## 1 Smooth curves

**1.1 Definition.** Let *C* be an affine plane curve in  $\mathbb{A}^2$  given by  $f \in \Bbbk[x, y]$  and let  $p = (a, b) \in C$ . Then *p* is said to be a *smooth point* (or *simple point*) of *C* if  $\nabla f(a, b) \neq (0, 0)$ . A point that is not smooth is called a *singular point* (or *multiple point*). A curve that is smooth at every point is called a *smooth curve* (or *non-singular curve*). A point *p* of *C* is smooth if and only if there exists a unique normal vector to *C* at *p*. The *tangent line* to *C* at *p* is given by the equation  $\nabla f(a, b) \cdot (x - a, y - b) = 0$ .

## 1.2 Examples.

- (i) The parabola  $V(y x^2)$  is non-singular since its gradient is (-2x, 1), which is never (0, 0).
- (ii) The cusp  $V(y^2 x^3)$  has a singular point at (0,0) since its gradient is  $(-3x^2, 2y)$  which is (0,0) at (0,0).
- (iii) The alpha curve  $V(y^2 x^3 x^2)$  has a singular point at (0,0).

**1.3 Definition.** The *Zariski tangent space* to *C* at p = (a, b) is

$$T_{\mathcal{P}}(C) = \{ v \in \mathbb{A}^2 \mid \nabla f(a, b) \cdot v = 0 \}.$$

Therefore,  $\dim_{\Bbbk}(T_p(C)) = 1$  if and only if p is a smooth point of C and  $T_p = \mathbb{A}^2$  if and only if p is singular. Clearly,  $T_p(C)$  is a  $\Bbbk$ -vector space. The  $\Bbbk$ -vector space dual  $(T_p(C))^*$  is called the *Zariski cotangent space* of C at p. Note that  $(T_p(C))^*$  is considered as a subspace of  $(\mathbb{A}^2)^*$ , whose elements are  $1 \times 2$  matrices. Recall the differential map  $d_p : \Bbbk[x, y] \to (\mathbb{A}^2)^*$  defined by

$$d_p g = \begin{bmatrix} \frac{\partial g}{\partial x}(p) & \frac{\partial g}{\partial y}(p) \end{bmatrix} = \text{Jac}(g)(p)$$

Without loss of generality, we can assume that p = (0, 0), as all notions under discussion are invariant under translations. Then, if *C* is given by  $f \in k[x, y]$ ,  $T_p(C) = \ker(d_p f)$ . We can also define a differential map on  $M_p(C)$ .

**1.4 Definition.** Let *C* be an affine plane curve. If  $p \in C$ , the map  $d_p : M_p(C) \rightarrow (T_p(C))^*$  defined by

$$\mathbf{d}_p \, \frac{\overline{a}}{\overline{b}} = \frac{\mathbf{d}_p \, a}{b(p)} \Big|_{\mathbf{T}_p(C)}$$

is called the *differential map at p*. Moreover, given  $g \in M_p(C)$ ,  $d_p g$  is the *differential of g at p*.

**1.5 Proposition.** Let *C* be an affine plane curve. If  $p \in C$ , the differential map  $d_p : M_p(C) \to (T_p(C))^*$  is a well-defined surjective linear map whose kernel is  $M_p^2(C)$ .

PROOF: As usual, without loss of generality we can assume that p = (0,0), as all notions under discussion are invariant under translations. Let  $f \in \Bbbk[x, y]$  be such that C = V(f). Suppose  $g \in M_p(C)$  is such that  $g = \overline{a}/\overline{b} = \overline{c}/\overline{d}$ , where  $\overline{a}, \overline{b}, \overline{c}, \overline{d} \in \Bbbk[C]$  are such that a(p) = c(p) = 0 and  $b(p), d(p) \neq 0$ . Then  $\overline{ad} - \overline{cb} = 0$ , so ad - cb = hf for some  $h \in \Bbbk[x, y]$ . Thus,

$$\mathbf{d}_p(ad-cb) = \mathbf{d}_p(hf).$$

Expanding both sides of this equation gives

 $a(p) \operatorname{d}_p d + d(p) \operatorname{d}_p a - c(p) \operatorname{d}_p b - b(p) \operatorname{d}_p c = h(p) \operatorname{d}_p f + f(p) \operatorname{d}_p h.$ 

But a(p) = c(p) = f(p) = 0, so

$$d(p) \operatorname{d}_p a - b(p) \operatorname{d}_p c = h(p) \operatorname{d}_p f.$$

Since  $d_p f|_{T_p(C)} = 0$ ,

$$d(p) \operatorname{d}_p a - b(p) \operatorname{d}_p c|_{\operatorname{T}_p(C)} = 0,$$

i.e.

$$\frac{\mathrm{d}_p a}{b(p)}\Big|_{\mathrm{T}_p(C)} = \frac{\mathrm{d}_p c}{d(p)}\Big|_{\mathrm{T}_p(C)}.$$

Therefore,  $d_p : M_p(C) \to (T_p(C))^*$  is well-defined. Clearly,  $d_p$  is linear. If  $\varphi \in (T_p(C))^*$ , then  $\varphi$  is the restriction to  $T_p(C)$  of some linear function f on  $\mathbb{A}^2$ , so  $d_p f = \varphi$ . Let  $M = \langle x, y \rangle$ . Let  $\delta : \Bbbk[x, y] \to (\mathbb{A}^2)$  be the map

$$\delta(h) = \mathrm{d}_p(h)|_{\mathrm{T}_p(C)}.$$

Then, it is easy to see that  $\ker(\delta|_M) = M^2$ . Since  $M_p(C) = \overline{M}\mathcal{O}_p(C)$ ,

$$\ker(\mathbf{d}_p) = \overline{M}^2 \mathcal{O}_p(C) = \mathrm{M}_p^2(C).$$

**1.6 Corollary.** Let *C* be an affine plane curve. Then  $M_p(C)/(M_p(C))^2 \cong (T_p(C))^*$ .

PROOF: This is immediate from the previous proposition and the First Isomorphism Theorem.  $\hfill \Box$ 

## 1.7 Examples.

- (i) Let *C* be the parabola  $V(y x^2)$ . *C* is smooth at every point and  $\Bbbk[C] = \&[t]$ . At p = (0, 0),  $M_p(C) = \langle x \rangle$  and  $M_p(C)/(M_p(C))^2 = \{\lambda x \mid \lambda \in \Bbbk\}$ .
- (ii) Let *C* be  $V(y^2 x^3)$ , which is singular at the origin p = (0,0). Here  $k[C] = k[x, y]/(y^2 x^3)$  and  $M_p(C) = \langle \overline{x}, \overline{y} \rangle \subseteq k(C)$ . We have

$$(\mathbf{M}_p(C))^2 = \langle \overline{x}^2, \overline{xy}, \overline{y}^2 \rangle = \langle \overline{x}^2, \overline{xy} \rangle,$$

so  $M_p(C)/(M_p(C))^2 = \{a\overline{x} + b\overline{y} \mid a, b \in \Bbbk\}$ . Since this has dimension two, we know that p is a singular point.

**1.8 Proposition.** Let *C* be an affine plane curve given by  $f \in k[x, y]$ . Then  $p \in C$  is a smooth point of *C* if and only if  $M_p(C)$  is principal. In this case,  $M_p(C) = \langle t \rangle$ , where V(t) is any line through *p* that is not  $T_p(C)$ .

**PROOF:** Suppose that *C* is smooth at *p*. By making an appropriate affine transformation, we may assume that p = (0,0) and that the tangent line at *p* is y = 0. We will show that  $M_p$  is generated by  $\overline{x}$ ; the proof that *M* is generated by any line that is not the tangent line is similar. By the above assumptions f(0,0) = 0, so it has no constant term. That the tangent line at (0,0) is y = 0 implies that *f* has no linear term in *x*. Therefore

$$f(x, y) = y +$$
higher order terms.

Grouping the terms with y, we get  $f = yg - x^2h$ , where g is a unit in  $\mathcal{O}_p(C)$  and  $h \in k[x]$ . Taking residue classes, we get that

$$0 = \overline{f} = \overline{y}\overline{g} - \overline{x}^2\overline{h},$$

so  $\overline{y} = \overline{g}^{-1}\overline{h}\overline{x}^2$ . Therefore  $\overline{y} \in \langle \overline{x} \rangle$ , so  $M_p = \langle \overline{x}, \overline{y} \rangle = \langle \overline{x} \rangle$  is principal.

Conversely, if the maximal ideal is principal, say  $M_p = \langle t \rangle$ , then  $M_p^2 = \langle t^2 \rangle$  and  $M_p / M_p^2 = \{at \mid a \in k\}$ , a one dimensional k-vector space. This implies that *C* is smooth at *p* by Corollary 1.6 and the remark after the definition of the tangent space.

**1.9 Corollary.** Let *C* be an affine plane curve. Then  $p \in C$  is a smooth point of *C* if and only if  $\mathcal{O}_p(C)$  is a DVR.

**PROOF:** This follows from the preceding proposition and the fact that  $\mathcal{O}_p(C)$  is a Noetherian local ring.

**1.10 Corollary.** *Let C be an affine plane curve. Then C is smooth everywhere if and only if* k[C] *is a Dedekind domain.* 

PROOF: This follows from the preceding corollary and the characterization of Dedekind domains as the one-dimensional integral domains whose localizations at all maximal ideals are DVRs.  $\hfill \Box$