

Definition:

Let $\Lambda = \sum_x p_x |x\rangle\langle x|_X \otimes \rho_{xQ}$.

\mathcal{M} measurement on Q with output space Y

The accessible information for ensemble $\mathcal{E} = \{p_x, \rho_{xQ}\}$ is

$$I_{\text{acc}}(\mathcal{E}) := \max_{\mathcal{M}} I(X:Y)_{\mathcal{I} \otimes \mathcal{M}(\Lambda)}$$

Example 1. $x = 0, 1, p(0) = p(1) = 1/2,$

$$\rho_x = |\psi_x\rangle\langle\psi_x|, \quad |\psi_0\rangle = a|0\rangle + b|1\rangle$$

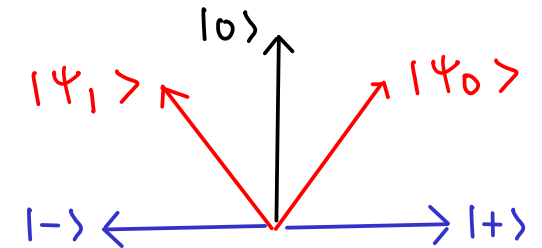
$$|\psi_1\rangle = a|0\rangle - b|1\rangle$$

$a, b \geq 0, a^2 + b^2 = 1$
 (most general form of
 2 arbitrary pure states)

Optimal measurement:

projective, along basis $\{|+\rangle, |-\rangle\}$

Levitin 95, or Fuchs PhD thesis 96 (Ch3.5)



$$p(x=0 | y=+) = p(x=0) p(y=+ | x=0)$$

$$\frac{1}{2} \text{tr} |+\rangle\langle+| \psi_0 \psi_0 \langle\psi_0| = \left(\frac{a}{\sqrt{2}} + \frac{b}{\sqrt{2}}\right)^2 = \frac{1}{2}(a^2 + b^2 + 2ab) = \frac{1}{2} + ab$$

$$p(x=1 | y=+) = \frac{1}{2}(\frac{1}{2} - ab)$$

$$p(y=+) = 1/2,$$

$$p(x=0 | y=+) = 1/2 + ab$$

$$p(x=1 | y=+) = 1/2 - ab$$

$$H(X | y=+) = h(1/2 + ab)$$

Similarly,

$$p(y=-) = 1/2,$$

$$H(X | y=-) = h(1/2 - ab) = h(1/2 + ab)$$

$$\therefore H(X|Y) = p(y=+) H(X|y=+) + p(y=-) H(X|y=-) = h(1/2 + ab)$$

$$I_{acc} = I(X:Y) = H(X) - H(X|Y) = 1 - h(1/2 + ab)$$

How to optimize measurement for lacc?

1. Unknown for most ensembles

For the few ensembles (highly symmetric) with known optimal measurements, there is no simple proof of optimality :(

How to optimize measurement for lacc?

2. EB Davies, IEEE Trans Info Th, 24, p596, 1978

For any ensemble of states in d dimensions, $\mathcal{E} = \{\rho_x, p_x\}$
optimal measurement has POVM $\mathcal{M} = \{M_y\}_{y=1}^n$ with

(a) $\text{rank}(M_y) = 1$ and

(b) $d \leq n \leq d^2$

Proof (a): If $M_y = \sum_k M_{y,k}$ is a decomp into rank 1 matrices

replace measurement \mathcal{M} with POVM $\{M_y\}$

by new measurement \mathcal{M}' with POVM $\{M_{y,k}\}$. outcome has 2 parts

$$\text{eg } \mathcal{M}: M_0 = \frac{1}{2}|0\rangle\langle 0| + \frac{1}{3}|+\rangle\langle +| \quad (y=0)$$

$$M_1 = \frac{1}{5}|1\rangle\langle 1| + \frac{1}{2}|-\rangle\langle -| \quad (y=1)$$

$$M_2 = \frac{4}{5}|1\rangle\langle 1| + \frac{1}{6}|+\rangle\langle +| \quad (y=2)$$

$$\mathcal{M}': M_{0,0} = \frac{1}{2}|0\rangle\langle 0| \quad (y=0, k=0) \quad M_{0,1} = \frac{1}{3}|+\rangle\langle +| \quad (y=0, k=1)$$

$$M_{1,0} = \frac{1}{5}|1\rangle\langle 1| \quad (y=1, k=0) \quad M_{1,1} = \frac{1}{2}|-\rangle\langle -| \quad (y=1, k=1)$$

$$M_{2,0} = \frac{4}{5}|1\rangle\langle 1| \quad (y=2, k=0) \quad M_{2,1} = \frac{1}{6}|+\rangle\langle +| \quad (y=2, k=1)$$

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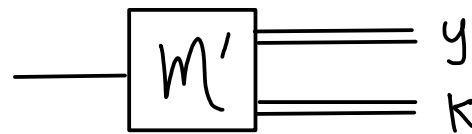
(a) $\text{rank}(M_y) = 1$ **and**

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if we discard k ,
 we perform \mathcal{M}

$$\therefore \text{lacc}(\mathcal{E}) \underset{\substack{\uparrow \\ \text{given} \\ \mathcal{M} \text{ optimal}}}{=} I(X:Y)_{\mathcal{I} \otimes \mathcal{M}(\Lambda)} = I(X:Y)_{\mathcal{I} \otimes \mathcal{M}'(\Lambda)} \left(\leq \right) I(X:YK)_{\mathcal{I} \otimes \mathcal{M}'(\Lambda)} \left(\leq \right) \text{lacc}$$

$\sum_x p_x |x\rangle\langle x| \otimes \rho_x$

q info proc-
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equal and \mathcal{M}'
 also optimal

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Proof (b): see e.g., Watrous book, or 1904.10985 Corollary 5.

Based on:

Caratheodory's Theorem:

Let $S \subseteq \mathbb{R}^t$, $\text{conv}(S)$ convex hull of S .

Then, any $x \in \text{conv}(S)$ is a convex combination of at most $t+1$ elements of S .

How to optimize measurement for lacc?

3. EB Davies, IEEE Trans Info Th, 24, p596, 1978
Sasaki, Barnett, Jozsa, Osaki, Hirota 9812062
Decker 0509122

Informally: many equiprobable ensembles of states with symmetry have optimal measurement with the same symmetry.

How to optimize measurement for lacc?

3. Ensembles with symmetry

Example 2. Define the ensemble \mathcal{E}_1 with

$$p(0) = p(1) = p(2) = 1/3, \quad \rho_x = |\psi_x\rangle\langle\psi_x|, \quad |\psi_0\rangle = |0\rangle$$

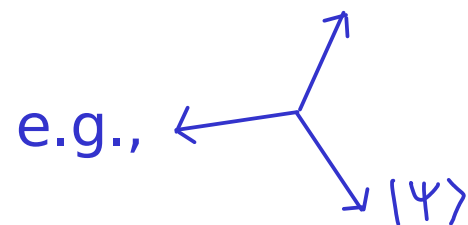
$$|\psi_1\rangle = \cos\frac{\pi}{3}|0\rangle + \sin\frac{\pi}{3}|1\rangle$$

$$|\psi_2\rangle = \cos\frac{\pi}{3}|0\rangle - \sin\frac{\pi}{3}|1\rangle$$

9812062: optimal meas has POVM

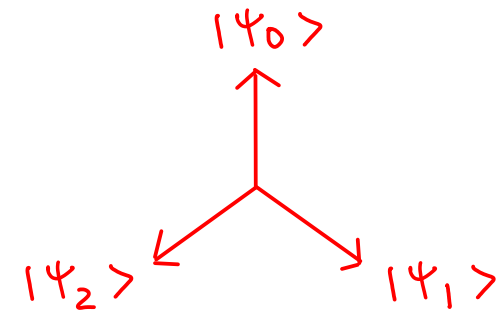
$$M_1 = \{M_k = \frac{2}{3} R^k |\psi\rangle\langle\psi| R^{k\dagger}\}_{k=0,1,2}$$

where $R = e^{i\sigma_y \frac{2}{3}\pi}$ (note $R^k |\psi_0\rangle = |\psi_k\rangle$)



Ex: optimal

$$|\psi\rangle = |\psi_0^\perp\rangle = |1\rangle.$$



(the trine or "Mercedes" states)

$$\text{So, } M_0 = |\psi_0^\perp\rangle\langle\psi_0^\perp| = |1\rangle\langle 1|$$

$$M_1 = |\psi_1^\perp\rangle\langle\psi_1^\perp|, \quad |\psi_1^\perp\rangle = \sin\frac{\pi}{3}|0\rangle - \cos\frac{\pi}{3}|1\rangle$$

$$M_2 = |\psi_2^\perp\rangle\langle\psi_2^\perp|, \quad |\psi_2^\perp\rangle = \sin\frac{\pi}{3}|0\rangle + \cos\frac{\pi}{3}|1\rangle$$

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$$M_1 = \{M_k\}_{k=0,1,2}$$

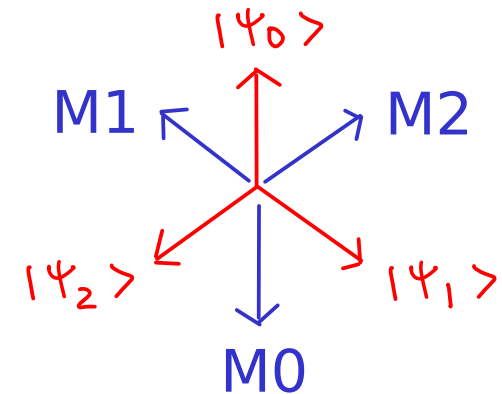
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$$M_2 = |\psi_2^\perp\rangle\langle\psi_2^\perp|, \quad |\psi_2^\perp\rangle = \sin\frac{\pi}{3}|0\rangle + \cos\frac{\pi}{3}|1\rangle$$

$$|\psi_1\rangle = \cos\frac{\pi}{3}|0\rangle + \sin\frac{\pi}{3}|1\rangle$$

$$|\psi_2\rangle = \cos\frac{\pi}{3}|0\rangle - \sin\frac{\pi}{3}|1\rangle$$



Ex: find $\text{pr}(y|x)$ for all x,y .

$$\text{If } y=0, \quad \text{pr}(x=0|y=0) = 0$$

$$\text{pr}(x=1|y=0) = \text{pr}(x=2|y=0) = 1/2, \quad \text{so } H(X|y=0) = 1.$$

$$H(X|Y) = p(y=0) H(X|y=0) + p(y=1) H(X|y=1) + p(y=2) H(X|y=2) = 1$$

$\frac{1}{3} \cdot 1 \quad \frac{1}{3} \cdot 1 \quad \frac{1}{3} \cdot 1$

$$\text{lacc} = H(X) - H(X|Y) = (\log 3) - 1 = 0.5850.$$