varepsilon|e\rangle\langle e|$, i.e., with probability $1 - \varepsilon$ it outputs ρ , and with complementary probability ε it outputs an orthogonal erasure flag $|e\rangle$. Another important operation on a composite system $A \otimes B$ is the partial trace $\text{Tr}_B(\rho^{AB})$ which effectively derives the *reduced* or marginal state of the A subsystem from the quantum state ρ^{AB} . Fixing an orthonormal basis $\{|i\rangle\}$ for B , the partial trace is given by $\text{Tr}_B(\rho^{AB}) = \sum_i (\mathbb{I} \otimes \langle i|) \rho (\mathbb{I} \otimes |i\rangle)$, and this is a valid quantum channel in $\mathcal{L}(A \otimes B, A)$. Note that the action of Tr_B is independent of the choice of basis chosen to represent it, so we unambiguously write $\rho^A = \text{Tr}_B(\rho^{AB})$.

An important special case for quantum systems comprises pure states, whose density operators have a special form: rank-one projectors $|\psi\rangle\langle\psi|$. In such a case, a more convenient notation is provided by the pure state formalism: a state is represented by the unit vector $|\psi\rangle$ (up to an irrelevant complex phase) upon which the density operator projects. We denote by $\mathcal{H}(A)$ the set of all such unit vectors (up to equivalence of global phase) in system A .

Pure state evolution is represented by a unitary operator U^A acting on $|\psi\rangle^A$,

denoted $U|\psi\rangle^A$. Evolution of the B register of a state $|\psi\rangle^{AB}$ under the action of a unitary operator U^B is represented by $(I^A \otimes U^B)|\psi\rangle^{AB}$, for I^A representing the identity operator acting on the A system, and is denoted by the shorthand $U^B|\psi\rangle^{AB}$ for convenience. We occasionally drop the superscripts when the systems are clear from the context. The evolution under consecutive action of unitary operators U_j 's is denoted by

$$(1) \quad \left(\prod_{j=1}^{\ell} U_j \right) |\psi\rangle = U_{\ell} \dots U_1 |\psi\rangle.$$

We represent a classical random variable X with probability density function p_X by a density operator σ^X that is diagonal in a fixed (orthonormal) basis $\{|x\rangle\}_{x \in \mathcal{X}}$: $\sigma^X = \sum_{x \in \mathcal{X}} p_X(x) |x\rangle\langle x|^X$. For a quantum system A classically correlated with a random variable X , we represent the corresponding classical-quantum state by the density operator $\rho^{XA} = \sum_{x \in \mathcal{X}} p_X(x) |x\rangle\langle x|^X \otimes \rho_x^A$, in which ρ_x^A is the state of system A conditioned on the random variable X taking value $x \in \mathcal{X}$. The extraction of classical information from a quantum system is represented by quantum instruments: classical-quantum CPTP maps that take classical-quantum states on a composite system $X \otimes A$ to classical-quantum states. Viewing classical random variables as a special case of quantum systems, quantum instruments can be viewed as a special case of quantum channels.

3.1.2. Pauli Operators. When considering a quantum system A of dimension q , we fix an orthonormal basis $\{|i\rangle\}_{i \in \{0, 1, \dots, q-1\}}$ for A and use the following generalizations of Pauli operators: for $j, k \in \{0, 1, \dots, q-1\}$, $X^j|k\rangle = |(k+j) \bmod q\rangle$ and $Z^j|k\rangle = e^{i2\pi \frac{jk}{q}}|k\rangle$. The operators in the set $\{X^j Z^k\}_{j, k \in \{0, 1, \dots, q-1\}}$ are known as the Heisenberg-Weyl operators and form a basis for the linear vector space of operators on A , and the operators in

$$(2) \quad \mathcal{F}_{q,N} = \{X^{j_1} Z^{k_1} \otimes \dots \otimes X^{j_N} Z^{k_N}\}_{j_{\ell} k_{\ell} \in \{0, 1, \dots, q-1\}^2, \ell \in [N]}$$

form a basis for the space of operators on $A^{\otimes N}$. For $E \in \mathcal{F}_{q,N}$, we denote by $\text{wt}(E)$ the weight of E , i.e., the number of A subsystems on which E acts non-trivially. For $\delta \in [0, 1]$, the set

$$(3) \quad \mathcal{E}_{\delta, q, N} = \{E \in \mathcal{F}_{q, N} : \text{wt}(E) \leq \delta N\}$$

is the subset of elements of $\mathcal{F}_{q, N}$ of weight less than or equal to δN .

3.1.3. Teleportation. Our simulation protocols make heavy use of the teleportation protocol between Alice and Bob [3], which uses the following resource state shared by Alice and Bob, called an EPR pair: $|\Phi^+\rangle^{T_A T_B} = \frac{1}{\sqrt{2}}(|00\rangle + |11\rangle)$, with the qubit in the T_A register held by Alice, and the qubit in the T_B register held by Bob. The teleportation protocol then uses one of these resource states to teleport one qubit either from Alice to Bob, or from Bob to Alice. If Alice wants to teleport a qubit $|\psi\rangle$ in the register C to Bob, with whom she shares an EPR pair, she applies a joint Bell measurement, which can perfectly distinguish the Bell states $\{|\Phi_{xz}\rangle = \frac{1}{\sqrt{2}}(|0x\rangle + (-1)^z |1\bar{x}\rangle)\}_{x, z \in \{0, 1\}}$, to the registers CT_A she holds, and obtains uniformly random measurement outcomes $xz \in \{0, 1\}^2$. After this measurement, the state in the T_B register is $X^x Z^z |\psi\rangle$, for X and Z the Pauli operators corresponding to

bit flip and phase flip in the computational (Z) basis, respectively. If Alice transmits the two bits xz to Bob, he can then decode the state $|\psi\rangle$ on the T_B register by applying $(X^x Z^z)^{-1} = Z^z X^x$. Teleportation from Bob to Alice is performed similarly (EPR pairs are symmetric).

3.1.4. Pseudo-Measurements. Another technique we use is that of making classical operations coherent: measurements and classically controlled operations are replaced by corresponding unitary operators (and ancilla register preparation). We call the coherent version of a measurement a *pseudo-measurement*. Without loss in generality, it suffices to consider the measurement of a single qubit in the standard basis $\{|0\rangle, |1\rangle\}$. This measurement corresponds to the instrument \mathcal{N} defined by $\mathcal{N}(\rho) = \langle 0 | \rho | 0 \rangle |0\rangle\langle 0| + \langle 1 | \rho | 1 \rangle |1\rangle\langle 1|$. We replace this with the action of the CNOT operation $|0\rangle\langle 0| \otimes I + |1\rangle\langle 1| \otimes X$ on the qubit and a fresh ancillary qubit prepared in state $|0\rangle$, i.e., with the CPTP map \mathcal{N}' defined by $\mathcal{N}'(\rho) = U(\rho \otimes |0\rangle\langle 0|)U^*$, where U is the CNOT operation. The ancilla qubit may now be transmitted instead of sending the classical outcome of the measurement \mathcal{N} . Provided all further operations on the two qubits are only controlled unitary operations (in which the two qubits may only be control qubits), each separately behaves like the classical measurement outcome. The advantage of this substitution is that unlike measurements, they are *reversible*. If it is later realized that a qubit should not have been measured, the pseudo-measurement can be undone.

3.1.5. Distance Measures. To measure the success of the simulation, we use the trace distance $\|\rho - \sigma\|_1^A$ between two arbitrary states ρ^A and σ^A , in which $\|O\|_1^A = \text{Tr}((O^\dagger O)^{\frac{1}{2}})$ is the trace norm for operators on system A . We might drop the A superscript if the system is clear from the context. The trace distance has the operational interpretation to be (four times) the best possible bias to distinguish between the two states ρ^A and σ^A , given a single unknown copy of one of these two states [53, Chapter 3]. To distinguish between quantum channels, we first consider the induced norm for quantum channels $\mathcal{N} \in \mathcal{L}(A, B)$: $\|\mathcal{N}\| = \max\{\|\mathcal{N}(\sigma)\|_1^B : \sigma \in \mathcal{D}(A)\}$. Correlations with another quantum system can help distinguish between quantum channels, so an appropriate norm to use to account for this is the completely bounded trace norm [1]: $\|\mathcal{N}\|_\diamond = \|\mathcal{N} \otimes I^R\|$ for some reference system R of the same dimension as the input system A [53, Chapter 3]. For two quantum channels $\mathcal{N}, \mathcal{M} \in \mathcal{L}(A, B)$, $\|\mathcal{N} - \mathcal{M}\|_\diamond$ has a useful operational interpretation: it is (four times) the best possible bias with which we can identify a uniformly random (unknown) channel out of the two, when we are allowed only one use of the channel.

3.2. Quantum Communication Model.

3.2.1. Noiseless Communication Model. In the *noiseless quantum communication model* that we want to simulate, there are five quantum registers: the A register held by Alice; the B register held by Bob; the C register, which is the communication register exchanged back and forth between Alice and Bob and initially held by Alice, the E register held by a potential adversary Eve; and finally the R register, a reference system which purifies the initial (and then also the final) state of the $ABCE$ registers. The initial state $|\psi_{\text{init}}\rangle^{ABCE R} \in \mathcal{H}(A \otimes B \otimes C \otimes E \otimes R)$ is chosen arbitrarily from the set of possible inputs and is fixed at the outset of the protocol, but it is possibly unknown (totally or partially) to Alice and Bob. Note that to allow for composition of quantum protocols in an arbitrary environment, we consider arbitrary quantum states as input, which may be entangled with systems RE . A protocol Π is

then defined by the sequence of unitary operations U_1, U_2, \dots, U_{N+1} , with U_i for odd i known at least to Alice (or given to her in a black box) and acting on registers AC , and U_i for even i known at least to Bob (or given to him in a black box) and acting on registers BC . For simplicity, we assume that N is even. We can modify any protocol to satisfy this property, while increasing the total cost of communication by at most one communication of the C register. The unitary operations of protocol Π can be assumed to be public information and known to Eve. On a particular input state $|\psi_{\text{init}}\rangle$, the protocol generates the final state $|\psi_{\text{final}}\rangle^{ABCE R} = U_{N+1} \cdots U_1 |\psi_{\text{init}}\rangle^{ABCE R}$, for which at the end of the protocol the A and C registers are held by Alice, the B register is held by Bob, and the E register is held by Eve. The reference register R is left untouched throughout the protocol. The output state of the protocol is the ABC part, i.e., $\Pi(|\psi_{\text{init}}\rangle) = \text{Tr}_{ER}(|\psi_{\text{final}}\rangle\langle\psi_{\text{final}}|^{ABCE R})$, and by a slight abuse of notation we also represent the induced quantum channel from $ABCE$ to ABC simply by Π . This is depicted in Figure 1. Note that while the protocol only acts on ABC , we wish to maintain correlations with the reference system R , while we simply disregard what happens on the E system assumed to be in Eve's hand. Since we consider local computation to be free, the sizes of A and B can be arbitrarily large, but still of finite size, say m_A and m_B qubits, respectively. We restrict ourselves to the case of a single-qubit communication register C , which is the worst case for noisy interactive communication. Every protocol can be converted into such a form by increasing the communication by a factor of at most two but possibly at the expense of much more interaction: if a party has to speak when it is not his turn, he sends a qubit in state $|0\rangle$. Note that both the Yao and the Cleve–Buhrman models of quantum communication complexity can be recast in this framework; see Section 3.3.

We later embed length N protocols into others of larger length $N' > N$. To perform such *noiseless protocol embedding*, we define some dummy registers \tilde{A} , \tilde{B} , \tilde{C} isomorphic to A , B , C , respectively. \tilde{A} and \tilde{C} are part of Alice's scratch register and \tilde{B} is part of Bob's scratch register. Then, for any isomorphic quantum registers D , \tilde{D} , let $\text{SWAP}_{D \leftrightarrow \tilde{D}}$ denote the unitary operation that swaps the D, \tilde{D} registers. Recall that N is assumed to be even. In a noiseless protocol embedding, for $i \in \{1, 2, \dots, N-1\}$, we leave U_i untouched. We replace U_N by $(\text{SWAP}_{B \leftrightarrow \tilde{B}} U_N)$ and U_{N+1} by $(\text{SWAP}_{AC \leftrightarrow \tilde{A}\tilde{C}} U_{N+1})$. Finally, for $i \in \{N+2, N+3, \dots, N'+1\}$, we define $U_i = \text{I}$, the identity operator. This embedding is important in the setting of interactive quantum coding for the following reasons: first, adding these U_i for $i > N$ makes the protocol well defined for $N'+1$ steps. Then, swapping the important registers into the safe registers \tilde{A} , \tilde{B} , \tilde{C} ensures that the important registers are never affected by noise arising after the first $N+1$ steps have been applied. Hence, in our simulation, as long as we succeed in implementing the first $N+1$ steps without errors, the simulation will succeed since the \tilde{A} , \tilde{B} , \tilde{C} registers will then contain the output of the simulation, with no error acting on these registers.

We refer later to the *unidirectional model*, consisting of one-way protocols; in this noiseless model, we allow for large local registers A' , B' and for a large communication register C' that is used only once, either from Alice to Bob or from Bob to Alice, depending on the protocol. These registers can be further decomposed such that when used for simulation, the A and C registers of the protocol to be simulated are subsystems of A' , and B is one of B' . For concreteness we consider here the case of communication from Alice to Bob; the other case is symmetric. A simulation protocol U in the unidirectional model is defined by two quantum instruments $\mathcal{M}_1^{A'C'}$, $\mathcal{M}_2^{B'C'}$, and the output of the protocol on input $|\psi\rangle \in \mathcal{H}(A \otimes B \otimes C \otimes E \otimes R)$ is the state

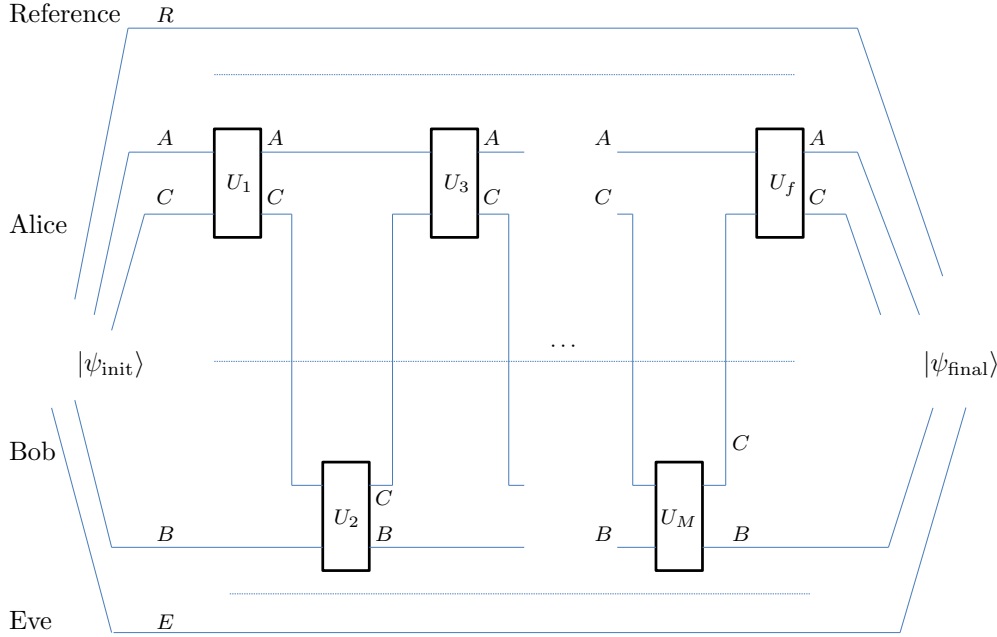


FIG. 1. Depiction of a quantum protocol in the noiseless communication model, adapted from the long version of [52, Figure 1].

of the ABC subsystem of $\mathcal{M}_2\mathcal{M}_1(|\psi\rangle)$ and is denoted $U(|\psi\rangle)$. By abuse of notation, the induced quantum channel from $ABCE$ to ABC is also denoted U .

3.2.2. Noisy Communication Model. There are many possible models for noisy communication. We consider two in particular: one analogous to the Yao model with no shared entanglement but noisy quantum communication, which we call the *quantum model*, and one analogous to the Cleve–Buhrman model with noiseless pre-shared entanglement but noisy classical communication, which we call the *shared entanglement model*. A further variation on the shared entanglement model in which the entanglement is also noisy is considered in [subsection 6.4](#). For simplicity, we formally define in this section what we sometimes refer to as *alternating* communication models, in which Alice and Bob take turns transmitting the communication register to each other, and this is the model in which most of our protocols are defined. Our definitions easily adapt to somewhat more general models which we call *oblivious* communication models, following Ref. [14]. In these models, Alice and Bob do not necessarily transmit their messages in alternation, but nevertheless in a fixed order and of fixed sizes known to all (Alice, Bob, and Eve) depending only on the round and not on the particular input or the actions of Eve. Communication models with a dependence on inputs or actions of Eve are called *adaptive* communication models.

Quantum Model. We give formal definitions for the quantum model in [Appendix A.1](#). Let us give an informal description here.

In the *quantum model*, Alice has workspace A' , Bob has workspace B' , adversary

Eve has workspace E' , and there is some quantum communication register C' of some fixed size q , exchanged back and forth between them N' times, passing through Eve's hand each time. Alice and Bob can perform arbitrary local processing between each transmission, whereas Eve's processing when the C' register passes through her hand is limited by the noise model as described below. The input registers $ABCE$ are shared between Alice (AC), Bob (B) and Eve (E) and the output registers $\tilde{A}\tilde{B}\tilde{C}$ are shared between Alice ($\tilde{A}\tilde{C}$) and Bob (\tilde{B}). The reference register R containing the purification of the input is left untouched throughout. Alice and Bob also possess registers C_A and C_B , respectively, acting as virtual communication register C from the original protocol Π of length N to be simulated. The communication rate of the simulation is given by the ratio $\frac{N}{N' \log q}$.

We are interested in two models of errors, adversarial and random noise. In the *adversarial* noise model, we are mainly interested in adversary Eve with a bound $\delta N'$ on the number of errors that she introduces on the quantum communication register C' that passes through her hand. The fraction δ of corrupted transmissions is called the error rate, and is assessed by requiring that there exists a representation of the global action of Eve on the N' quantum communication registers with Kraus operators of weight at most $\delta N'$.

In the random noise model, we consider N' independent and identically distributed uses of a noisy quantum channel acting on register C' , half the time in each direction. Eve's workspace register E' (including her input register E) can be taken to be trivial in this noise model.

For both noise models, we say that the simulation succeeds with error ε if for any input, the output in register $\tilde{A}\tilde{B}\tilde{C}$ corresponds to that of running protocol Π on the same input, while also maintaining correlations with system R , up to error ε in trace distance.

Shared Entanglement Model. We give formal definitions for the shared entanglement model in Appendix A.2. Let us give an informal description here.

In the *shared entanglement model*, Alice has workspace A' , Bob has workspace B' , adversary Eve has workspace E' , and there is some classical communication register C'' of some fixed size q , exchanged back and forth between them N' times, passing through Eve's hand each time. Alice and Bob also pre-share noiseless entanglement in register $T_A T_B$. Alice and Bob can perform arbitrary local processing between each transmission, whereas Eve's processing when the C'' register passes through her hand is limited by the noise model as described below. The input registers $ABCE$ are shared between Alice (AC), Bob (B) and Eve (E) and the output registers $\tilde{A}\tilde{B}\tilde{C}$ are shared between Alice ($\tilde{A}\tilde{C}$) and Bob (\tilde{B}). The reference register R containing the purification of the input is left untouched throughout. Alice and Bob also possess registers C_A and C_B , respectively, acting as virtual communication register C from the original protocol Π of length N to be simulated. The communication rate of the simulation is given by the ratio $\frac{N}{N' \log q}$.

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In the random noise model, we consider N' independent and identically distributed uses of a noisy classical channel acting on register C'' , half the time in each

direction. Eve’s workspace register E' (including her input register E) can be taken to be trivial in this noise model.

For both noise models, we say that the simulation succeeds with error ε if for any input, the output in register $\tilde{A}\tilde{B}\tilde{C}$ corresponds to that of running protocol Π on the same input, while also maintaining correlations with system R , up to error ε in trace distance.

Notice that adversaries in the quantum model and shared entanglement model are incomparable. In the quantum model, the adversary can inject fully quantum errors since the messages are quantum, while errors in the shared entanglement model are restricted to be modifications of classical symbols. On the other hand, in the shared entanglement model the adversary can read all the classical messages without the risk of corrupting them, whereas in the quantum model, any attempt to “read” messages will result in an error in general on some quantum message.

3.3. Quantum Communication Complexity. We discuss how standard models for quantum communication complexity fit into our model for noiseless quantum communication. In the Yao model for quantum communication complexity [56], Alice is given a classical input $x \in X$ and Bob is given a classical input $y \in Y$, and they want to compute a classical function $f : X \times Y \rightarrow Z$ of their joint input (often $X = Y = \{0, 1\}^n$, $Z = \{0, 1\}$) by communicating as few quantum bits as possible, but without regard to the local computation cost. Often, we are only interested in $x \in X$, $y \in Y$ satisfying some promise $P : X \times Y \rightarrow \{0, 1\}$. A global quantum system is split into three subsystems: the A register held by Alice, the B register held by Bob, and the C register, which is the communication register initially held by Alice and exchanged back and forth by Alice and Bob in each round. Our formal description of the protocols in this model is based upon the one given in Ref. [35].

A length N protocol is defined by a sequence of unitary operators U_1, \dots, U_{N+1} in which for i odd, U_i acts on the AC register, and for i even, U_i acts on the BC register. We need $N + 1$ unitary operators in order to have N messages since a first unitary operation is applied before the first message is sent and a last one is applied after the final message is received. Initially, all the qubits in the A , B , C registers are set to the all $|0\rangle$ state, except for n qubits in the A register initially set to $x \in X$, and n in the B register set to $y \in Y$. The number of qubits $m_A, m_B \in \mathbb{N}$ in the A and B registers is arbitrary (of course, $m_A, m_B \geq n$) and is not taken into account in the cost of the protocol. The complexity of the U_i ’s is also immaterial, since local computation is deemed free. However, the number of qubits c in the C register is important and is taken into account in the communication cost, which is $N \cdot c$. The outcome of the protocol is obtained by measuring an appropriate number of qubits of registers A and B of Alice and Bob, respectively, after the application of U_{N+1} . The protocol succeeds if the outcomes of both measurements equal $f(x, y)$ with good probability, usually required to be a constant greater than $1/2$, for any x, y satisfying the promise.

Another model for quantum communication complexity was introduced by Cleve and Buhrman [18]. In their model, communication is classical, but parties are allowed to pre-share an arbitrary entangled quantum state at the outset of the protocol. We can view protocols in this model as a modification on those of Yao’s model in which the initial state $|\psi\rangle$ on the ABC register is arbitrary except for n qubits in each of the A, B registers initialized to x, y , respectively. Also, each qubit in the C register is measured in the computational basis, and it is the outcome of these measurements that is communicated to the other party. Note that by using pseudo-measurements instead

of actual measurements in each round, the parties can use quantum communication instead of classical communication. Then the two models become almost identical, except for the initial state, which is arbitrary in the Cleve–Buhrman model, and fixed to the all 0 state in the Yao model (not including each party’s classical input). Since our simulation protocols consider general unitary local processing but do not assume any particular form for the initial state, they work on this slight adaptation of the Cleve–Buhrman model as well as on the Yao model of quantum communication complexity.

Hence, both the Yao and the Cleve–Buhrman models of quantum communication complexity can be recast in our framework for noiseless communication by making all operations coherent: put the initial classical registers into quantum registers, replace classically controlled operations by quantumly controlled operations, also replace measurements by pseudo-measurements, and then replace any classical communication by quantum communication. In particular, this gets rid of the problem of the non-reversibility of measurements in the Cleve–Buhrman model.

3.4. Classical Communication.

3.4.1. History. Our simulation protocols contain an important classical component. In our setting, we are interested in protocols in which each party sends a message from some message set $[d] = \{1, 2, \dots, d-1, d\}$ of size d in alternation, for some fixed number of rounds N' (actually, $\frac{N'}{2}$ in our protocols). A round consists of Alice sending a message to Bob and then Bob sending a message back. Parties only have access to some noisy channels, so they need to encode these messages in some way. The codes used to do so in an interactive setting are described in the next subsection. For the moment, let us focus on the messages the parties wish to transmit, without the coding.

In round i , Alice transmits a message $a_i \in [d]$ to Bob, and then Bob sends back a message $b_i \in [d]$. These messages depend on the messages $a_1, a_2, \dots, a_{i-1} \in [d]$ and $b_1, b_2, \dots, b_{i-1} \in [d]$ that Alice and Bob sent in the previous rounds, respectively. We refer to these sequences of messages (at the end of round i) as Alice’s history $s_A = a_1 \cdots a_i \in [d]^i$ and Bob’s history $s_B = b_1 \cdots b_i \in [d]^i$, respectively. Note that these histories are updated in each round, and that each history, at the end of round i , can be represented as a node at depth i in some d -ary tree of depth N' . This tree is called a history tree. The whole (noiseless) communication can be extracted from the information in these two histories.

When the communication is noisy, in some rounds one party makes errors when trying to determine the other party’s history. When comparing the history $s = s_1 \cdots s_i \in [d]^i$ of a party in round i of the protocol without coding, with the other party’s best guess $s^i = s_1^i \cdots s_i^i \in [d]^i$ for that history, the least common ancestor of s and s^i is the node at depth $i - \ell$ such that $s_1 \cdots s_{i-\ell} = s_1^i \cdots s_{i-\ell}^i$ but $s_{i-\ell+1} \neq s_{i-\ell+1}^i$. We call ℓ the *magnitude* of the error of such a guess s^i , and in general for two histories $s, s^i \in [d]^i$ satisfying the above (with least common ancestor at depth $i - \ell$) we write $L(s, s^i) = \ell$. Note that we can compute ℓ as $i - \max\{t : (\forall j \leq t)[s_j = s_j^i]\}$.

3.4.2. Tree Codes. Standard error correcting codes are designed for data transmission and therefore are not particularly well suited for interactive communication over noisy channels. In his breakthrough papers [46, 47], Schulman defined tree codes, which are particular codes designed for such interactive communication. Indeed, these tree codes can perform encoding and decoding round by round (following Ref. [25], we refer to such codes as online codes), such that for each round, a message from the mes-

sage set $[d]$ is transmitted, but even if there is some decoding error in this round, for each additional round that we perform (without transmission error), the more likely it is that this previous decoding error is correctly decoded. We describe this self-healing property in more detail after formally defining tree codes. We use the following for our definition. Given a set A and its k -fold Cartesian product $A^k = A \times \cdots \times A$ (k -times), we denote, for any $n \in \mathbb{N}$, $A^{\leq n} = \cup_{k=1}^n A^k$. Also, given a transmission alphabet Σ and two words $\bar{e} = e_1 \cdots e_t \in \Sigma^t$ and $\bar{e}' = e'_1 \cdots e'_t \in \Sigma^t$ over this alphabet, we denote by $\Delta(\bar{e}, \bar{e}')$ (the Hamming distance) the number of different symbols, i.e., $\Delta(\bar{e}, \bar{e}') = |\{i : e_i \neq e'_i\}|$.

DEFINITION 2. (Tree codes [47]) *Given a message set $[d]$ of size $d > 1$, a number of rounds of communication $N' \in \mathbb{N}$, a distance parameter $0 < \alpha < 1$ and a transmission alphabet Σ of size $|\Sigma| > d$, a d -ary tree code of depth N' and distance parameter α over alphabet Σ is defined by an encoding function $\mathcal{E} : [d]^{\leq N'} \rightarrow \Sigma$, and a decoding function $\mathcal{D} : \Sigma^{\leq N'} \rightarrow [d]^{\leq N'}$.*

Let $\bar{\mathcal{E}} : [d]^{\leq N'} \rightarrow \Sigma^{\leq N'}$ denote the extension of \mathcal{E} to strings, i.e., for any $t \leq N'$ and $a = a_1 \cdots a_t \in [d]^t$,

$$\bar{\mathcal{E}}(a) = \mathcal{E}(a_1) \mathcal{E}(a_1 a_2) \cdots \mathcal{E}(a_1 \cdots a_{t-1}) \mathcal{E}(a_1 \cdots a_t) ,$$

which is a string in Σ^t .

The encoding function satisfies the following distance property, called the tree code property. For any $t \leq N'$, and $a, a' \in [d]^t$,

$$L(a, a') = \ell \quad \implies \quad \Delta(\bar{\mathcal{E}}(a), \bar{\mathcal{E}}(a')) \geq \alpha \cdot \ell .$$

In other words, if the least common ancestor of a, a' is at depth $t - \ell$, then the corresponding codewords are at distance at least $\alpha \ell$.

The decoding function satisfies the property that for any $t \leq N'$, and $\bar{e} \in \Sigma^t$,

$$\mathcal{D}(\bar{e}) \in \{a : a \in [d]^t \text{ minimizes } \Delta(\bar{\mathcal{E}}(a), \bar{e})\} .$$

See Appendix B for a depiction of tree codes.

We later consider decoding of tree codes with an erasure symbol \perp , that is not used by the encoding function, but may occur in the output of a channel. The decoding algorithm extends *verbatim* to received words with erasure symbols: it outputs a message sequence whose tree encoding is closest in Hamming distance to the received word.

Note that the decoding function is not uniquely defined for a given tree code: we could avoid ambiguity by outputting a special failure symbol for $\mathcal{D}(\bar{e})$ whenever $|\{a : a \in [d]^t \text{ minimizes } \Delta(\bar{\mathcal{E}}(a), \bar{e})\}| > 1$. Also note that we can view tree codes in the following alternative way, connecting them with the history tree representation defined above. Starting with a history tree, we can label the arcs out of each node by a symbol from Σ corresponding to the encoding of that path in the tree code. The encoding function $\bar{\mathcal{E}}$ represents the concatenation of the symbols on the path from root to node a , and the distance property is related to the distance of a, a' to their least common ancestor in the history tree, and to the number of errors during these corresponding $L(a, a')$ last transmissions. The following was proved in Ref. [47] for the existence of tree codes. Let $H(\alpha) = -\alpha \cdot \log \alpha - (1 - \alpha) \cdot \log(1 - \alpha)$ denote the binary entropy function.

LEMMA 3. *Given a message set $[d]$ of size $d > 1$, a number of rounds of communication $N' \in \mathbb{N}$, and a distance parameter $0 < \alpha < 1$, taking transmission alphabet*

Σ with $|\Sigma| = 2 \lfloor (2 \cdot 2^{H(\alpha)} \cdot d)^{\frac{1}{1-\alpha}} \rfloor - 1$ suffices to label the arcs of some tree code, i.e., there exists an encoding function \mathcal{E} satisfying the tree code property, and the required alphabet size is independent of N' , the number of rounds of communication.

In fact, the result due to Schulman is even stronger: there exists an unbounded depth tree code with Σ of the size discussed above. This stronger result could be useful in the case in which the number of rounds N' is not bounded at the beginning of the protocol, and it has been used to authenticate streams of classical data in Ref. [25].

The distance property of tree codes ensures the following: if in round t the decoding is good for the first $t - \ell$ messages sent ($\ell \geq 0$), but wrong for the message sent in round $t - \ell + 1$ (and possibly also for some other messages), then the re-encoding of the sequence of decoded messages must be distinct from the transmitted one in at least $\alpha \cdot \ell$ positions in the last ℓ rounds. Then, incorrect decoding (i.e., decoding to a message different from the one encoded) implies that there were at least $\frac{1}{2} \cdot \alpha \cdot \ell$ transmission errors during those rounds, independent of what was sent in the first $t - \ell$ rounds. More precisely, given a transmitted message $\bar{a} \in [d]^t$, encoded as $\bar{e} = \bar{\mathcal{E}}(\bar{a}) \in \Sigma^t$, received as $\bar{e}'' \in \Sigma^t$, and decoded as $\bar{a}' = \mathcal{D}(\bar{e}'') \in [d]^t$, with $\bar{e}' = \mathcal{E}(\bar{a}')$, if we have $a_1 \cdots a_{t-\ell} = a'_1 \cdots a'_{t-\ell}$ but $a_{t-\ell+1} \neq a'_{t-\ell+1}$, i.e., $L(a, a') = \ell$, then $\Delta(\bar{e}, \bar{e}') \geq \alpha \cdot \ell$ and $\Delta(e_{t-\ell+1} \cdots e_t, e'_{t-\ell+1} \cdots e'_t) \geq \frac{1}{2} \cdot \alpha \cdot \ell$. (Note that $e_1 \cdots e_{t-\ell} = e'_1 \cdots e'_{t-\ell}$.) This property is extremely useful for interactive communication: even if the decoding of a message is incorrect in some round, if there are sufficiently many error-free subsequent transmissions, we can later correct that error. This self-healing property is essential to our analysis of the simulation protocol, and to our proof of [Lemma 16](#).

3.4.3. Blueberry Codes. Another kind of online code we need in order to withstand the highest possible error rates are randomized error detection codes called blueberry codes in Ref. [25]. To use these, Alice and Bob encode and decode messages with a shared secret key in a way that weakly authenticates and encrypts each message, and in this way adversary Eve cannot apply a corruption of her choosing. Such codes unknown to the adversary were termed private codes in Ref. [36]. At best, with some small (but constant) probability Eve is able to corrupt a message in such a way that Alice and Bob do not detect it, and this results in an effective decoding error, but most of the time a corruption of Eve results in an effective erasure decoding. Since the tree code property, and hence also its decoding, is defined in terms of Hamming distance, transmission errors are twice as harmful as erasures in the tree decoding. (We can view the erasure flag \perp as a special symbol in Σ ; although never used in the encoding, this symbol helps in decoding.) When incorrect decoding occurs, the two parties might perform operations on the quantum registers that need to be corrected later. On the other hand, when an erasure occurs, it is visible to the recipient and this prevents him from performing such incorrect operations. Hence, concatenating a blueberry code with the tree code enables significant improvement in the allowed error rates.

These blueberry codes were defined in Ref. [25] for the purpose of authenticating streams of classical messages and for the simulation of interactive classical protocols. Below we summarize their definition and important properties.

DEFINITION 4. (blueberry codes [25]) *For $i \geq 1$ let $\mathcal{B}_i : \Gamma \rightarrow \Gamma$ be a random and independent permutation. The blueberry code maps a string $e \in \Sigma^t \subset \Gamma^t$ of arbitrary length t to $\mathcal{B}(e) = \mathcal{B}_1(e_1)\mathcal{B}_2(e_2) \cdots \mathcal{B}_t(e_t)$. We denote such a code as $\mathcal{B} : \Sigma^* \rightarrow \Gamma^*$, and define the erasure parameter of this code as $\beta = 1 - \frac{|\Sigma|-1}{|\Gamma|-1}$, and its complement $\varepsilon_\beta = 1 - \beta = \frac{|\Sigma|-1}{|\Gamma|-1}$.*

DEFINITION 5. Assume that at some time i , $d_i = \mathcal{B}_i(e_i)$ is transmitted and $d'_i \neq d_i$ is received. If $d'_i \notin \mathcal{B}_i(\Sigma)$, we mark the transmission as an erasure, and the decoding algorithm (for the Blueberry code) outputs \perp . Otherwise, this event is called an error.

COROLLARY 6. Let $e \in \Sigma^t$ and assume $\mathcal{B}(e)$ is communicated over a noisy channel. Every symbol corrupted by the channel causes either an error with probability ε_β , or an erasure with probability β .

LEMMA 7. Assume a blueberry code $\mathcal{B} : \Sigma^* \rightarrow \Gamma^*$ is used to transmit a string $e \in \Sigma^t$ over a noisy channel. For any constant $0 \leq c \leq 1$, if the channel's corruption rate is c , then with probability $1 - 2^{-\Omega(t)}$ at least a $(1 - 2\varepsilon_\beta)$ -fraction of the ct corrupted transmissions are marked as erasures.

COROLLARY 8. If out of t received transmissions, ct were marked as erasures while decoding a blueberry code $\mathcal{B} : \Sigma^* \rightarrow \Gamma^*$, then except with probability $2^{-\Omega(t)}$ over the shared randomness, the adversarial corruption rate is at most $c/(1 - 2\varepsilon_\beta)$.

4. Basic Simulation Protocol. We start by describing a basic simulation protocol, which achieves our first goal of simulating quantum protocols with asymptotically positive communication and tolerable error rates, and with entanglement consumption linear in the communication. This provides an interactive analogue of a family of good quantum codes. This protocol contains the essential ideas of the optimal protocol of [section 5](#), but the description and analysis are simplified because we do not have the additional blueberry code layer. Moreover, this protocol succeeds with perfect fidelity, provided the number of errors is below a certain threshold.

4.1. Result. We focus on the shared entanglement model. Techniques to distribute entanglement in both random [[39](#), [50](#), [22](#)] and adversarial [[16](#), [24](#), [43](#)] error models are well studied. We can combine our findings with these entanglement distribution techniques to translate results in the shared entanglement model to the quantum model. We first focus on an adversarial error model, and then adapt these results to a random error model. Such extensions to other communication models are explored in [section 6](#). For the basic simulation protocol described in this section, entanglement is only used to teleport the quantum information back and forth between the two parties. In [section 5](#), we show how to tolerate maximum error rates by also using entanglement to generate a shared secret key unknown to the adversary, thus enabling the two honest parties to detect most adversarial errors as effective erasures.

Given an adversarial channel in the shared entanglement model with low enough error rate, we show how to simulate perfectly any noiseless protocol of length N over this channel using a number of transmissions linear in N , and consuming a linear number of EPR pairs. More precisely, we prove the following. (See [Appendix A.2](#) for the definition of $\mathcal{A}_{\delta,q,N'}^S$, which is mentioned in the theorem.)

THEOREM 9. There exist a constant error rate $\delta > 0$, communication rate $R_C > 0$, transmission alphabet size $q \in \mathbb{N}$, and entanglement consumption rate $R_E \in \mathbb{R}^+$ such that for all noiseless protocol lengths $N \in 2\mathbb{N}$, there exists a universal simulator S in the shared entanglement model of length N' , with communication rate at least R_C , transmission alphabet size q , entanglement consumption rate at most R_E , which succeeds with zero error at simulating all noiseless protocols of length N against all adversaries in $\mathcal{A}_{\delta,q,N'}^S$.

Specific values for the constants posited in the theorem are given at the end of [subsection 4.4](#).

4.2. Intuition for the Simulation Protocol. Before describing in detail the basic simulation protocol, first we give some intuition on how it succeeds in simulating a noiseless quantum protocol over a noisy channel. The strategy to avoid losing the quantum information in the communication register over the noisy channel is to teleport the C register of the noiseless protocol back and forth into Alice's C_A register and Bob's C_B register, creating a virtual C register which is either in Alice's or in Bob's hand. They use the shared entanglement in $T_A T_B$ to do so, and use the noisy classical channels to transmit their teleportation measurement outcomes. Whenever Alice possesses the virtual C register she can try to evolve the simulation of the noiseless protocol by applying one of her noiseless protocol unitary operators on the virtual AC register, and this applies similarly for Bob on the virtual BC register. If they later realize that there has been some error in the teleportation decoding, they might have to apply inverses of these operations, but overall, everything acting on the virtual ABC quantum register can be described as an intertwined sequence of Pauli operators acting on the C register and noiseless protocol unitary operators (and their inverses) acting on the AC and the BC registers. There are two important points to notice here. First, the sequence of operations acting on the joint register is a sequence of reversible unitary operators. Hence, if the parties keep track of the sequence of operations on the joint register, then at least one of the parties can reverse any of his/her operations when he/she is in possession of the virtual C register. Second, both parties know the order in which these operators have been applied while only one knows exactly which operator was applied: for Pauli operators, both parties know $\pm X^x Z^z$ is applied at some point, but only one knows the correct value of $xz \in \{0, 1\}^2$, and similarly both know that U_j^M (with $U_j^{+1} = U_j$, $U_j^{-1} = U_j^\dagger$, $U_j^0 = \mathbf{I}$) is applied at some point, but only one knows the correct values of $j \in \{1, \dots, N' + 1\}$ and $M \in \{-1, 0, +1\}$. This is the classical information they try to transmit to each other so that both know exactly the sequence of operations that have been applied on the joint register. The tree codes due to Schulman are particularly well suited for protecting against noise in this interactive scenario.

More concretely, in each round the parties first need to decode the teleportation before trying to evolve the simulation of the quantum protocol and finally teleporting back the communication register to the other party. The goal is for each party to know his/her exact position in the simulation of the protocol (i.e., the sequence of unitary operators that have been applied to the virtual protocol registers) when they are able to correctly decode the classical messages sent by the other party. To enable a party to learn exactly what action was taken by the other party in the earlier rounds, the message sent in each round is in $\{0, 1\}^2 \times \{-1, 0, +1\} \times \{0, 1\}^2$, encoded with a tree code. The first pair of bits corresponds to the teleportation decoding operation done at the beginning of a party's turn. The trit is associated with the evolution in the noiseless protocol: $+1$ stands for going forward with the protocol, i.e., for a unitary operator of the noiseless protocol that was applied to the joint state of the party's local register and the communication register; -1 stands for going backward with the protocol, i.e., for the inverse of a unitary operation of the noiseless protocol that was applied by that party to the joint state; and 0 stands for holding the protocol idle, i.e., no action is taken by that party to evolve the protocol in that round. Note that the index j of the unitary operator U_j^M that a party applies can be computed solely from the sequence of trits sent by that party, and such an explicit calculation is defined in the simulation description. Finally, the last pair of bits corresponds to the outcome of the measurement in the teleportation of the communication register, which enables

the other party to correctly decode the teleportation.

For each party, we call his/her *history* at some point the sequence of these triplets of messages that he/she transmitted up to that point (see [subsection 3.4](#)). If a party succeeds in correctly decoding the history of the other party, he/she then possesses all the information about the operations that were applied on the joint quantum register and can choose his/her next move accordingly.

Note that the information about which Pauli operator was used to decode the teleportation might appear redundant, it is not when there are decoding errors. This is a subtle and important point, so let us explain in more detail what we mean. In the case of decoding errors, the wrong Pauli operator might be applied to do the teleportation decoding. Even though the party who applied the wrong Pauli operator will later realize his/her mistake (when the self-healing property of the tree code eventually enables him/her to decode this message correctly), the other party still needs to be informed of this previous error in decoding. Sending the information about which Pauli operator was used to do the teleportation decoding accomplishes this and even enables the other party to correct this wrong teleportation decoding if needed. Indeed this property has an essential use, especially in the simulation for maximal error tolerance in [section 5](#). In more detail, when a corruption is detected as an erasure, the teleportation decoding operation applied is the trivial one. This is wrong three-quarters of the time on average. Another approach that would also work would be to let the other party know what information was received, and then let each party correct for his/her own previous decoding error. The problem with this is that the tolerable error rate would have to be much lower than $\frac{1}{2} - \varepsilon$: in the terms used in the analysis, we would need a good round to recover from an erasure round, which is undesirable.

4.3. Description of the Simulator. All communication is done with a tree encoding over some alphabet Σ . To later simplify the analysis, we fix the distance parameter to $\alpha = \frac{39}{40}$. The message set consists of $\{0, 1\}^2 \times \{-1, 0, +1\} \times \{0, 1\}^2 \cong [4] \times [3] \times [4] \cong [48]$, so we take arity $d = 48$. Also, taking $N' = 4(1 + \frac{1}{N})N$ is sufficient. By [Lemma 3](#), we know that there exists a $q \in \mathbb{N}$ independent of N' such that an alphabet Σ of size q suffices to label the arcs of a tree code of any depth $N' \in \mathbb{N}$. Before the protocol begins, both parties agree on such a tree code of depth N' with corresponding encoding and decoding functions \mathcal{E} and \mathcal{D} (each party uses a separate instance of the same tree code to transmit her/his messages to the other party). The goal is to tolerate error rates up to $\delta = \frac{1}{80}$.

We use the following convention for the variables describing the protocol. On Alice's side, in round i , $x_i^{\text{AD}} z_i^{\text{AD}} \in \{0, 1\}^2$ correspond to the bits she uses for the teleportation decoding on the X and Z Pauli operators, respectively; $x_i^{\text{AM}} z_i^{\text{AM}} \in \{0, 1\}^2$ correspond to the bits of the teleportation measurement on the corresponding Pauli operators; $j_i^{\text{A}} \in \mathbb{Z}$ and $M_i^{\text{A}} \in \{-1, 0, +1\}$ correspond, respectively, to the index of the unitary operator she uses in round i and to whether she uses $U_{j_i^{\text{A}}}^{+1} = U_{j_i^{\text{A}}}$ or its inverse $U_{j_i^{\text{A}}}^{-1} = U_{j_i^{\text{A}}}^\dagger$ or simply applies the identity channel $U_{j_i^{\text{A}}}^0 = \text{I}$ on the AC quantum register; and the counter c_i^{A} keeps track of the sum of all previous messages M_ℓ^{A} , $l \leq i$. On Bob's side, we use a similar set of variables, with superscript B instead of A. All Pauli operators are applied on the virtual C register. When discussing variables obtained from decoding in round i , a superscript i is added to account for the fact that this decoding might be wrong and could be corrected in later rounds. Similarly, a superscript i is used when discussing other variables that are round-dependent.

4.3.1. Representations of the Joint State. The actions taken by Alice and Bob round i are based on their best guesses for the state $|\psi_i\rangle$ of the joint register at the beginning of round i . (Note that $|\psi_1\rangle = |\psi_{\text{init}}\rangle$ is the initial state in the protocol being simulated.) The state $|\psi_i\rangle$ can be classically computed from the information in Alice's and Bob's histories; due to noise, it is generally unknown, at least in part, to Alice and Bob. The analysis rests on the following two representations for the state $|\psi_i\rangle$. The first can be directly computed, up to irrelevant operations of Eve on the E register, as

$$(4) \quad |\psi_i\rangle^{ABCEr} = \prod_{\ell=1}^{i-1} \left(X^{x_\ell^{\text{BM}}} Z^{z_\ell^{\text{BM}}} U_{j_\ell^{\text{B}}}^{M_\ell^{\text{B}}} Z^{z_\ell^{\text{BD}}} X^{x_\ell^{\text{BD}}} X^{x_\ell^{\text{AM}}} Z^{z_\ell^{\text{AM}}} U_{j_\ell^{\text{A}}}^{M_\ell^{\text{A}}} Z^{z_\ell^{\text{AD}}} X^{x_\ell^{\text{AD}}} \right) |\psi_{\text{init}}\rangle^{ABCEr}.$$

Here, from the history s_A of Alice's history tree, we can directly obtain from the ℓ th message sent by Alice, for $\ell = 1 \dots i-1$, the two bits $x_\ell^{\text{AD}} z_\ell^{\text{AD}}$ used to decode the teleportation, the trit M_ℓ^{A} corresponding to the evolution of the protocol performed in round ℓ , and then the two bits $x_\ell^{\text{AM}} z_\ell^{\text{AM}}$ corresponding to the outcome of the teleportation measurement. We then use counters c_ℓ^{A} 's that maintain the sums of the M_ℓ^{A} 's to compute the indices j_ℓ^{A} 's of the noiseless protocol unitary operators used by Alice in round ℓ : $c_0^{\text{A}} = 0$, $c_\ell^{\text{A}} = c_{(\ell-1)}^{\text{A}} + M_\ell^{\text{A}}$, $j_\ell^{\text{A}} = 2c_{(\ell-1)}^{\text{A}} + M_\ell^{\text{A}}$. Note that j_ℓ^{A} depends only on the sequence of messages $M_1^{\text{A}}, M_2^{\text{A}}, \dots, M_{(i-1)}^{\text{A}}, M_i^{\text{A}}$. Similarly, the history s_B of Bob's history tree is used to obtain $x_\ell^{\text{BD}} z_\ell^{\text{BD}}, x_\ell^{\text{BM}} z_\ell^{\text{BM}}$, as well as M_ℓ^{B} , and to compute $c_0^{\text{B}} = 0$, $c_\ell^{\text{B}} = c_{(\ell-1)}^{\text{B}} + M_\ell^{\text{B}}$, $j_\ell^{\text{B}} = 2c_{(\ell-1)}^{\text{B}} + M_\ell^{\text{B}} + 1$. We define $U_j^M = \text{I}$ whenever $j \leq 0$ or $M = 0$. Note that if $M_\ell^{\text{A}} \neq 0$, j_ℓ^{A} is odd and $U_{j_\ell^{\text{A}}}^{M_\ell^{\text{A}}}$ acts on Alice's side. Similarly, if $M_\ell^{\text{B}} \neq 0$, j_ℓ^{B} is even and $U_{j_\ell^{\text{B}}}^{M_\ell^{\text{B}}}$ acts on Bob's side. Also note that $j \leq N' + 1$, so the U_j 's are well-defined, by the noiseless protocol embedding described in [subsection 3.2.1](#).

This first representation of the form of the state $|\psi_i\rangle$ is not too informative in itself, but from it we can classically compute a second representation by recursively cleaning it up. The cleanup is performed by combining as many of the operators as possible as follows: we multiply all consecutive Pauli operators acting on the C register, and simplify consecutive pairs of operators U_ℓ, U_ℓ^{-1} acting on the same set of qubits, to obtain a state of the form

$$(5) \quad |\psi_i\rangle^{ABCEr} = \hat{\sigma}^i \tilde{U}_{t_i}^i \tilde{\sigma}_{t_i}^i \tilde{U}_{t_i-1}^i \tilde{\sigma}_{t_i-1}^i \dots \tilde{U}_2^i \tilde{\sigma}_2^i \tilde{U}_1^i \tilde{\sigma}_1^i U_{r_i} U_{r_i-1} \dots U_2 U_1 |\psi_{\text{init}}\rangle^{ABCEr}$$

with $\hat{\sigma}^i = \pm X^{\hat{x}^i} Z^{\hat{z}^i}$, and for $\ell \in \{1, \dots, t_i\}$, $\tilde{\sigma}_\ell^i = X^{\hat{x}_\ell^i} Z^{\hat{z}_\ell^i}$ for $\hat{x}_\ell^i z_\ell^i, x_\ell^i z_\ell^i \in \{0, 1\}^2$, and $\tilde{U}_\ell^i = U_{\ell'}^{\pm 1}$ for some $r_i - 2t_i \leq \ell' \leq r_i + 2t_i$. The rules used recursively to perform the cleanup are the following: in the case when $\tilde{\sigma}_\ell^i = \text{I}$, for two consecutive unitary operators acting on the same set of qubits we require that if $\ell > 1$, then $\tilde{U}_\ell^i \neq (\tilde{U}_{\ell-1}^i)^{-1}$, and if $\ell = 1$, then $\tilde{U}_1^i \neq U_{r_i+1}$ and $\tilde{U}_1^i \neq U_{r_i}^{-1}$. This last rule is what determines the cut between U_{r_i} and $\tilde{U}_1^i \tilde{\sigma}_1^i$. The parameter r_i determines the number of noiseless protocol unitary operators the parties have been able to successfully apply on the joint register before errors arise, and the parameter t_i determines the number of errors the parties have to correct before being able to evolve the state as in the noiseless protocol. Note that this is well defined: there is a unique representation in the form (5) corresponding to any in the form (4). This second representation is thus powerful: it is the analogue in our setting of the protocol tree representation of classical protocols, and it enables us to precisely keep track of the evolution of the

noiseless protocol simulation. This is why Alice and Bob will always base their actions on their best estimates of this representation.

4.3.2. Choosing the Next Step. To decide which action to take in round i , Alice starts by decoding the possibly corrupted messages $f'_1, \dots, f'_{i-1} \in \Sigma$ received from Bob up to this point to obtain her best guess $s_B^i = \mathcal{D}(f'_1, \dots, f'_{i-1})$ for the history s_B of his history tree. Along with the history s_A of her history tree, she uses this to compute her best guess of the form (5) of the joint state. If her decoding of Bob's history is *good* (error-free), then she has all the information she needs to compute the joint state $|\psi_i\rangle$. She can then choose the correct actions to evolve the simulation. She takes the following actions based on the assumption that her decoding is good. If it is not, errors might accumulate on the joint register ABC , which she will later have to correct.

Alice's next move depends on whether $t_i = 0$ in her best guess for the state $|\psi_i\rangle$. If $t_i = 0$, then she wishes to evolve the protocol one round further, if it is her turn to do so. That is, if r_i is even, then Alice sets $M_i^A = +1$ to apply $U_{r_i+1}^{AC}$, but if r_i is odd, Bob should be the next to apply a unitary operator of the protocol, so she sets $M_i^A = 0$. If $t_i \neq 0$, then she wishes to correct the last error not yet corrected if she is the one who applied it. That is, if $\tilde{U}_{t_i} = U_{\ell'}^{M'}$ for ℓ' odd, then she sets $M_i^A = -M' \in \{\pm 1\}$ (note that in this case it holds that $j_i^A = \ell'$); otherwise, she sets $M_i^A = 0$ and hopes that Bob will correct \tilde{U}_{t_i} . In all cases, with $\hat{\sigma}_i^C = \pm X^{\hat{x}_i} Z^{\hat{z}_i}$, she sets $x_i^{\text{AD}} = \hat{x}_i$, $z_i^{\text{AD}} = \hat{z}_i$ and computes $c_i^A = c_{(i-1)}^A + M_i^A$, $j_i^A = 2c_{(i-1)}^A + M_i^A$. Note that she does not care about the global phase factor ± 1 appearing in $\hat{\sigma}_i$ during the clean-up from the form (4) to the form (5). This phase arises because the Pauli operators X and Z anticommute, and it is irrelevant.

After this classical preprocessing, she can now perform her quantum operations on the AC registers: she first decodes the teleportation operation (and possibly some other Pauli errors remaining on the C register) by applying $Z^{z_i^{\text{AD}}} X^{x_i^{\text{AD}}}$ on the $T_A^{2(i-1)}$ register before swapping registers $T_A^{2(i-1)}$ and C_A , effectively putting the virtual C register into C_A . (Note that in round 1, Alice already possesses the C register so this part is trivial: we let $T_A^0 = C_A$ and set $x_1^{\text{AD}} z_1^{\text{AD}} = 00$.) She then performs $U_{j_i^A}^{M_i^A}$ on the virtual AC register to try to evolve the protocol (or correct a previous error) before teleporting back the virtual C register to Bob using the half of the entangled state in the T_A^{2i-1} register, obtaining measurement outcome $x_i^{\text{AM}} z_i^{\text{AM}} \in \{0, 1\}^2$. She updates her history s_A by following the edge $a_i = (x_i^{\text{AD}} z_i^{\text{AD}}, M_i^A, x_i^{\text{AM}} z_i^{\text{AM}})$ in the history tree, and transmits message $e_i = \mathcal{E}(a_1 \cdots a_i)$ over the noisy classical channel, with \mathcal{E} the encoding function of the tree code.

Upon receiving the message e'_i , a possibly corrupted version of e_i , Bob obtains his best guess s_A^i for Alice's history s_A by computing, with previous messages $e'_1 \cdots e'_{i-1}$, $s_A^i = \mathcal{D}(e'_1 \cdots e'_i)$. He uses this, along with his own history s_B , to compute his best guess of the representation of the state

$$(6) \quad \left(X^{x_i^{\text{AM}}} Z^{z_i^{\text{AM}}} U_{j_i^A}^{M_i^A} Z^{z_i^{\text{AD}}} X^{x_i^{\text{AD}}} \right) |\psi_i\rangle$$

analogous to that in (4). He then cleans this up to obtain a representation analogous to that in (5) and, based on this latest representation, chooses in the same way as Alice his $x_i^{\text{BD}} z_i^{\text{BD}}$, M_i^B , and then uses M_i^B and c_{i-1}^B to compute c_i^B, j_i^B . After this classical preprocessing, he can then perform his quantum operations: he first decodes the teleportation operation by applying $Z^{z_i^{\text{BD}}} X^{x_i^{\text{BD}}}$ on the T_B^{2i-1} register and by swapping it

with C_B , creating a virtual C register, then performs $U_{j_i^B}^{M_i^B}$ on the virtual BC register to try to evolve the protocol before teleporting back the virtual C register to Alice using the half of the entangled state in the T_B^{2i} register, and obtains measurement outcome $x_i^{BM} z_i^{BM}$. He updates his history s_B by following the edge $b_i = (x_i^{BD} z_i^{BD}, M_i^B, x_i^{BM} z_i^{BM})$, and transmits message $f_i = \mathcal{E}(b_1 \cdots b_i)$ over the channel. The round is completed when Alice receives message f'_i , a possibly corrupted version of f_i . After the $\frac{N'}{2}$ rounds, Alice and Bob take the particular registers \tilde{A}, \tilde{B} , and \tilde{C} specified by the noiseless protocol embedding (see subsection 3.2.1) and use them as their respective outcomes for the protocol. If the simulation is successful, the output quantum state corresponds to the ABC subsystem of $|\psi_{\text{final}}\rangle^{ABCE}$ specified by the original noiseless protocol. We later prove that the protocol is successful if the error rate is below $\frac{1}{80}$.

4.3.3. Summary of Protocol. We summarize the protocol below. Alice and Bob start with the state $|\psi_{\text{init}}\rangle$ in the registers $ABC_A E$, the register C_B initialized to $|0\rangle$, the registers $T_A T_B$ initialized to N' EPR pairs $\left[\frac{1}{\sqrt{2}}(|00\rangle + |11\rangle)\right]^{\otimes N'}$, with one qubit each from each EPR pair held by Alice and Bob, and the qubits in registers $\tilde{A}, \tilde{B}, \tilde{C}$ initialized to $|0\rangle$ (cf. the noiseless protocol embedding described in subsection 3.2.1). They also have access to a suitable amount of classical workspace for local computations required for the simulation. They repeat the following for $i = 1, \dots, \frac{N'}{2}$:

1. If $i > 1$, Alice computes $s_B^i = \mathcal{D}(f'_1 \cdots f'_{i-1})$, and for $\ell = 1, \dots, i-1$ she extracts $b_\ell^i = (x_\ell^{iBD} z_\ell^{iBD}, M_\ell^{iB}, x_\ell^{iBM} z_\ell^{iBM})$. These are her best guesses for Bob's messages. She computes the corresponding c_ℓ^{iB}, j_ℓ^{iB} . For $i = 1$, the values of the parameters Alice needs for the simulation are straightforward.
2. Also using s_A , she computes her best guess for the form (5) of the state $|\psi_i\rangle$ of the joint register and of the corresponding $x_i^{AD} z_i^{AD}, M_i^A, c_i^A, j_i^A$, described earlier in this section.
3. If $i > 1$, she completes the teleportation operation by applying $Z^{z_i^{AD}} X^{x_i^{AD}}$ to register $T_A^{2(i-1)}$ and swaps this with the C_A register.
4. She applies $U_{j_i^A}^{M_i^A}$ to the AC_A register, in an attempt to evolve the original protocol.
5. She teleports the C_A register to Bob using entanglement in register T_A^{2i-1} and gets outcomes $x_i^{AM} z_i^{AM}$.
6. Alice updates her state s_A by following edge $a_i = (x_i^{AD} z_i^{AD}, M_i^A, x_i^{AM} z_i^{AM})$ and transmits message $e_i = \mathcal{E}(a_1 \cdots a_i)$ using the noisy classical channel to Bob, who receives e'_i , a possibly corrupted version of e_i .
7. Bob computes $s_A^i = \mathcal{D}(e'_1 \cdots e'_i)$ and also using s_B , performs actions analogous to Alice's. He completes the teleportation operation, swaps register T_B^{2i-1} with C_B , applies the appropriate unitary operation to the register $C_B B$, uses the T_B^{2i} register to teleport the C_B register to Alice, and finally transmits f_i . Round i is completed when Alice receives f'_i , a possibly corrupted version of f_i .

After these $\frac{N'}{2}$ rounds, both Alice and Bob extract their protocol outcomes from the $\tilde{A}\tilde{B}\tilde{C}$ registers specified by the noiseless protocol embedding.

4.4. Analysis. The analysis is done conditioned on some overall classical state (and in particular, some respective views of Alice and Bob) at each round. By a view of Alice or Bob, we mean the transcript of messages sent and received. Moreover, if the adversary Eve has an adaptive, probabilistic strategy, we condition on some

strategy based on the outcome of her previous measurements. We return to this issue later.

The total number of rounds is $\frac{N'}{2}$, with two transmissions per round, for a total of N' transmissions. We define two kinds of rounds: *good* rounds in which both parties correctly decode the each other's history, and *bad* rounds, in which at least one party makes a decoding error. To analyse the protocol, we define a ‘‘potential function’’ $P(i) \in \mathbb{Z}$, which increases at least by some (strictly positive) amount in good rounds, and decreases by at most some other (bounded) amount in bad rounds. The potential function is such that we know the simulation succeeds whenever $P(\frac{N'}{2} + 1) \geq N + 1$. Hence, it is sufficient to bound the ratio of good to bad rounds as a function of the error rate to prove the success of the simulation.

Let us now define $P(i)$ more formally. To do so, we use the representation (5) for the form of the quantum state of the joint registers at the beginning of round i (or equivalently, at the end of round $i - 1$). Recall that r_i determines the number of noiseless protocol unitary operators that the parties have been able to successfully apply on the joint register before errors arise, and t_i determines the number of errors that the parties have to correct before being able to resume the simulation. Define

$$(7) \quad P(i) = r_i - 2t_i.$$

The factor of 2 in front of t_i accounts for the worst-case scenario for the simulation in round i . As will be apparent from our analysis below, in the worst case, all remaining \tilde{U}_ℓ^i 's are applied by the same party who applied U_{r_i-1} and $\tilde{U}_{t_i}^i = U_{r_i-1-2(t_i-1)}^{-1}$. Then, if $P(\frac{N'}{2} + 1) \geq N + 1$, the operators \tilde{U}_ℓ^i in (5) at the end of the simulation (i.e., with $i = N' + 1$) may only be equal to the identity operator, as ensured by the noiseless protocol embedding. Thus the output of the simulation is correct. We now prove the following technical lemma which bounds $P(i)$ as a function of the number of good and bad rounds.

LEMMA 10. *At the end of round i , define*

$$\begin{aligned} N_g^i &= |\{j : j \leq i, \text{ round } j \text{ was good}\}|, \\ N_b^i &= |\{j : j \leq i, \text{ round } j \text{ was bad}\}|. \end{aligned}$$

Then $P(i + 1) \geq N_g^i - 4N_b^i$.

Proof. We prove Lemma 10 by induction. For the base case, $|\psi_1\rangle = |\psi_{\text{init}}\rangle$, so $P(1) = 0$, and the statement holds.

To get a flavor of the induction step, let us look at $P(2)$ at the end of round 1. In round 1, Alice applies U_1 and then teleports the virtual C register. If Bob decodes the message correctly, he applies U_2 and teleports back the virtual register C , leading to a joint state of the form $\hat{\sigma}U_2U_1|\psi_{\text{init}}\rangle$. In this case $N_b^1 = 0$, so $P(2) = 2 \geq 1 = N_g^1$. If there is a decoding error, at worst Bob applies the incorrect Pauli operation to complete the teleportation step, and he still applies U_2 . The joint state is then of the form $\hat{\sigma}U_2\tilde{\sigma}U_1|\psi_{\text{init}}\rangle$. In this case $N_g^1 = 0$, and $P(2) = 1 - 2 = -1 \geq -4 = -4N_b^1$.

For the induction step, given the state $|\psi_i\rangle$ at the end of round $i - 1$, we consider two cases. First, suppose that the i th round is good, so that $N_g^i = N_g^{i-1} + 1$ and $N_b^i = N_b^{i-1}$. Both Alice and Bob correctly reconstruct the state as in (5). If $t_i = 0$, by the simulation rules, at least one of Alice or Bob can advance the original noiseless protocol, and $t_{i+1} = t_i = 0$ and $r_{i+1} \geq r_i + 1$. (If r_i is odd, only Bob advances the protocol, otherwise both do.) If $t_i \geq 1$, again, at least one of Alice or Bob can invert

the unitary operation $\tilde{U}_{t_i}^i$ (depending on the parity of ℓ , where $\tilde{U}_{t_i}^i = U_\ell^{\pm 1}$). Then $t_{i+1} \leq t_i - 1$, and $r_{i+1} \geq r_i$. So in all cases

$$\begin{aligned} P(i+1) &= r_{i+1} - 2t_{i+1} \\ &\geq r_i - 2t_i + 1 \\ &= P(i) + 1 \\ &\geq N_g^{i-1} - 4N_b^{i-1} + 1 \\ &= N_g^i - 4N_b^i. \end{aligned}$$

In the second case, the i th round is bad, so that $N_g^i = N_g^{i-1}$ and $N_b^i = N_b^{i-1} + 1$. At worst, both Alice and Bob decode the received messages incorrectly. With an incorrect guess for the state in (5), Alice's actions in this round either decrease r_i by one, increase t_i by one, or leave both unchanged. The same holds for Bob. At worst, $t_{i+1} = t_i + 2$ and $r_{i+1} = r_i$. The other eight possibilities such as $t_{i+1} = t_i + 1, r_{i+1} = r_i - 1$, or $t_{i+1} = t_i, r_{i+1} = r_i - 2$, lead to a smaller decrease in the potential function P . So

$$\begin{aligned} P(i+1) &= r_{i+1} - 2t_{i+1} \\ &\geq r_i - 2t_i - 4 \\ &= P(i) - 4 \\ &\geq N_g^{i-1} - 4N_b^{i-1} - 4 \\ &= N_g^i - 4N_b^i. \end{aligned}$$

In all cases, $P(i+1) \geq N_g^i - 4N_b^i$ which proves the claim. \square

COROLLARY 11. *If $P(\frac{N'}{2} + 1) \geq N + 1$, then the simulation succeeds with zero error.*

Proof. For notational convenience, in this proof let $r = r_{\frac{N'}{2}+1}$, $t = t_{\frac{N'}{2}+1}$. We also let the superscript $\frac{N'}{2} + 1$ be implicit in all of the operators $\tilde{U}_\ell^{\pm 1}$ that occur in the proof below.

The only unitary operations from the original protocol that Alice applies are of the form $U_\ell^{\pm 1}$ for odd ℓ . Moreover, Alice knows her history at all times. Thus, even in a bad round i , she applies either $U_{\ell+2}$, I , or U_ℓ^{-1} , where U_ℓ is the last unitary operation she applied in the representation (5). A similar statement holds for Bob. Thus, the subscripts in the original protocol of two consecutive unitary operators applied by the same party in (5) do not differ by more than 2.

We have $P(\frac{N'}{2} + 1) = r - 2t \geq N + 1$, so $r \geq N + 1 + 2t$ with $t \geq 0$. In particular, we have $r \geq N + 1$. Once U_r has been applied, the noiseless protocol embedding ensures that the final state of the noiseless protocol in registers ABC is safely stored in local registers $\tilde{A}\tilde{B}\tilde{C}$ that are never changed by $U_{N+2} \cdots U_{N'+1}$ or by the Pauli operations on the virtual C register. It remains to be verified that all of the operators \tilde{U}_ℓ , $0 \leq \ell \leq t$, have indices strictly higher than $N + 1$.

The indices (in the original protocol) of the operators \tilde{U}_ℓ applied by Alice may decrease by at most two at once, and similarly for Bob. So the worst case is if all of the operators \tilde{U}_ℓ are applied by the same party, and are inverses of the noiseless protocol unitary operators. Without loss of generality, we consider only this case. If the party who applied U_r also applies all the operators \tilde{U}_ℓ , then $\tilde{U}_1 = U_r^{-1}$, $\tilde{U}_2 = U_{r-2}^{-1}$,

$\dots, \tilde{U}_t = U_{r-2(t-1)}^{-1}$ and $r - 2(t - 1) > r - 2t = P(\frac{N'}{2} + 1) \geq N + 1$. Thus the simulation generates the correct output. Similarly, if the party who applied U_{r-1} also applies all the operators \tilde{U}_ℓ , then $\tilde{U}_1 = U_{r-1}^{-1}, \tilde{U}_2 = U_{r-3}^{-1}, \dots, \tilde{U}_t = U_{r-2t+1}$, and $r - 2t + 1 > r - 2t = P(\frac{N'}{2} + 1) \geq N + 1$. In all cases, the safe registers $\tilde{A}\tilde{B}\tilde{C}$ to be outputted by the parties contain the ABC subsystem of $|\psi_{\text{final}}\rangle$ at the end of round $\frac{N'}{2}$ whenever $P(\frac{N'}{2} + 1) \geq N + 1$. \square

We now show that if the number of errors as a fraction of N' , which is the total number of classical symbols transmitted over the adversarial channel, is bounded by a particular constant $\delta > 0$, then we are guaranteed that the simulation succeeds. We do this in two steps: we first give a bound on the fraction of bad rounds as a function of the error rate, and then use it to show that below a certain error rate, the simulation succeeds.

The bound on the fraction of bad rounds as a function of the error rate we use follows from the more general result in [Lemma 16](#), which we prove in the next section when studying a protocol designed to tolerate the highest possible error rate. The implication we use here is the following: if the error rate is bounded by δ (so there are at most $\delta N'$ errors) and the tree code distance of both Alice and Bob's tree code is at least α , then the number of bad rounds N_b is bounded as $N_b \leq (2\delta + \varepsilon_\alpha)N'$, where $\varepsilon_\alpha = 1 - \alpha$.

We are now ready to prove that the simulation succeeds with the parameters chosen for our protocol. We have $\varepsilon_\alpha = \frac{1}{40}$, $\delta = \frac{1}{80}$, $N' = 4(N + 1)$, so

$$\begin{aligned} P\left(\frac{N'}{2} + 1\right) &\geq N_g - 4N_b \\ &= \frac{N'}{2} - 5N_b \\ &\geq \frac{N'}{2} - 5(2\delta + \varepsilon_\alpha)N' \\ &= N' \left(\frac{1}{2} - \frac{10}{80} - \frac{5}{40} \right) \\ &= \frac{1}{4}N' \\ &= N + 1 . \end{aligned}$$

Here, the first inequality is from [Lemma 10](#), the first equality is by definition of N_g , N_b , i.e., $\frac{N'}{2} = N_g + N_b$, and the second inequality is from our bound on N_b due to [Lemma 16](#). The fact that the simulation succeeds is then immediate from [Corollary 11](#).

Note that the form of the simulation protocol does not depend on the particular protocol to be simulated but only on its length N and the noise parameter of the adversarial channel we want to tolerate. Also note that even if the adversary is adaptive and probabilistic (with adaptive, random choices depending on her measurement outcomes and her view of the transcript, as allowed by the model), the simulation succeeds regardless of her choice of action. As long as the corruption rate is bounded by δ , our analysis holds in each branch of the adversary's probabilistic computation. We use the definition of the class $\mathcal{A}_{\delta,q,N'}^S$ to prove that, indeed, the simulation succeeds with zero error. (See [Appendix A.2](#) for the definition of $\mathcal{A}_{\delta,q,N'}^S$.)

For $|\psi\rangle \in \mathcal{H}(A \otimes B \otimes C \otimes E \otimes R)$, with R a purifying system of the same size as

$A \otimes \tilde{B} \otimes \tilde{C} \otimes E$, we have that

$$(\Pi \otimes \mathbb{I}^R)(|\psi\rangle) = \text{Tr}_E(U_N \cdots U_1 |\psi\rangle\langle\psi| U_1^\dagger \cdots U_N^\dagger),$$

where Π is the protocol being simulated. For any adversary in $\mathcal{A} \in \mathcal{A}_{\delta,q,N'}^S$, the simulation yields state

$$(S^\Pi(\mathcal{A}) \otimes \mathbb{I}^R)(|\psi\rangle) = \text{Tr}_{-(\tilde{A}\tilde{B}\tilde{C}R)}(\mathcal{M}_{N'+1}^\Pi \mathcal{N}_{N'} \mathcal{M}_{N'}^\Pi \cdots \mathcal{M}_2^\Pi \mathcal{N}_1 \mathcal{M}_1^\Pi(|\psi\rangle\langle\psi|)),$$

in which the $-(\tilde{A}\tilde{B}\tilde{C}R)$ subscript for the partial trace means that we trace all except the $\tilde{A}\tilde{B}\tilde{C}R$ registers, and the instrument \mathcal{M}_ℓ^Π is the simulation step for the ℓ th local computation by the corresponding party. Then we can rewrite

$$\begin{aligned} & (S^\Pi(\mathcal{A}) \otimes \mathbb{I}^R)(|\psi\rangle) \\ &= \sum_{x_T y_T z} p_{X_T Y_T Z}(x_T, y_T, z | |\psi\rangle) |x_T\rangle\langle x_T|^{X_T} \otimes |y_T\rangle\langle y_T|^{Y_T} \otimes |z\rangle\langle z|^Z \otimes \rho(x_T, y_T, z) \end{aligned}$$

where X_T, Y_T are the registers containing the views x_T, y_T of the transcript as seen by Alice and Bob, respectively, Z is the adversary's classical register, $\rho(x_T, y_T, z)$ are some quantum states, and $p_{X_T Y_T Z}$ is a probability distribution conditional on the input $|\psi\rangle$. By definition of the class $\mathcal{A}_{\delta,q,N'}^S$, we have that, conditioned on some classical state z of Eve, $\rho(x_T, y_T, z)$ suffers at most $\delta N'$ corruptions by Eve for any possible transcript views x_T, y_T . So, by the above analysis, the $\tilde{A}\tilde{B}\tilde{C}R$ subsystems contains $\text{Tr}_E(U_N \cdots U_1 |\psi\rangle\langle\psi| U_1^\dagger \cdots U_N^\dagger)$, a perfect copy of $(\Pi \otimes \mathbb{I}^R)(|\psi\rangle)$ for any views x_T, y_T of the transcripts of Alice and Bob, respectively. Hence, tracing over all subsystems but $\tilde{A}\tilde{B}\tilde{C}R$, we obtain $(\Pi \otimes \mathbb{I}^R)(|\psi\rangle)$, and the simulation protocol succeeds with zero probability of error at simulating any noiseless protocol of length N against all adversaries in $\mathcal{A}_{\delta,q,N'}^S$.

We have thus established the following. We use a tree code of arity $d = 48$ and distance parameter $\alpha = 1 - \varepsilon_\alpha = \frac{39}{40}$. With $q = |\Sigma|$ chosen according to [Lemma 3](#), $R_C = \frac{N}{N' \log q} = \frac{1}{4(1 + \frac{1}{N}) \log q} \geq \frac{1}{8 \log q}$, $R_E = \frac{1}{\log q}$, and $\delta = \frac{1}{80}$, we have that for all N , there exists a universal simulation protocol in the shared entanglement model that, given black-box access to any two-party quantum protocol of length N in the noiseless model, succeeds with zero probability of error at simulating the noiseless protocol on any input (independent of the contents of the purifying register held by Eve) while transmitting $\frac{1}{R_C \log q} N$ symbols from an alphabet Σ of size q over any adversarial channel with error rate δ , and consuming $\frac{R_E}{R_C} N$ EPR pairs. This proves [Theorem 9](#).

5. Tolerating Maximal Error Rates. We show how we can modify the basic protocol described in the last section such that it tolerates an error rate up to $\frac{1}{2} - \varepsilon$, for arbitrarily small $\varepsilon > 0$, in the shared entanglement model. In particular, we show that given an adversarial channel in the shared entanglement model with error rate strictly smaller than $\frac{1}{2}$, we can simulate any noiseless protocol of length N with negligible error over this channel using a linear in N number of constant-size transmissions and consuming a linear number of EPR pairs.

THEOREM 12. *There exists a constant $c > 0$ such that for arbitrarily small constant $\varepsilon > 0$, there exist a communication rate $R_C > 0$, an alphabet size $q \in \mathbb{N}$, and an entanglement consumption rate $R_E \geq 0$ such that for all $N \in 2\mathbb{N}$, there exists a universal simulator S for noiseless quantum protocols of length N with the following properties. The simulator S is in the shared entanglement model, has length N' ,*

communication rate R_C , transmission alphabet size q , and entanglement consumption rate R_E . Further, the simulation succeeds with error at most 2^{-cN} for all noiseless protocols of length N against all adversaries in $\mathcal{A}_{\frac{1}{2}-\epsilon, q, N'}^S$.

This is optimal since we also prove that no interactive protocol can withstand an error rate of $\frac{1}{2}$ in this model. In particular, given any two-party quantum protocol of length N in the noiseless model, no simulation protocol in the shared entanglement model can tolerate an error rate of $\frac{1}{2}$ and succeed in simulating the noiseless protocol with worst-case error lower than the worst-case error of the best uni-directional protocol.

THEOREM 13. *For all noiseless protocol lengths $N \in \mathbb{N}$, communication rates $R_C > 0$, transmission alphabet sizes $q \in \mathbb{N}$, entanglement consumption rates $R_E \geq 0$, and simulation protocols S in the shared entanglement model of length N' with the above parameters, there exists an adversary $\mathcal{A} \in \mathcal{A}_{\frac{1}{2}, q, N'}^S$ and a unidirectional protocol U such that for all noiseless protocols Π of length N , $\|\mathcal{S}^\Pi(\mathcal{A}) - \Pi\|_\diamond \geq \|U - \Pi\|_\diamond$. This result holds in the oblivious model as well as the alternating communication model.*

5.1. Proof of Optimality. To prove [Theorem 13](#), we observe that the argument of Ref. [25] in the classical case applies here as well; we need only note that if the error rate is $\frac{1}{2}$ with alternating communication in the shared entanglement model, then an adversary can completely corrupt all of the transmissions of either Alice or Bob, at his choosing. For example, the adversary could replace all of Bob's transmissions by a fixed message and leave Alice's messages unchanged. Effectively, Bob does not transmit any information to Alice, and this protocol can be simulated in the uni-directional model. Indeed, suppose that for a fixed register E , transmission alphabet Σ of size q , noiseless protocol length N , and simulation protocol length N' , the adversary $\mathcal{A}_{\frac{1}{2}}$ maps all transmissions from Bob to Alice to a fixed symbol $e_0 \in \Sigma$ for any simulator S of length N' that tries to simulate a noiseless protocol Π of length N . We construct \mathcal{M}_1^U , which is the composition of all operations of Alice in S while replacing all messages of Bob by e_0 . In the unidirectional protocol U , Alice applies the instrument \mathcal{M}_1^U to Alice's share of the joint state in the simulation protocol. The quantum communication from Alice to Bob is the concatenation of all the messages from Alice in the simulation protocol, along with Bob's share of the initial joint state. Bob would then apply the instrument \mathcal{M}_2^U , which is the sequential application of all his operations in the simulation protocol S . This unidirectional protocol simulates S running against the adversary $\mathcal{A}_{\frac{1}{2}}$ for any noiseless protocol and any input and then produces the same output.

The above proof also applies in an oblivious model for noisy communication. In an oblivious model, the order in which the parties speak is fixed by the protocol and does not depend on the input or the actions of the adversary. An adversary can choose to disrupt all of the messages of the party who communicates at most half the number of bits. Hence, the proof also extends to the case of oblivious, but not necessarily alternating, communication. In such a case, the simulation protocol would also define a function $\text{Speak} : [N'] \rightarrow \{A, B\}$ known to all (Alice, Bob, and Eve) which specifies whose turn it is to speak and is independent of both the input and the action of Eve.

We can further extend the argument to the case of a Speak function, which depends on some secret key and is unknown to Eve, so Eve does not always know who is going to speak more often. In that case, Eve can flip a random bit to decide which party's communication she is going to corrupt. If the communication is classical, then

a reasonable assumption is that Eve can see who speaks *before* she decides whether or not to corrupt a message. In this case, the statement is changed to “ $\|S^{\Pi}(\mathcal{A}) - \Pi\|_{\diamond}$ is bounded away from zero”, as can be seen by considering, for increasing N , some family of protocols computing, for example, the bitwise parity function of $\frac{N}{2}$ bits output by both parties or the swap function in which Alice and Bob want to exchange their A, B registers. An extension of the argument of the proof of [Theorem 19](#) shows that the fidelity is also bounded away from 1 for the case of protocols computing the inner product binary function. To reach the $\frac{1}{2}$ bound on the tolerable error rate, the parties would then need an adaptive strategy that depends on the sequence of errors applied by the adversary. However, this is dangerous in a noisy model: depending on the error pattern, the parties might not agree on whose turn it is to speak, and they could run into synchronisation problems.

5.2. Proof of Achievability.

5.2.1. Description of the Simulation. The proof of achievability is somewhat more involved. It follows ideas similar to those of the basic simulation, but the protocol must be carefully analysed and optimized. We start by setting up new notation that enables us to do so. The intuition given in [subsection 4.2](#) still applies here, but parameters which were fixed in the basic case now depend on the parameter ε when we wish to tolerate an error rate of $\frac{1}{2} - \varepsilon$. In particular, the distance parameter $\alpha = 1 - \varepsilon_{\alpha}$, as well as the length of the protocol $N' = \ell N$, now changes. Since the parties have access to shared entanglement, they do not need to distribute it at the beginning of the protocol, and they can also use it to generate a secret key unknown to the adversary Eve. The secret key is used to generate a blueberry code with erasure parameter $\varepsilon_{\beta} = (|\Sigma| - 1)/(|\Gamma| - 1)$, with Σ the tree code alphabet and Γ the blueberry code alphabet. Each of the tree code transmission alphabet symbols is further encoded with the blueberry code before transmission over the noisy channel. A corruption caused by the adversary is detected as an erasure with probability $1 - \varepsilon_{\beta}$. When an erasure is detected by either party in a round, that party does not attempt to continue the simulation (as in the previous section) in that round. The corresponding trit sent is 0, and the teleportation decoding bits are 00. Otherwise, the structure of the protocol is mainly unchanged.

We summarize the optimized protocol below. Alice and Bob start with the state $|\psi_{\text{init}}\rangle$ in the registers ABC_AE , the register C_B initialized to $|0\rangle$, the registers $T_A T_B$ initialized to N' EPR pairs $\left[\frac{1}{\sqrt{2}}(|00\rangle + |11\rangle)\right]^{\otimes N'}$, with one qubit each from each EPR pair held by Alice and Bob, and the qubits in registers $\tilde{A}, \tilde{B}, \tilde{C}$ initialized to $|0\rangle$ (cf. the noiseless protocol embedding described in [subsection 3.2.1](#)). They measure a suitable number of additional EPR pairs to produce a secret key unknown to the adversary. Using this, they generate common blueberry codes $\mathcal{B}_1, \mathcal{B}_2, \dots, \mathcal{B}_{N'}$ uniformly and independently from the set of permutations over Γ . They also have access to a suitable amount of classical workspace for local computations required for the simulation.

Alice and Bob repeat the following for $i = 1 \dots \frac{N'}{2}$:

1. For $i = 1$, there is no message to be decoded, and the values of the parameters needed for the simulation are straightforward. Alice continues with [step 3](#). If $i > 1$, Alice decodes the blueberry encoding of Bob’s possibly corrupted last transmission. If she detects an erasure, she sets $M_i^A = 0$, $x_i^{\text{AD}} = z_i^{\text{AD}} = 0$ and $f'_{i-1} = \perp$ and skips to [step 4](#). Otherwise, she decodes the transmission as $f'_{i-1} \in \Sigma$, a possibly corrupted version of Bob’s last tree encoding f_{i-1} , and

- continues with step 2.
2. Alice computes $s_B^i = \mathcal{D}(f'_1 \cdots f'_{i-1})$, and for $\ell = 1, \dots, i-1$ she extracts $b_\ell^i = (x_\ell^{i\text{BD}} z_\ell^{i\text{BD}}, M_\ell^{i\text{B}}, x_\ell^{i\text{BM}} z_\ell^{i\text{BM}})$, her best guess for Bob's messages, and the corresponding $c_\ell^{i\text{B}}, j_\ell^{i\text{B}}$.
 3. Using s_A, s_B , she computes her best guess for the state $|\psi_i\rangle$ of the joint register, and the corresponding $x_i^{\text{AD}} z_i^{\text{AD}}, M_i^{\text{A}}, c_i^{\text{A}}, j_i^{\text{A}}$.
 4. She completes the teleportation by applying $Z^{z_i^{\text{AD}}} X^{x_i^{\text{AD}}}$ to register $T_A^{2(i-1)}$ and swaps this with the C_A register.
 5. She tries to make progress in the simulation by applying $U_{j_i^{\text{A}}}^{M_i^{\text{A}}}$ to the AC_A register.
 6. She teleports the C_A register to Bob using entanglement in register T_A^{2i-1} and gets outcomes $x_i^{\text{AM}} z_i^{\text{AM}}$.
 7. Alice updates her history s_A by following edge $a_i = (x_i^{\text{AD}} z_i^{\text{AD}}, M_i^{\text{A}}, x_i^{\text{AM}} z_i^{\text{AM}})$, computes $e_i = \mathcal{E}(a_1 \cdots a_i)$, and transmits the blueberry encoding $\mathcal{B}_{2i-1}(e_i)$ of e_i over the noisy channel to Bob.
 8. Upon receiving a possibly corrupted version of Alice's last transmission, Bob decodes the blueberry code layer: he either detects an erasure and sets $e'_i = \perp$, or else decodes the transmission as $e'_i \in \Sigma$, a possibly corrupted version of e_i .
 9. Bob computes $x_i^{\text{BD}} z_i^{\text{BD}}, M_i^{\text{B}}$ in the same way as Alice, depending on whether or not he detects an erasure. In more detail, if Bob does not detect an erasure, he decodes $s_A^i = \mathcal{D}(e'_1 \cdots e'_i)$ and also uses s_B to compute the above parameters. He then performs actions on his registers analogous to Alice's: he completes the teleportation step, swaps register T_B^{2i-1} with C_B , applies the operator $U_{j_i^{\text{B}}}^{M_i^{\text{B}}}$ to the registers BC_B , uses the T_B^{2i} register to teleport back the C_B register to Alice, computes f_i , and transmits the blueberry encoding $\mathcal{B}_{2i}(f_i)$ of f_i to Alice. Round i is completed when Alice receives a possibly corrupted version of this message.

After these $\frac{N'}{2}$ rounds, both Alice and Bob extract the output of the simulation from the $\tilde{A}\tilde{B}\tilde{C}$ registers specified by the noiseless protocol embedding.

5.2.2. Analysis. As in the proof in [subsection 4.4](#), the analysis is first carried conditioned on some respective views of Alice and Bob of the transcript at each round. An additional component is the conditioning on some classical state z of the Z register of the adversary, Eve, and the averaging over the shared secret key used for the blueberry code. In particular, if the adversary has an adaptive and probabilistic strategy, we condition on some strategy consistent with the transcript on which we have already conditioned. We return to this issue later.

We again define a function $P(i)$ such that the simulation succeeds whenever $P(\frac{N'}{2} + 1) \geq N + 1$. Using the notation and the form of the state $|\psi_i\rangle$ as in [\(5\)](#) on the joint register $ABCE$ at the beginning of round i (or at the end of round $i-1$), we let $P(i) = r_i - 2t_i$ (i.e., the same potential function works for the enhanced simulation as well). We now have three kinds of rounds: *good* rounds, in which both parties decode correctly the other party's history; *bad* rounds in which at least one party makes a decoding error; and *erasure* rounds, in which no party makes a decoding error, but at least one party decodes an erasure from the blueberry code. (In an erasure round, the party detecting an erasure applies the identity operator on the quantum register before teleporting it back.)

We state an analogue of the technical [Lemma 10](#) and its corollary.

LEMMA 14. *At the end of round i , define*

$$\begin{aligned} N_g^i &= |\{j : j \leq i, \text{ round } j \text{ was good}\}|, \\ N_b^i &= |\{j : j \leq i, \text{ round } j \text{ was bad}\}|, \\ N_e^i &= |\{j : j \leq i, \text{ round } j \text{ was an erasure round}\}|. \end{aligned}$$

Then $P(i+1) \geq N_g^i - 4N_b^i$.

The proof of this lemma and its corollary below are omitted since they are nearly identical to the proofs in the basic simulation. The only difference is if at least one party detects an erasure in some round, which may be a bad round or an erasure round. We sketch the argument in the case that round i is an erasure round. The only unitary operation applied by a party that detects an erasure, is a Pauli operator on the virtual communication register C . If both parties detect an erasure, $r_{i+1} = r_i$ and $t_{i+1} = t_i$. If any one party decodes correctly and the other detects an erasure, we have $r_{i+1} \geq r_i$ and $t_{i+1} \leq t_i$, so $P(i+1) \geq P(i)$. (The function increases only if the party that decoded correctly can apply $U_{r_{i+1}}$ or $\tilde{U}_{t_i}^{-1}$ as defined by the simulation; i.e., that party holds the registers on which the said unitary operation acts.) In both cases, the quantity $N_g^i - 4N_b^i = N_g^{i-1} - 4N_b^{i-1} \leq P(i)$, so $P(i+1) \geq N_g^i - 4N_b^i$.

COROLLARY 15. *If $P(\frac{N'}{2} + 1) \geq N + 1$, then the simulation succeeds with zero error.*

Hence, it suffices to bound the ratio of bad to good rounds as a function of the corruption rate in order to prove the success of the simulation. To do so, we show that depending on a given tolerable error rate $\frac{1}{2} - \varepsilon$, we can vary the distance parameter $\alpha = 1 - \varepsilon_\alpha$ of the tree codes used by Alice and Bob, as well as the erasure parameter $\beta = 1 - \varepsilon_\beta$ of the blueberry codes they use, and make this ratio as low as desired (except with negligible probability in the random choice of the shared secret key used for the blueberry code). However, there is now a third kind of round, and we would also want to ensure that the ratio of good rounds versus erasure rounds does not become arbitrarily low and that $P(\frac{N'}{2} + 1) \geq N + 1$.

We focus on the numbers $N_g = N_g^{\frac{N'}{2}+1}$, $N_b = N_b^{\frac{N'}{2}+1}$ and $N_e = N_e^{\frac{N'}{2}+1}$ of good, bad and erasure rounds in the whole simulation, respectively. To bound the fraction of bad rounds as a fraction of the corruption rate, we appeal to a corollary of the following technical lemma. The lemma derives a new bound on tree codes with an erasure symbol. Since this result only pertains to the structure of such codes independent of our application, it might have applications to classical interactive coding and other settings as well.

LEMMA 16. *If there is a bound δ on the fraction of the total number of transmissions N' that are corrupted and not detected as erasure errors by the blueberry code, then the number N_b of bad rounds in the whole simulation is bounded as $N_b \leq (2\delta + \varepsilon_\alpha)N'$, where $\varepsilon_\alpha = 1 - \alpha$, and α is the distance parameter of the tree code with an erasure symbol used by Alice and Bob.*

Proof. For any $1 \leq i \leq j \leq \frac{N'}{2}$, let $I_e^A(i, j)$, $I_b^A(i, j)$, $I_g^A(i, j)$ be the subset of rounds $i, i+1, \dots, j-1, j$ in which the symbol that Alice gets from the blueberry decoding is an erasure, an error (i.e., an incorrect symbol), or the original encoded symbol, respectively. Note that these are disjoint sets satisfying $I_e^A(i, j) \cup I_b^A(i, j) \cup I_g^A(i, j) = [i, j]$, where $[i, j]$ denotes the set $\{i, i+1, \dots, j-1, j\}$. Similarly, let $J_b^A(i, j)$ and $J_g^A(i, j)$ be the subsets of $[i, j]$, respectively, in which the sequence of messages

Alice receives from the tree decoding corresponds to a decoding error and the correct decoding. Again note that $I_e^A(i, j) \cup J_b^A(i, j) \cup J_g^A(i, j) = [i, j]$, a disjoint union. We define analogous subsets for Bob with A's replaced by B's in the notation. Using this notation, we have

$$N_b = \left| J_b^A\left(1, \frac{N'}{2}\right) \cup J_b^B\left(1, \frac{N'}{2}\right) \right|, \quad \text{and}$$

$$\left| I_b^A\left(1, \frac{N'}{2}\right) \right| + \left| I_b^B\left(1, \frac{N'}{2}\right) \right| \leq \delta N' .$$

The statement we wish to prove is

$$\left| J_b^A\left(1, \frac{N'}{2}\right) \cup J_b^B\left(1, \frac{N'}{2}\right) \right| \leq 2\delta N' + \varepsilon_\alpha N' .$$

We prove the following stronger statements, which claim that the number of rounds in which a party makes a tree code decoding error is only slightly larger than the number of rounds in which that party makes a blueberry code decoding error:

$$(8) \quad \left| J_b^A\left(1, \frac{N'}{2}\right) \right| \leq 2 \left| I_b^A\left(1, \frac{N'}{2}\right) \right| + \frac{1}{2} \varepsilon_\alpha N' ,$$

and

$$\left| J_b^B\left(1, \frac{N'}{2}\right) \right| \leq 2 \left| I_b^B\left(1, \frac{N'}{2}\right) \right| + \frac{1}{2} \varepsilon_\alpha N' .$$

The proofs of the two statements are similar, so we only prove the statement for Alice's subsets. To simplify notation, we drop the A superscripts. For any subset K of $[\frac{N'}{2}]$ and any two strings $\bar{e}, \bar{e}' \in \Sigma^t$ with $\bar{e} = e_1 \cdots e_t$ and $\bar{e}' = e'_1 \cdots e'_t$, and $t \leq N'/2$, define $\Delta_K(\bar{e}, \bar{e}') = |\{i \in K : i \leq t, e_i \neq e'_i\}|$. Note that with $\bar{K} = [\frac{N'}{2}] \setminus K$, $\Delta(\bar{e}, \bar{e}') = \Delta_K(\bar{e}, \bar{e}') + \Delta_{\bar{K}}(\bar{e}, \bar{e}')$, and $\Delta_K(\bar{e}, \bar{e}') \leq |K|$.

We are now ready to prove the statement (8). We prove by strong induction on the number of rounds t that $|J_b(1, t)| \leq 2|I_b(1, t)| + \varepsilon_\alpha t$. The base case, $t = 1$, is immediate: in the first round, Alice does not decode any message, so that the two sets $J_b(1, 1), I_b(1, 1)$ are empty.

For $t > 1$, assume that

$$|J_b(1, j)| \leq 2|I_b(1, j)| + \varepsilon_\alpha j ,$$

for all j with $0 \leq j < t$, where we define $J_b(1, 0) = I_b(1, 0) = \emptyset$. If in round t , $t > 1$, Alice detects an erasure or decodes correctly, then the induction step is immediate. Hence, for the induction step, we consider the case of incorrect decoding. Let $\bar{a} \in [d]^t$ be the sequence of transmitted messages, $\bar{e} = \bar{\mathcal{E}}(\bar{a}) \in \Sigma^t$ the corresponding sequence of transmissions, $\bar{e}' \in \Sigma^t$ the sequence of possibly corrupted receptions, $\bar{a}' = \mathcal{D}(\bar{e}') \in [d]^t$ the sequence of decoded messages, and $\bar{e}'' = \bar{\mathcal{E}}(\bar{a}')$ the encoding of \bar{a}' in the tree code. Then, by the decoding condition, $\Delta(\bar{e}'', \bar{e}') \leq \Delta(\bar{e}, \bar{e}')$. Let $\ell = L(\bar{a}, \bar{a}')$ be the distance of \bar{a}, \bar{a}' to their least common ancestor. Then $\Delta_{[1, t-\ell]}(\bar{e}'', \bar{e}') = 0$, as the encodings have the same prefix as well. Since $\bar{e}'' \neq \bar{e}'$, note that $1 \leq \ell \leq t$. By the induction hypothesis,

$$|J_b(1, t-\ell)| \leq 2|I_b(1, t-\ell)| + \varepsilon_\alpha(t-\ell) .$$

By definition

$$\begin{aligned} |J_b(1, t)| &= |J_b(1, t - \ell)| + |J_b(t - \ell + 1, t)|, \\ |I_b(1, t)| &= |I_b(1, t - \ell)| + |I_b(t - \ell + 1, t)|, \end{aligned}$$

so it suffices to prove

$$(9) \quad |J_b(t - \ell + 1, t)| \leq 2|I_b(t - \ell + 1, t)| + \varepsilon_\alpha \ell$$

to complete the proof.

Let $K = I_e(t - \ell + 1, t)$, the set of rounds in which Alice detects an erasure. Since codewords in the tree code, in particular \bar{e}'' and \bar{e} , do not contain the erasure symbol, the decoding condition $\Delta(\bar{e}'', \bar{e}') \leq \Delta(\bar{e}', \bar{e})$ is equivalent to $\Delta_K(\bar{e}'', \bar{e}') \leq \Delta_{\bar{K}}(\bar{e}', \bar{e})$. We therefore have

$$\begin{aligned} \Delta(\bar{e}'', \bar{e}) &= \Delta_K(\bar{e}'', \bar{e}) + \Delta_{\bar{K}}(\bar{e}'', \bar{e}) \\ &\leq |I_e(t - \ell + 1, t)| + \Delta_{\bar{K}}(\bar{e}'', \bar{e}) \\ &\leq |I_e(t - \ell + 1, t)| + \Delta_{\bar{K}}(\bar{e}'', \bar{e}') + \Delta_{\bar{K}}(\bar{e}', \bar{e}) \\ &\leq |I_e(t - \ell + 1, t)| + 2\Delta_{\bar{K}}(\bar{e}', \bar{e}) \\ (10) \quad &= |I_e(t - \ell + 1, t)| + 2|I_b(t - \ell + 1, t)| . \end{aligned}$$

On the other hand, the tree code distance condition stipulates that $\Delta(\bar{e}'', \bar{e}) \geq \alpha \ell = (1 - \varepsilon_\alpha)\ell$ since $\bar{a} \neq \bar{a}'$. Along with (10), this gives

$$(11) \quad \ell \leq \Delta(\bar{e}'', \bar{e}) + \varepsilon_\alpha \ell \leq |I_e(t - \ell + 1, t)| + 2|I_b(t - \ell + 1, t)| + \varepsilon_\alpha \ell .$$

We use this to bound the number of bad rounds for Alice, in terms of the number of blueberry decoding errors she encounters. We have

$$\begin{aligned} \ell &= |I_e(t - \ell + 1, t)| + |J_b(t - \ell + 1, t)| + |J_g(t - \ell + 1, t)| \\ (12) \quad &\geq |I_e(t - \ell + 1, t)| + |J_b(t - \ell + 1, t)| . \end{aligned}$$

Combining (11) and (12), we get the claimed bound, as in (9). \square

COROLLARY 17. *If the corruption rate c of the channel satisfies $0 \leq c < \frac{1}{2}$, then except with probability smaller than $2^{-\Omega(N')}$, where N' is the length of the simulation protocol, the total number of bad rounds in the simulation is bounded as $N_b \leq (2\varepsilon_\beta + \varepsilon_\alpha)N'$, where $\varepsilon_\alpha = 1 - \alpha$, α is the distance parameter of the tree code, $\varepsilon_\beta = 1 - \beta$, and β is the erasure parameter of the blueberry code.*

Proof. Suppose that the transmitted symbol is $g_i \in \Gamma$ after a blueberry encoding \mathcal{B}_j (where $j \in \{2i - 1, 2i\}$) and that conditional on her classical state and some measurement outcomes z_k until round i , Eve chooses to corrupt g_i into a different $g'_i \in \Gamma$. This action is independent of the randomness used in \mathcal{B}_j , and it holds that $\Pr[B_i^{-1}(g'_i) \in \Sigma | z_1, \dots, z_i] = \varepsilon_\beta$. This is independent of the classical state and any measurement outcome z_i of Eve. We consider two cases. First, suppose the corruption rate c is bounded as $\varepsilon_\beta \leq c < \frac{1}{2}$ (so that the corruption rate is at least a constant). By Lemma 7, with probability $1 - 2^{-\Omega(N')}$ at least a $(1 - 2\varepsilon_\beta)$ -fraction of the cN' corrupted transmissions are detected as erasures. So the blueberry decoding gives at most $cN' - c(1 - 2\varepsilon_\beta)N' = 2c\varepsilon_\beta N' < \varepsilon_\beta N'$ transmission errors, except with probability negligible in N' . Taking $\delta = \varepsilon_\beta$ in the statement of Lemma 16 gives us the corollary. If $0 \leq c \leq \varepsilon_\beta$, then the corollary is immediate from Lemma 16, with $\delta = \varepsilon_\beta$. \square

With the above result in hand, we can show that if the corruption rate is $\frac{1}{2} - \varepsilon$ with $\varepsilon > 0$, and we take $\varepsilon_\alpha = \frac{1}{20}\varepsilon, \varepsilon_\beta = \frac{1}{40}\varepsilon, N' \geq \frac{2}{\varepsilon}(N + 1)$, then except with negligible probability, the simulation succeeds:

$$\begin{aligned}
P\left(\frac{N'}{2} + 1\right) &\geq N_g - 4N_b \\
&= \frac{N'}{2} - N_e - 5N_b && \text{(By Lemma 14)} \\
&\geq \varepsilon N' - 5N_b && \text{(since } N'/2 = N_g + N_b + N_e) \\
&\geq \varepsilon N' - 5(2\varepsilon_\beta + \varepsilon_\alpha)N' && \text{(since } N_e \leq (1/2 - \varepsilon)N') \\
&= N' \left(\varepsilon - \frac{10}{40}\varepsilon - \frac{5}{20}\varepsilon \right) && \text{(By Corollary 17)} \\
&= \frac{1}{2}\varepsilon N' \\
&\geq N + 1 .
\end{aligned}$$

That the simulation succeeds is now immediate from [Corollary 15](#).

The above statement holds conditional on some classical state z of the Z register of Eve and on some respective views of Alice and Bob of the transcript at each round. To prove [Theorem 12](#), we argue as in [subsection 4.4](#) in order to translate these results into the output state produced by the protocols, even when we consider inputs entangled with some reference register R . We do not repeat the whole analysis here, since it is nearly identical to the analysis in [subsection 4.4](#) once we make the following observation. An arbitrary adversary Eve fitting the framework of the shared entanglement model could have adaptive, probabilistic behaviour based on previous measurement outcomes. However, these probabilistic choices are independent of the secret key generated by Alice and Bob for the blueberry code. As in [subsection 4.4](#), the above result holds for each probabilistic choice of Eve. Summing over all such choices, we obtain the same result, proving [Theorem 12](#).

6. Results in Other Models. By adapting the results in the shared entanglement model for an adversarial error model, we can obtain several other interesting results. We first complete our study of the shared entanglement model with results in a random error setting. We then consider the quantum model and obtain results for both adversarial and random error settings. We also prove that the standard forward quantum capacity of the quantum channels used does not characterize their communication capacity in the interactive communication scenario. Finally, we consider a variation on the shared entanglement model in which, along with the noisy classical communication, the shared entanglement is also noisy.

6.1. Shared Entanglement Model with Random Errors. In this section we consider two-party protocols with prior shared entanglement and classical communication over binary symmetric channels. Given a two-party quantum protocol of length N in the noiseless model and any $C > 0$, we exhibit a simulation protocol in the shared entanglement model that is of length $O(\frac{1}{C}N)$ and succeeds in simulating the original protocol with negligible error over classical binary symmetric channels of capacity C . More precisely, we have the following theorem.

THEOREM 18. *There exist constants $c, l > 0$ such that given any $C > 0$ and $N \in 2\mathbb{N}$, there exists a universal simulator S for noiseless quantum protocols of length N with the following properties. The simulator S is in the shared entanglement model,*

has length N' , communication rate $R_C \geq lC$, transmission alphabet of size 2, and entanglement consumption rate $R_E \leq 6$. Further, the simulation succeeds with error at most 2^{-cN} for all noiseless protocols of length N over any classical binary symmetric channel \mathcal{M} of capacity C .

We complement this with a lower bound for the communication rate. We exhibit a sequence of two-party quantum protocols of increasing length N in the noiseless model such that for all $C > 0$, any corresponding sequence of simulation protocols of length $o(\frac{1}{C}N)$ in the shared entanglement model with classical binary symmetric channels of capacity C fails at producing the final state with low error on some input. Moreover, the family of quantum protocols can be chosen as one that computes a distributed binary function. More precisely, we have the next theorem.

THEOREM 19. *There exists a sequence $\{\Pi_N\}_{N \in 2\mathbb{N}}$ of two-party quantum protocols such that for all $C > 0$, for any simulation protocol S in the shared entanglement model of length $N' \in o(N/C)$ with communication rate $R_C = \frac{N}{N'}$ and arbitrary entanglement consumption rate R_E , the simulation produces an error of at least $1 - o(1)$ over binary symmetric channels of capacity C .*

6.1.1. Discussion of Optimality. The above results show that in the regime where we use binary symmetric channels of classical capacity close to 0, we cannot do much better than what we achieve, up to a multiplicative constant on top of the $\frac{1}{C}$ dilation factor. If we want to perform better in that regime, we would have to use the specifics of the operations implemented by the noiseless protocol instead of using these operations as black-boxes, even if we are restricting to protocols computing binary functions. We could, however, hope to be able to get much better hidden constants, since we do not match the case of one-way communication in which the constant can be made arbitrarily close to $\frac{1}{2}$ as the quantum message size increases. Another regime of interest would be one for channels of capacity close to 1, in which our techniques dilate the length of the protocols by a large multiplicative constant even when the error rate is low. In the classical case, recent results of Kol and Raz [34] show how to obtain communication rates going to 1 as the capacity goes to 1.

6.1.2. Proof of Theorem 18. In Lemma 2 of Ref. [47], it is stated that, given a transmission alphabet Σ , there exists $d > 0$ and $\varepsilon \in (0, \frac{1}{90})$ such that given a binary symmetric channel \mathcal{M} of capacity C , there is a $p \in \mathbb{N}$, $p \leq d\frac{1}{C}$, an encoding function $\mathcal{E} : \Sigma \rightarrow \{0, 1\}^p$ and a decoding function $\mathcal{D} : \{0, 1\}^p \rightarrow \Sigma$ such that $\Pr[\mathcal{D}(\mathcal{M}(\mathcal{E}(e))) \neq e] \leq \varepsilon$ for all $e \in \Sigma$. We use this in conjunction with the result of Theorem 9 and the Chernoff bound to obtain the following result. Consider $\varepsilon < \frac{1}{80}$, Σ given by Lemma 3 for a tree code of arity 48 and distance parameter $\alpha = \frac{39}{40}$, the corresponding $d > 0$, and the length $N'' = 4(1 + \frac{1}{N})N$ of the basic simulation protocol over alphabet Σ for the length N of the noiseless protocol to be simulated. Given a binary symmetric channel of capacity C and the corresponding $p \in \mathbb{N}$, \mathcal{E} , and \mathcal{D} , if all the Σ transmissions in the basic simulation protocol are done by re-encoding over $\{0, 1\}^p$ with \mathcal{E} (and decoding with \mathcal{D}), then $N' = pN''$ is the length of the oblivious simulation protocol over the binary symmetric channel, and except with probability $2^{-\Omega(N'')}$, the error rate for transmission of Σ symbols is below $\frac{1}{80}$. By Theorem 9 the simulation succeeds.

6.1.3. Proof of Theorem 19. It is known that for a classical discrete memoryless channel such as the binary symmetric channel, entanglement assistance does not increase the classical capacity [8], and it is also known that allowing for classical feedback does not lead to an increase in the classical capacity. However, we might hope that allowing for both simultaneously might lead to improvements. This is not

the case: classical feedback augmented by shared entanglement can be seen as equivalent to quantum feedback, and it is also known that for discrete memoryless quantum channels, the classical capacity with unlimited quantum feedback is equal to that with unlimited entanglement assistance [9]. Hence, in the shared entanglement model, the classical capacity of the binary symmetric channels used is not increased by the entanglement assistance and the other binary symmetric channel's feedback. For some protocols of length N fitting our general framework in the noiseless model, such as those accomplishing a quantum swap function or even a classical swap or bitwise XOR functions on inputs of size $\frac{N}{2}$, the parties effectively exchange their entire inputs to produce the correct output. Hence, a dilation factor proportional to the inverse of the capacity $\frac{1}{C}$ is necessary. What we wish to prove is even stronger: there exists a family of distributed binary functions such that this is necessary. We consider the inner product function $\text{IP}_n : \{0, 1\}^n \times \{0, 1\}^n \rightarrow \{0, 1\}$, defined as $\text{IP}_n(x, y) = \bigoplus_{i=1}^n x_i \wedge y_i$, which has communication complexity in $\Theta(n)$ in both the Yao and the Cleve–Buhrman quantum communication complexity model [19, 40].

By a reduction due to Cleve, van Dam, Nielsen, and Tapp [19], any protocol evaluating the IP_n function with small error can be used to transmit n classical bits with small probability of error. Hence, any noise-tolerant simulation of such a protocol over a channel of classical capacity C can be used to transmit n -bit strings with some small probability of failure. As a consequence, for small enough error, the simulation requires at least $\frac{1}{C}n$ uses of the channel. Note that we have made the reasonable assumption that we can run the simulation backward over the noisy channel at the same communication cost or else that we can start with a coherent protocol for the inner product function. The restriction of having protocols compute a function in a coherent way is natural if we wish to compose quantum simulation protocols; then they may be run on arbitrary superpositions of inputs.

6.2. Quantum Model with Adversarial Errors. We turn our attention to two-party protocols where there is no prior entanglement and the communication is over noisy *quantum* channels. Given an adversarial channel in the quantum model with error rate strictly smaller than $\frac{1}{6}$, we can simulate any noiseless protocol of length N over this channel using a number of transmissions linear in N . More precisely, we show the following. (See [Appendix A.1](#) for the definition of $\mathcal{A}_{\frac{1}{6}-\varepsilon, q, N'}^{\text{Q}}$ mentioned in the theorem.)

THEOREM 20. *There exists a constant $c > 0$ such that for arbitrarily small $\varepsilon > 0$, there exist a communication rate $R_C > 0$ and an alphabet size $q \in \mathbb{N}$ such that for all $N \in 2\mathbb{N}$, there exists a universal simulator S for noiseless quantum protocols of length N with the following properties. The simulator S is in the quantum model, has length N' , communication rate at least R_C , and transmission alphabet size q . Further, the simulation succeeds with error at most 2^{-cN} for all noiseless protocols of length N against all adversaries in $\mathcal{A}_{\frac{1}{6}-\varepsilon, q, N'}^{\text{Q}}$.*

6.2.1. Proof of Theorem 20. The approach we take in the quantum model is to emulate the simulation in the shared entanglement model. First, we use the quantum channels available to distribute sufficient entanglement. Alice and Bob can use entanglement to generate a secret key. They then use the quantum channels effectively as classical channels along with the entanglement to run the simulation protocol from [section 5](#). Thus the simulation consists of an entanglement distribution phase, followed by a protocol implementation phase.

Specifically, suppose we wish to emulate a simulation protocol of length N' in the shared entanglement model. Alice uses lN' transmissions, for a parameter l to be specified below, to distribute sufficient perfect entanglement to Bob through the use of a quantum error correcting code (QECC). (We refer the reader to Ref. [41, Chapter 10] for the definition of a QECC.) They then run the simulation protocol in [section 5](#). During this protocol implementation phase, before transmission and after reception of a quantum register through the channel, both the sender and the receiver measure the register. These measurements have the effect of transforming all possible quantum actions of Eve into classical actions. Conditioned on the results of the two measurements, the corresponding branches of the simulation proceed exactly as if the sender and the receiver had transmitted and received information over a classical channel. If the size q of the communication register is larger than the alphabet size Γ of the transmissions, and Eve maps some of these classical messages outside of Γ , Alice and Bob mark these as erasures. So Eve does not gain anything by introducing errors outside Γ .

We start by pinning down the parameters of the QECCs needed to distribute the necessary amount of entanglement. In the interest of simplicity, we do not attempt to optimize the parameters involved.

For a given $\varepsilon > 0$, let $s = \frac{(\Gamma!)}{(\Gamma - |\Sigma|)!}$ be the size of the shared secret key used to do the blueberry encoding in each round of the simulation in [section 5](#). Two maximally entangled states of size $2s$, i.e., states of the form $\sum_{j=0}^{2s-1} |j\rangle^{T_A} |j\rangle^{T_B}$, are used to generate the secret keys and to create the EPR pairs required for teleportation in every round. For a given size q for the communication register, and for a simulation protocol in the shared entanglement model of length N' , we distribute a maximally entangled state over $N' \log_q(2s)$ registers of size q .

In the entanglement distribution phase of the simulation in the quantum model, we encode the $N' \log_q(2s)$ registers into lN' registers of size q . For the encoding, we use a quantum error correcting code with alphabet size q , transmission rate $R_Q \geq \frac{1}{l} \log_q(2s)$, and maximum tolerable error rate δ to be determined shortly. We only consider exact QECCs, but the analysis extends to approximate ones. (Approximate error correction allows for some deviation from perfect transmission.)

To determine the relationship between q, l , and δ required for the simulation to succeed, we first note that in the protocol implementation phase (the second phase of the simulation), we transmit classical messages chosen from a set of size $|\Gamma|$ over the quantum channel. For simplicity, we choose $q \geq |\Gamma|$. To ensure that this second phase succeeds, the number of corruptions in it should be bounded by $(\frac{1}{2} - \varepsilon)N'$. An adversary could choose to put all of the allowed corruptions in the first (entanglement distribution) phase, so the QECC should be able to recover from the same number of errors. In other words, we require $\delta lN' \geq \frac{N'}{2} - \varepsilon N'$. The length of the message in the entanglement distribution phase satisfies $l \geq \frac{1-2\varepsilon}{2\delta}$. In summary, the entire simulation tolerates $\frac{N'}{2} - \varepsilon N'$ adversarial errors during a total of $(l+1)N'$ transmissions of size q registers provided a suitable QECC exists. The error rate tolerated is $\frac{1-2\varepsilon}{2(l+1)}$.

The above analysis applies to the oblivious communication model. If we restrict ourselves to the alternating communication model, we have twice as much communication, i.e., $2lN'$ size- q registers, in the entanglement transmission phase. The adversary can choose to corrupt the transmissions of one party alone, so $l \geq \frac{1-2\varepsilon}{2\delta}$ as before. The total number of transmissions is, however, $(2l+1)N'$, so the error rate tolerated is $\frac{1-2\varepsilon}{2(2l+1)}$.

We now appeal to a high-dimensional quantum Gilbert–Varshamov bound [2, 24]

stating that for arbitrarily small $\varepsilon' > 0$, there exist strictly positive communication rate $R_Q > 0$ and large enough transmission alphabet size such that families of quantum codes of arbitrarily large length exist which can tolerate a fraction $\frac{1}{4} - \varepsilon'$ of errors and allow for perfect decoding of the quantum state. Using these codes with $\varepsilon' = \varepsilon$, we get $\delta = \frac{1}{4} - \varepsilon$, $l \geq \frac{1-2\varepsilon}{2\delta} = \frac{2(1-2\varepsilon)}{1-4\varepsilon}$ and net error rate $\frac{1-2\varepsilon}{2(2l+1)} = \frac{(1-2\varepsilon)(1-4\varepsilon)}{6-16\varepsilon} \geq \frac{1}{6} - \varepsilon$ that the simulation protocol can tolerate in an oblivious model of communication. In an alternating model of communication, we are able to tolerate an error rate of $\frac{1}{10} - \varepsilon$.

The above choice of parameters ensures that the error rate in the entanglement distribution phase is bounded by $\frac{1}{4} - \varepsilon$, and the received quantum state can be decoded perfectly. This establishes a shared maximally entangled state of the required dimension. Moreover, the corruption rate of the adversary during the protocol implementation phase is lower than $\frac{1}{2} - \varepsilon$. Recall that Alice and Bob measure the states received over the quantum channel in the standard basis to convert it to a classical channel. Given any strategy of the adversary, which is necessarily independent of the secret key used for the blueberry codes, for any choice of measurement outcomes for Alice and Bob, the simulation succeeds with probability exponentially close to 1 (in terms of N'). The remainder of the analysis follows that in [subsection 5.2.2](#), proving [Theorem 20](#).

6.2.2. Discussion of Optimality. If we consider only perfect QECCs for quantum data transmission, it is known that we cannot tolerate error rates of more than $\frac{1}{4}$ asymptotically. With the approach of first distributing entanglement and then using the $\frac{1}{2} - \varepsilon$ error rate simulation protocol in the shared entanglement model, we get an overall tolerable error rate for the simulation of less than $\frac{1}{6}$. Crépeau, Gottesman, and Smith [20] showed how we can tolerate an error rate up to $\frac{1}{2}$ asymptotically for data transmission if we consider approximate QECCs. Using these, we could get a tolerable error rate of $\frac{1}{4} - \varepsilon$ for a two phase simulation protocol as described above. However, their register size, as well as the number of communicated registers, is linear in the number of transmitted qubits in the original protocol. This would lead to a communication rate of 0 asymptotically in the simulation. It would be interesting to see whether we can do something similar with register size independent of the transmission size, but possibly dependent on the fidelity we want to reach and how close to $\frac{1}{2}$ (or some other fraction strictly larger than $\frac{1}{4}$) we would like the tolerable error rate to be. Using this kind of code, if we break up the simulation into two phases—an entanglement distribution part and then a protocol implementation part—the above is the best we can do. We might hope to develop a fully quantum analogue of tree codes that does not entail the two phase simulation, in order to achieve higher error rates. The putative quantum codes would require some properties for fault-tolerant computation, so that we may coherently apply the noiseless protocol unitary operations in the simulation. This issue does not occur in the fully classical setting, since we can copy classical information and perform the computation on the copy.

Finally, we note that the proof of [Theorem 13](#) applies here as well. It establishes a bound of $\frac{1}{2}$ on the maximum error rate tolerable in an oblivious communication model, that is, no simulation protocol in the quantum model can succeed with arbitrarily small error against all adversaries in $\mathcal{A}_{\frac{1}{2}, q, N'}^Q$ for any $q, N' \in \mathbb{N}$. (See [Appendix A.1](#) for the definition of $\mathcal{A}_{\frac{1}{2}, q, N'}^Q$.)

6.3. Quantum Model with Random Errors. We shift our focus to quantum communication over depolarizing channels. Given a two-party quantum protocol of

length N in the noiseless model and any $C_Q > 0$, we devise a simulation protocol in the quantum model that is of length $O(\frac{1}{C_Q}N)$ and succeeds in simulating the original protocol with arbitrarily small error over quantum depolarizing channels of quantum capacity C_Q . (We refer the reader to Ref. [54, Chapter 23] for the definition of quantum capacity C_Q .) More precisely, we state the following theorem.

THEOREM 21. *There exist a constant $l > 0$ and a function $f : \mathbb{N} \rightarrow \mathbb{R}^+$ with $\lim_{N \rightarrow \infty} f(N) = 0$ such that given any $C_Q > 0$ and $N \in 2\mathbb{N}$, there exists a universal simulator P for noiseless quantum protocols of length N with the following properties. The simulator P is in the quantum model, has length N' , communication rate $R_Q \geq lC_Q$, and transmission alphabet size 2. Further, the simulation succeeds with error at most $f(N)$ in simulating all noiseless protocols of length N over depolarizing channel \mathcal{M} of quantum capacity C_Q .*

We point out that quantum capacity with feedback is a lower bound on the dilation needed to simulate protocols over depolarizing channels. There exist a sequence of two-party quantum protocols of increasing length N in the noiseless model such that for all $C_Q^B > 0$, any corresponding sequence of simulation protocols of length $o(\frac{1}{C_Q^B}N)$ in the quantum model with quantum depolarizing channels of quantum capacity C_Q^B with classical feedback fails at producing the final state with low error on some input. (We refer the reader to Refs [5, 37] for definitions of quantum capacity with classical feedback C_Q^B and quantum capacity with free assistance by two-way classical communication C_Q^2 .) Moreover, the family of quantum protocols can be chosen as one computing a distributed binary function.

THEOREM 22. *There exists a sequence $\{\Pi_N\}_{N \in 2\mathbb{N}}$ of two-party quantum protocols such that for all $C_Q^B > 0$, for any simulation protocol P in the quantum model of length $N' \in o(N/C)$ with communication rate $R_Q = \frac{N}{N'}$, the simulation produces an error of at least $\Omega(1)$ over quantum depolarizing channels of quantum capacity C_Q^B with classical feedback.*

It turns out that quantum capacity does not capture the ability to transmit information in an interactive setting. Given a two-party quantum protocol of length N in the noiseless model, there exist a quantum depolarizing channel of unassisted forward quantum capacity $C_Q = 0$ and a simulation protocol in the quantum model with asymptotically positive rate of communication which succeeds in simulating the original protocol with arbitrarily small error over that quantum channel.

THEOREM 23. *There exist constants $c, R_Q > 0$ such that given any $N \in 2\mathbb{N}$, there exists a universal simulator P for noiseless quantum protocols of length N with the following properties. The simulator P is in the quantum model, has length N' , communication rate at least R_Q , and transmission alphabet size 2. Further, the simulation succeeds with error at most 2^{-cN} at simulating all noiseless protocols of length N over a particular depolarizing quantum channel \mathcal{M}_0 of forward quantum capacity $C_Q = 0$.*

6.3.1. Proof of Theorem 21. For the case of random error in the quantum model, we use techniques similar to the case of adversarial error. Indeed, we split the protocol into two phases: an entanglement distribution phase and a protocol implementation phase.

It suffices to adapt the result from [section 4](#) for a basic simulation protocol of length N'' over some large alphabet Σ . We then need only distribute N'' maximally entangled states of the appropriate size. For any depolarizing channel of quantum capacity $C_Q > 0$, we use standard coding results from quantum Shannon theory [54]

to distribute entanglement at a rate of $\frac{d}{C_Q}$ for some $d > 0$ with low error. Then, for the protocol implementation phase, we appeal to two properties. First, the classical capacity C of a quantum channel is at least as large as its quantum capacity. Second, a classical capacity achieving strategy for the depolarizing channel is to simulate a binary symmetric channel (BSC) of capacity C for each transmission by measuring the output in the computational basis, and then to block code over the corresponding BSC (see, e.g., Ref. [54] for details). We can then translate the proof of [Theorem 18](#) in order to design our classical strategy. This succeeds with overwhelming probability assuming perfect entanglement, and the output is arbitrarily close to the noiseless protocol output. Combining the bound on the error from the two phases, the simulation can be made to succeed with error less than $f(N)$ over the depolarizing channel of quantum capacity C_Q , for some function $f : \mathbb{N} \rightarrow \mathbb{R}^+$ which asymptotically goes to zero.

6.3.2. Proof of [Theorem 22](#). The idea for this proof is to use the fact that distributing an EPR pair over a quantum depolarizing channel produces a Werner state, which is symmetric under the interchange of Alice and Bob (see [subsection 6.4](#) for a definition of Werner states). Moreover, if Bob uses the free classical feedback to teleport to Alice with these Werner states, this creates a virtual depolarizing channel from him to Alice, with the same parameter as the actual channel from Alice to him. Hence, a quantum depolarizing channel from Alice to Bob along with free classical feedback is sufficient to simulate depolarizing channels in both directions, and the total number of uses of the depolarizing channel is the same in both cases.

Similar to what was argued in the proof of [Theorem 19](#) for classical communication, there exist protocols of length N that fit our general framework in the noiseless model and can be used to communicate up to $\frac{N}{2}$ qubits in each direction. Hence, since our simulation protocols of length N' can be simulated by N' uses of a depolarizing channel from Alice to Bob supplemented by classical feedback from Bob to Alice, we cannot have a rate of communication better than $\frac{N}{2C_Q}$ for small enough error.

To prove that a protocol to compute a binary function is sufficient, we once again consider the inner product function IP_n . We apply a coherent version of the idea to use the inner product protocol to communicate, as in the proof of [Theorem 19](#). This allows us to use the depolarizing channel to distribute quantum entanglement, and then also to teleport (again with the inner product protocol used this time to communicate classical information). For this, it is sufficient to note that what we achieved in the proof of [Theorem 19](#) using the protocol for IP_n is actually stronger than $\Theta(N)$ bits of classical communication: we had a coherent bit channel [29] for $\Theta(N)$ cobits (coherent bits), which can be used to distribute $\Theta(N)$ ebits (EPR pairs). Note that we once again make the reasonable assumption that we can run the simulation backward over the noisy channel at the same communication cost or that we can start with a coherent protocol for the inner product function.

6.3.3. Proof of [Theorem 23](#). The case of the depolarizing channel requires some technical work, so for simplicity we first consider the case of the quantum erasure channel. For the quantum erasure channel, we use the property that, for erasure probability $\frac{1}{2} \leq p < 1$, the (forward, unassisted) quantum capacity is 0 while both the classical capacity and the entanglement generation capacity with classical feedback equal $1-p$ [5]. Moreover, the feedback required to achieve this bound is only one message of length linear in the size of the quantum communication. The strategy we use is the following: for a basic simulation protocol of length N'' over Σ , Alice distributes

N'' EPR pairs to Bob by sending $\frac{4N''}{(1-p)}$ halves of such states over the quantum erasure channel. Then, except with negligible probability, at least N'' of them are received intact, and Bob knows which ones these are. The feedback consists of informing Alice which N'' pairs were received intact and can be used in the protocol. This can be done over the quantum erasure channel, with probability negligibly smaller than 1, with a classical message of length linear in N'' .

Then, given a message set Σ we can use the quantum erasure channel a constant number of times to decrease the probability of error in a classical transmission of any symbol $e \in \Sigma$ below $\frac{1}{90}$. Except with negligible probability, the fraction of N'' transmissions of symbols of Σ transmitted in this way is below $\frac{1}{80}$. We can then use a reasoning similar to that in the proof of [Theorem 20](#) to argue that the output is arbitrarily close to the noiseless protocol output.

Now for the depolarizing channel, the reasoning is mostly the same, but we have to work harder to obtain (almost) noiseless entanglement. The unassisted forward capacity of the depolarizing channel is shown in Ref. [6] to be equivalent to one-way entanglement distillation yield. To separate one-way and two-way entanglement distillation, they use a combination of the recurrence method of Ref. [4] along with their hashing method. The recurrence method is an explicitly two-way entanglement distillation protocol, which can purify highly noisy entanglement but does not have a positive yield in the limit of high fidelity distillation. The hashing method is a one-way protocol with positive yield in the perfect fidelity limit, but which does not work on highly noisy entanglement. We cannot hope to use this strategy to distill near-perfect EPR pairs in our scenario since the hashing method as they describe it requires too much communication. (We could probably use a derandomization argument to avoid communicating the random strings in this protocol.) To reduce the communication cost, we instead use a hybrid approach of entanglement distillation followed by quantum error correction.

Starting with a depolarizing channel with depolarizing parameter as high as possible, but still low enough to have $C_Q = 0$, we use it to distribute imperfect EPR pairs. This yields (rotated) Werner states with the highest possible fidelity to perfect EPR pairs, but such that one-way entanglement distillation protocols cannot have a positive yield of EPR pairs while two-way entanglement distillation protocols can. (See [subsection 6.4](#) for a definition of Werner states.) We then do one round of the recurrence method for entanglement distillation to obtain a lesser number of Werner states of higher fidelity to perfect EPR pairs, and so we could now use one-way distillation protocols on these to obtain a positive yield of near-perfect EPR pairs. The amount of classical communication required up to this point is one message from Alice to Bob of linear length informing him of her measurement outcomes, and then one classical message of linear length from Bob to Alice informing her which states to keep as well as which rotation to apply to these. (The rotation takes the states back to the symmetric Werner form; $\log 12$ bits of information per pair is sufficient for this purpose [6].) We now use these EPR pairs along with teleportation to effectively obtain a depolarizing channel of quantum capacity $C_Q > 0$. We use standard coding from quantum Shannon theory [54] over this quantum channel to distribute N'' near-perfect EPR pairs. This new step only requires a linear amount of classical communication. After the initial very noisy entanglement distribution step, we thus only have three classical messages to send over the depolarizing channel of classical capacity $C > 0$. We generate near-perfect entanglement using the depolarizing channel a linear number of times, and then go on to the protocol implementation phase

as before. Note that we are not yet guaranteed an exponential decay of the error at this point, but only that the error tends to zero in the limit of large N . To get exponential decay in error, we adapt the above protocol. Before using teleportation and QECCs to distribute near-perfect entanglement, we perform a few more rounds of the recurrence method until the Werner states reach fidelity parameter above 0.82. Except with negligible probability, starting with some linear number of noisy EPR pairs, after a constant number of rounds of the recurrence method, we are left with sufficiently many less noisy EPR pairs for our next step. At this point, it is known that there exist stabilizer codes achieving the hashing bound (which has strictly positive yield for this noise parameter) and which have negligible error. Using the property that some classical capacity achieving strategy for the depolarizing channel also has negligible error, we get the stated exponential decay in the error.

6.3.4. Discussion of Optimality. It is known that for some range of the depolarizing parameter, the quantum capacity C_Q^B with classical feedback of the depolarizing channel is strictly larger than its unassisted forward quantum capacity C_Q [6]. In particular, there exist values for which $C_Q = 0$ but $C_Q^B > 0$. A careful analysis of the related two-way entanglement distillation protocols (in particular their communication cost and their amount of interaction) reveals that there is some range of the depolarizing parameter for which we can achieve successful simulation even though $C_Q = 0$, by using the depolarizing channels in each direction to transmit classical information. This proves that the standard forward quantum capacity of the quantum channels used does not characterize their communication capacity in the interactive communication scenario. Note that $C_Q^B > 0$ if and only if the depolarizing parameter $\varepsilon' < \frac{2}{3}$, and so $C_Q^B > 0$ if and only if the quantum capacity assisted by two-way classical communication $C_Q^2 > 0$. In the case where we are given a depolarizing channel with $C_Q^B > 0$, we can modify the method used in the proof of [Theorem 23](#). We iteratively use the recurrence method a constant number of times on the noisy distributed EPR pairs, until the depolarizing channels induced through teleportation over the noisy distilled EPR pairs have non-zero forward quantum capacity. (Here the constant depends on the depolarizing parameter, but not on N .) Then we distribute entanglement over the induced channels using standard QECCs. We achieve asymptotically positive rates of communication for our simulation protocols. It is an interesting open question whether we can close the gap between our lower and upper bounds and always achieve successful simulation at a rate $O(\frac{1}{C_Q^B} N)$. The separation result regarding the forward, unassisted quantum capacity of the depolarizing channel requires some technical work, but the case of the erasure channel already makes it clear that in general for discrete memoryless quantum channels, the unassisted forward quantum capacity is not the most suitable quantity to consider in the setting of interactive quantum communication.

6.4. Noisy Entanglement. The last model we consider is a further variation on the shared entanglement model, in which, along with the noisy classical links between the honest parties, the entanglement these parties share is also noisy.

There are many possible models for noisy entanglement; we consider a simple one in this section, in which parties share noisy EPR pairs instead of perfect pairs. Following Ref. [4], we consider the so-called (rotated) Werner states $W_F = F|\Phi_{00}\rangle\langle\Phi_{00}| + \frac{1-F}{3}(|\Phi_{01}\rangle\langle\Phi_{01}| + |\Phi_{10}\rangle\langle\Phi_{10}| + |\Phi_{11}\rangle\langle\Phi_{11}|)$, which are mixtures of the four Bell states parametrized by $0 \leq F \leq 1$. Note that these are the result of passing one qubit of an EPR pair through a $\mathcal{T}_{\varepsilon'}$ depolarizing channel, for $F = 1 - \frac{3\varepsilon'}{4}$. The

purification of these noisy EPR pairs is given to Eve. We use the result of Ref. [4] to show that for any $F > \frac{1}{2}$, simulation protocols with asymptotically (in $N \rightarrow \infty$, not in $F \rightarrow \frac{1}{2}$) positive communication rates and which can tolerate a positive error rate can succeed with asymptotically zero error. This is optimal since at $F = \frac{1}{2}$, Werner states are separable, so there is no way to use them in conjunction with classical communication to simulate quantum communication.

6.4.1. Adversarial Errors in the Classical Channel. We first consider the case of adversarial errors. Let l_c be the number of rounds of the recurrence method [4] for entanglement distillation necessary to reach the $F = 0.82$ bound. This number is independent of N , and depends only on the initial value of the parameter F . As described in the proof of [Theorem 23](#), each round of the recurrence method only requires a linear length classical message in each direction. After this bound is reached, one last linear length classical message is sufficient to generate a linear amount of entanglement through teleportation via an induced depolarizing channel of non-zero quantum capacity C_Q . Standard quantum error correction techniques enable us to extract near-perfect entanglement at this point. Once we have near-perfect entanglement, we can use techniques from the basic simulation protocol to perform successful simulation of noiseless protocols and hence achieve our goal. The protocol sketched above requires the communication of $2l_c + 1$ messages to distill near-perfect entanglement, independent of N , followed by a phase of simulating the message transmissions from the original protocol. The simulation protocol tolerates a constant error rate, though inversely proportional to l_c . It requires a constant rate of noisy entanglement consumption, which is exponential in l_c since each round of the recurrence method consumes at least half of the noisy EPR pairs. The protocol has a constant, positive rate of communication, though inversely proportional to the number of consumed noisy EPR pairs.

6.4.2. Random Errors in the Classical Channel. The case of noisy communication through binary symmetric channels once again is immediate from the adversarial error case by a concentration of measure argument. The communication rate of the resulting protocol is inversely proportional to the classical capacity C , and also to the number of noisy EPR pairs consumed.

7. Conclusion: Discussion and Open Questions. In this work, we proposed a simulation of interactive quantum protocols intended for noiseless communication over noisy channels. Our approach is to replace irreversible measurements by reversible pseudo-measurements in the Cleve–Buhrman model, i.e., the model with shared entanglement and classical communication. Then, in the noisy version of the model, we teleport back and forth the corresponding quantum communication register to avoid losing quantum information. We develop a representation for such noisy quantum protocols that gives an analogue of Schulman’s protocol tree representation for classical protocols. We prove that with this approach, it is possible to simulate the evolution of quantum protocols designed for noiseless quantum channels over noisy classical channels with only a linear dilation factor.

In the case of adversarial channel errors in which the parties are allowed to pre-share a linear amount of entanglement, we prove that the error rate of $\frac{1}{2} - \varepsilon$ that our simulation tolerates is optimal unless we allow adaptive protocols. (An adaptive protocol is a generalization of the noisy communication model wherein the order in which the parties take turns speaking can be adapted to the errors.) In a noisy setting, restricting to non-adaptive (oblivious) protocols seems natural. Adaptive protocols

run the risk of entering a deadlock: depending on the particular view of each party of the evolution of the protocol due to previous errors, the parties could disagree on whose turn it is to speak. This would result in protocols that are not well defined.

To get the tolerable error rate as high as $\frac{1}{2} - \varepsilon$, we develop new techniques along with a new bound on tree codes with an erasure symbol, [Lemma 16](#). To simplify the exposition, we chose not to optimize the parameters in our simulation protocol such as communication and entanglement consumption rates, or the size of the communication register.

We adapt our findings to a random error model in which parties are allowed to share entanglement but communicate over binary symmetric channels of non-zero capacity C . We obtain communication rates proportional to C . We show that, up to a hidden constant, this is optimal for some family of distributed binary functions, for example the inner product functions $\text{IP}_n : \{0, 1\}^n \times \{0, 1\}^n \rightarrow \{0, 1\}$, defined as $\text{IP}_n(x, y) = \bigoplus_{i=1}^n x_i \cdot y_i$. Our findings can also be adapted to obtain similar (though not optimal) results for the quantum model (the noisy version of Yao’s model). Here, the simulation protocols run in two phases. In the first, a preprocessing phase, a linear amount of entanglement is distributed with standard techniques from quantum Shannon theory for random noise and from quantum coding theory for adversarial noise. This is followed by a simulation phase in which the actions of the parties parallel those in the shared entanglement model. In the case of adversarial noise, we show that we can tolerate an error rate of $\frac{1}{6} - \varepsilon$ in the quantum model. In the case of random noise in which the parties communicate over depolarizing channels of capacity $C_Q > 0$, we obtain rates proportional to C_Q . Perhaps surprisingly, we show that the use of depolarizing channels in both directions enables the simulation to succeed even for some quantum channels of unassisted forward quantum capacity $C_Q = 0$. This proves that Q does not characterize a quantum channel’s capacity for interactive quantum communication. We extend our ideas to perform simulation in an extension of the shared entanglement model in which not only the classical communication is noisy but also the entanglement.

A direction of research that immediately grows out of this work is characterizing the communication rates in all of the models discussed. In particular, the precise interactive capacity of the depolarizing channel with a specified noise parameter remains open. The question of interactive capacity for the binary symmetric channel was raised in the classical context by Schulman [\[47\]](#) and brought to attention recently by Braverman in a survey article on the topic of interactive coding [\[13\]](#). Recent developments provide tight lower and upper bounds for this quantity [\[34\]](#). In the classical setting, a particular problem with worst-case interaction of one-bit transmissions to which all classical interactive protocols can be mapped was proposed for the study of such a quantity. Since every interactive quantum protocol can be mapped onto our general problem, it would be natural to study such a quantity in the quantum domain. Would the interactive capacity of the binary symmetric channel (with entanglement assistance) for quantum protocols be the same as that for classical protocols [\[34\]](#), up to a factor of 2 for teleportation? Do the techniques developed in Ref. [\[34\]](#) adapt to the quantum setting to obtain an upper bound of $\frac{1}{2} - \Omega(\sqrt{H(\varepsilon)})$? What about the depolarizing channel and other channels?

Another question that remains open is finding the highest adversarial error rate that can be withstood in the quantum model. To study this question, it is likely that a “fully quantum” approach with new kinds of quantum codes is needed. In particular, ideas from fault-tolerant quantum computation might be necessary. Furthermore, the important question of integrating our results into a larger fault-tolerant

framework, in which the local operations are also noisy, remains open. Yet another important question for interactive quantum coding is what would happen in a shared entanglement setting if, along with the noisy classical communication, the entanglement provided were also noisy; we investigated this question for a depolarizing noise model for the entanglement, but other models would also be interesting to study, in particular, adversarial noise on the shared EPR pairs above the unidirectional binary error rate limit. Note that below that bound, standard quantum error correction for qubits with teleportation can be used for distillation. Finally, the question of computationally efficient simulation also remains open.

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Appendix A. Formal Definitions for Noisy Communication Model.

A.1. Quantum Model. For the *quantum model*, Alice possesses a local quantum register A' which contains five subsystems of interest: to implement a noiseless protocol Π as a black-box, the A and C_A parts correspond to the registers of the noiseless communication protocol, while \tilde{A} and \tilde{C}_A are the corresponding registers defined by the noiseless protocol embedding, and A'' is some scratch register used for her local quantum computation in the simulation. Similarly, Bob possesses a local quantum register B' which contains four subsystems of interest: to implement Π as a black-box, the B and C_B parts correspond to the registers of the noiseless communication protocol, while \tilde{B} is the corresponding register defined by the noiseless protocol embedding, and B'' is some scratch register used for his local quantum computation in the simulation. Eve possesses a local quantum register E' which contains two subsystems of interest: the E part corresponds to her input register of the noiseless communication protocol and E'' is some scratch register used for her local quantum computation in the simulation. The input registers $ABC_A E$ are purified by a reference register R , which remains untouched throughout. A quantum communication register C' , of some fixed size q independent of the length N of the protocol to be simulated, is exchanged back and forth between Alice and Bob, passing through Eve; it is held by Alice at both the beginning and the end of the simulation protocol. A simulation protocol Q in the quantum model of length N' is defined by a sequence of quantum instruments $\mathcal{M}_1^{A'C'}$, $\mathcal{M}_2^{B'C'}$, \dots , $\mathcal{M}_{N'+1}^{A'C'}$ such that, on state $|\psi'_{\text{init}}\rangle^{A'B'C'E'R} = |\psi_{\text{init}}\rangle^{ABC_A ER} \otimes |0\rangle$ as input, given black-box access to a noiseless protocol Π (Π is assumed to be known to everyone) and against an adversary \mathcal{A} defined by a sequence of quantum instruments $\mathcal{N}_1^{E'C'}$, \dots , $\mathcal{N}_{N'}^{E'C'}$, the protocol outputs the $\tilde{A}\tilde{B}\tilde{C}$ subsystems of

$$(13) \quad \rho_{\text{final}} = \mathcal{M}_{N'+1}^{\Pi} \mathcal{N}_{N'} \mathcal{M}_{N'}^{\Pi} \cdots \mathcal{M}_2^{\Pi} \mathcal{N}_1 \mathcal{M}_1^{\Pi} (|\psi'_{\text{init}}\rangle \langle \psi'_{\text{init}}|).$$

(Here, the superscript Π emphasizes the black-box access to the protocol.) We denote the state of the output registers $\tilde{A}\tilde{B}\tilde{C}$ by $Q^{\Pi}(\mathcal{A}(|\psi_{\text{init}}\rangle))$, and the induced quantum channel from $ABCE$ to $\tilde{A}\tilde{B}\tilde{C} \cong ABC$ by $Q^{\Pi}(\mathcal{A})$. The success of the simulation is measured by how close the simulation output state is to the final state of the noiseless protocol on the ABC registers, and is captured by the following definition.

DEFINITION 24. *A simulation protocol Q in the quantum model of length N' succeeds with error ε at simulating all length N noiseless protocols against all adversaries in some class \mathcal{A} if, for all noiseless protocols Π of length N , for all adversaries $\mathcal{A} \in \mathcal{A}$, $\|\Pi - Q^{\Pi}(\mathcal{A})\|_{\diamond} \leq \varepsilon$. The communication rate R_Q of Q is $R_Q = \frac{N}{N' \log q}$ for $q \geq 2$ the alphabet size of the communication register C' .*

Note that the adversary only has to make the simulation fail on some particular protocol, and on some particular input, to characterize the simulation protocol as ineffective against her.

In a random error model (analogous to that studied in quantum information theory à la Shannon), Eve is a non-malicious passive environment, and $\mathcal{N}_i = \mathcal{N}^Q$ for some fixed quantum channel \mathcal{N}^Q , and the class \mathcal{A} contains a single element $\mathcal{N}^{C' \otimes N'}$ (with trivial Z, E' registers). For simplicity, we then say that the simulation succeeds over \mathcal{N}^Q . In an adversarial error model (analogous to that studied in quantum coding theory, à la Hamming), Eve is a malicious adversary who wants to make the protocol fail, and we are interested in particular classes of adversaries which we denote by $\mathcal{A}_{\delta, q, N'}^Q$ for some parameter δ such that $0 \leq \delta \leq 1$. The class $\mathcal{A}_{\delta, q, N'}^Q$ contains all adversaries with a bound δ on the fraction of communications of the C' register they corrupt, in the following sense. Here, $\mathcal{F}_{q', 1}, \mathcal{E}_{\delta, q, N'}$ are defined in Eqs. (2) and (3), respectively.

DEFINITION 25. *The class $\mathcal{A}_{\delta, q, N'}^Q$ of adversaries in the quantum model with error rate bounded by δ , $0 \leq \delta \leq 1$, contains adversaries of the following kind: each adversary is specified by a sequence of instruments $\mathcal{N}_1^{E' C'_1}, \dots, \mathcal{N}_{N'}^{E' C'_{N'}}$ with arbitrary local quantum register E' of dimension $q' \in \mathbb{N}$. All of these adversaries act on a quantum communication register C' of dimension $q \in \mathbb{N}$, and on protocols of length $N' \in \mathbb{N}$. For any $\rho \in \mathcal{D}(E' \otimes C'^{\otimes N'})$, the action of such an adversary is*

$$\mathcal{N}_{N'}^{E' C'_{N'}} \dots \mathcal{N}_1^{E' C'_1}(\rho) = \sum_i G_i \rho G_i^\dagger,$$

for i ranging over some finite set and with each G_i of the form

$$G_i = \sum_{H \in \mathcal{E}_{\delta, q, N'}, F \in \mathcal{F}_{q', 1}} \alpha_{H, F, i} F^{E'} \otimes H^{C'^{\otimes N'}},$$

which is also subject to the requirement that $\sum_i G_i^\dagger G_i = I^{E' C'^{\otimes N'}}$.

This adapts to an interactive communication model the formal definition of adversarial channel given in Ref. [38] in a unidirectional communication model. Note that this allows for adaptive, probabilistic, entangled strategies for Eve, but such that any Kraus operator G_{i, z, z_0} is a linear combination of operators which act on at most a δ fraction of the C' registers non-trivially. We therefore say that the fraction of errors is bounded by δ for all adversaries in $\mathcal{A}_{\delta, q, N'}^Q$.

A.2. Shared Entanglement Model. For the *shared entanglement model*, Alice, Bob and Eve possess local classical-quantum registers split analogously to those in the quantum model. In addition to the entanglement inherent in $|\psi_{\text{init}}\rangle^{ABCE R}$, Alice and Bob also share entanglement to be consumed during the simulation in the form of a large state $|\phi\rangle^{T_A T_B}$ with the registers T_A, T_B held by Alice and Bob, respectively. In general, the entanglement registers have a product decomposition $T_A = T_A^1 \otimes \dots \otimes T_A^{N'}, T_B = T_B^1 \otimes \dots \otimes T_B^{N'}$. A classical communication register C'' , of some fixed size q independent of the length N of the protocol to be simulated, is exchanged back and forth between Alice and Bob, passing through Eve; it is held by Alice at both the beginning and the end of the simulation protocol. A simulation protocol S in the shared entanglement model of length N' is defined by a sequence of quantum instruments $\mathcal{M}_1^{A' T_A C''}, \mathcal{M}_2^{B' T_B C''}, \dots, \mathcal{M}_{N'+1}^{A' T_A C''}$ such that, with state

$|\psi'_{\text{init}}\rangle^{A'B'C''E'R} = |\psi_{\text{init}}\rangle^{ABCAER} \otimes |0\rangle$ as input, given black-box access to a noiseless protocol Π , and against an adversary \mathcal{A} defined by a sequence of quantum instruments $\mathcal{N}_1^{E'C''}, \dots, \mathcal{N}_{N'}^{E'C''}$, the protocol outputs the $\tilde{A}\tilde{B}\tilde{C}$ subsystems of the state ρ_{final} given by

$$(14) \quad \rho_{\text{final}} = \mathcal{M}_{N'+1}^{\Pi} \mathcal{N}_{N'} \mathcal{M}_{N'}^{\Pi} \cdots \mathcal{M}_2^{\Pi} \mathcal{N}_1 \mathcal{M}_1^{\Pi} (|\psi'_{\text{init}}\rangle\langle\psi'_{\text{init}}|).$$

(Again, the superscript Π emphasizes the black-box access to the protocol by the simulator.) We denote the state of the output registers $\tilde{A}\tilde{B}\tilde{C}$ by $S^{\Pi}(\mathcal{A}(|\psi_{\text{init}}\rangle))$, and the induced quantum channel from $ABCE$ to $\tilde{A}\tilde{B}\tilde{C} \cong ABC$ by $S^{\Pi}(\mathcal{A})$. The success of the simulation is measured by how close the simulation output state is to the final state of the noiseless protocol on the ABC registers, and is captured by the following definition:

DEFINITION 26. *A length N' simulation protocol S in the shared entanglement model of succeeds with error ε at simulating all length N noiseless protocols against all adversaries in some class \mathcal{A} if, for all noiseless protocols Π of length N , for all adversaries $\mathcal{A} \in \mathcal{A}$, $\|\Pi - S^{\Pi}(\mathcal{A})\|_{\diamond} \leq \varepsilon$. The communication rate R_C of S is $R_C = \frac{N}{N' \log q}$ for $q \geq 2$, the alphabet size of the classical communication register C'' , and the entanglement consumption rate R_E is $R_E = \frac{\log(\max(\dim T_A, \dim T_B))}{N'}$ for T_A, T_B the entanglement registers used for the simulation by Alice and Bob, respectively.*

In a random error model, Eve is a non-malicious passive environment, $\mathcal{N}_i = \mathcal{N}^S$ for some fixed classical channel \mathcal{N}^S , and the class \mathcal{A} contains a single element $\mathcal{N}^{C'' \otimes N'}$ (with trivial Z, E' registers). For simplicity, we then say that the simulation succeeds over \mathcal{N}^S . In an adversarial error model, Eve is a malicious adversary who wants to make the protocol fail, and we are interested in particular classes of adversaries, which we denote by $\mathcal{A}_{\delta, q, N'}^S$ for some parameter $0 \leq \delta \leq 1$. The class $\mathcal{A}_{\delta, q, N'}^S$ contains all adversaries with a bound δ on the fraction of communications of the C'' register they corrupt, in the following sense. Here, for two strings c, c_0 over a finite alphabet, Δ is the Hamming distance function counting the number of positions in which c, c_0 differ; see [subsection 3.4.2](#) for a formal definition.

DEFINITION 27. *The class $\mathcal{A}_{\delta, q, N'}^S$ of adversaries with error rate bounded by δ , $0 \leq \delta \leq 1$, in the shared entanglement model contains adversaries of the following kind: each adversary is specified by instruments $\mathcal{N}_1^{E'C''}, \dots, \mathcal{N}_{N'}^{E'C''}$ with arbitrary local quantum register E' of dimension $q' \in \mathbb{N}$. All these instruments act on a classical communication register C'' of dimension $q \in \mathbb{N}$, and on protocols of length $N' \in \mathbb{N}$. For any $\rho \in \mathcal{D}(E' \otimes C''^{\otimes N'})$, the action of such an adversary is*

$$\mathcal{N}_{N'}^{E'C''} \cdots \mathcal{N}_1^{E'C''}(\rho) = \sum_{c, c_0} G_{c, c_0} \rho G_{c, c_0}^{\dagger},$$

for $c, c_0 \in \{0, 1, \dots, q-1\}^{N'}$ satisfying $\Delta(c, c_0) \leq \delta N'$ and with each G_{c, c_0} of the form

$$G_{c, c_0} = \sum_{F \in \mathcal{F}_{q', 1}} \alpha_{F, c, c_0} F^{E'} \otimes |c\rangle\langle c_0|^{C'' \otimes N'},$$

also subject to the requirement that for any $c_0 \in \{0, 1, \dots, q-1\}^{N'}$,

$$\sum_c G_{c, c_0}^{\dagger} G_{c, c_0} = I^{E'} \otimes |c_0\rangle\langle c_0|^{C'' \otimes N'}.$$

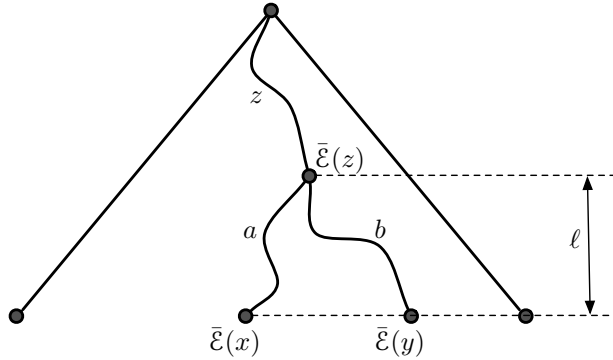


FIG. 2. Depiction of paths $x = za$ and $y = zb$ in a tree with divergence of length ℓ , along with the encodings $\bar{\mathcal{E}}(x)$, $\bar{\mathcal{E}}(y)$, and $\bar{\mathcal{E}}(z)$ of these strings.

Note that this allows for adaptive, probabilistic strategies for Eve, but such that conditioned on any final transcript c and input transcript c_0 on the communication register, at most a δ fraction of the actions of Eve have acted non-trivially on the C'' register, even though she can copy all classical transmissions in the E' registers. We therefore say that the fraction of error is bounded by δ for all adversaries in $\mathcal{A}_{\delta, q, N'}^S$.

Note that the adversaries in the quantum and the shared entanglement models are fundamentally different: in the shared entanglement model, Eve can copy all classical messages without inducing any error and gather the corresponding information to establish her strategy, but she cannot modify Alice's or Bob's quantum information, except for what is possible by corrupting their classical communication and by using the information in the quantum register E purifying the input state. In contrast, in the quantum model, she cannot always "read" the quantum messages, but she can apply entangled, fully quantum corruptions to the quantum register when she chooses to.

Appendix B. Tree Code Figure.

Figure 2 depicts two paths $x = za$ and $y = zb$ in a tree with divergence of length ℓ , along with the encodings $\bar{\mathcal{E}}(x)$, $\bar{\mathcal{E}}(y)$, and $\bar{\mathcal{E}}(z)$ of the strings x , y , and z . Let $a = a_1 a_2 \dots a_\ell$ and $b = b_1 b_2 \dots b_\ell$; then the tree code encoding of x and y are $\bar{\mathcal{E}}(x) = \bar{\mathcal{E}}(z) \circ \bar{\mathcal{E}}(a|z)$ and $\bar{\mathcal{E}}(y) = \bar{\mathcal{E}}(z) \circ \bar{\mathcal{E}}(b|z)$, in which \circ is the concatenation operator for strings, $\bar{\mathcal{E}}(a|z) = \mathcal{E}(za_1) \mathcal{E}(za_1 a_2) \dots \mathcal{E}(za)$ and $\bar{\mathcal{E}}(b|z) = \mathcal{E}(zb_1) \mathcal{E}(zb_1 b_2) \dots \mathcal{E}(zb)$.

The main property of the tree code is : $\Delta(\bar{\mathcal{E}}(x), \bar{\mathcal{E}}(y)) = \Delta(\bar{\mathcal{E}}(a|z), \bar{\mathcal{E}}(b|z)) \geq \alpha \cdot \ell$; i.e., the suffixes of the codewords are at distance at least $\alpha \ell$.

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