



Unitary groups

Hermitian inner product on \mathbb{C}^n

$$\langle x, y \rangle = \sum_{i=1}^n \bar{x}_i y_i$$

Unitary group: matrices A such that

$$\langle Ax, Ay \rangle = \langle x, y \rangle \quad \forall x, y$$

Do they preserve length?

$$\langle x+y, x+y \rangle = \langle A(x+y), A(x+y) \rangle$$

$$\begin{aligned} \langle x, x \rangle + \langle y, y \rangle + \langle x, y \rangle + \langle y, x \rangle &= \langle Ax, Ax \rangle + \langle Ay, Ay \rangle \\ &\quad + \langle Ax, y \rangle + \langle Ay, x \rangle \end{aligned}$$

$$\text{So } \langle Ax, y \rangle + \langle Ay, x \rangle = \langle x, y \rangle + \langle y, x \rangle$$

Use $ix+y$ in place of $x+y$:

$$-i \langle Ax, y \rangle + i \langle Ay, x \rangle = -i \langle x, y \rangle + i \langle y, x \rangle.$$

If U is unitary, $U^*U = I \Rightarrow |\det(U)| = 1$.

Constructing unitary matrices

1) Use an orthonormal basis

2) If $H^* = -H$ (skew Hermitian) then $\exp(H)$ is unitary

3) If $H^* = -H$ and $H+I$ is invertible, then

$$U = (I+H)(I-H)^{-1}$$

is unitary.

Cayley transform
 $(H = -(I-U)(I+U)^{-1})$

4) Diagonal, diagonal entries of norm 1.

5) reflections

$$\tau_{a,\alpha}(v) = v - (1-\alpha) \frac{\langle a, v \rangle}{\langle a, a \rangle} a$$

So $\tau(v) = v$ if $\langle a, v \rangle = 0$ and

$$\tau(a) = \alpha a$$

Claim: $\tau_{a,\alpha}$ is unitary if $|\alpha| = 1$

over \mathbb{R} ,
take $\alpha = -1$

It's called a reflection if α has finite order.

($|\alpha| = 1$) and P is a projection

$$((1-\bar{\alpha})P-I)((1-\alpha)P-I)$$

$$= (1-\bar{\alpha})(1-\alpha)P - (1-\bar{\alpha})P - (1-\alpha)P + I$$

but $(1-\bar{\alpha})(1-\alpha) = 2 - \alpha - \bar{\alpha}$ and therefore

$(1-\alpha)P - I$ is unitary.

Neighbourhood of identity in $U(n)$.

If $U = I + H$ then

$$I = U^*U = (I + H^*)(I + H) = I + H + H^* + HH^*$$

Hence $U \approx I$ then $H + H^* \approx 0$.

If $H + H^* = 0$, then $\exp(H)$ is unitary.

If $H^* = -H$ & $K^* = -K$, then

$$(HK - KH)^* = (-K)(-H) - (-H)(-K) = -(HK - KH)$$

If M & N are $n \times n$ matrices $MN - NM$ is their

Lie bracket, denoted $[M, N]$.

A Lie algebra is a vector space V with a bilinear map $V \times V \rightarrow V$, denoted $[M, N]$ such that

$$(a) [N, M] = -[M, N]$$

$$(b) [L, [M, N]] + [M, [N, L]] + [N, [L, M]] = 0$$

Jacobi identity

e.g. square matrices with

$$[M, N] = (MN - NM)$$

$$\begin{aligned} & \cancel{LMN} - \cancel{LNM} - \cancel{MNL} + \cancel{NML} \\ & \cancel{MNL} - \cancel{MLN} - \cancel{NLM} + \cancel{LNM} \\ & \cancel{NLM} - \cancel{NML} - \cancel{LMN} + \cancel{MLN} \end{aligned}$$

A **derivation** on an algebra A is a linear map δ in $\text{End}(A)$ such that

$$\delta(AB) = \delta(A)B + A\delta(B)$$

Note that

$$\delta(I) = \delta(I^2) = \delta(I)I + I\delta(I) = 2\delta(I)$$

$$\Rightarrow \delta(I) = 0.$$

Claim The set $D(A)$ of derivations of A is a Lie algebra.

Example: $\delta_A: M \mapsto AM - MA$ is a derivation. on $\text{Mat}_{n \times n}(\mathbb{C})$

Claim If L is a Lie algebra, then

$$\exp(L) := \{ \exp(M) : M \in L \}$$

is a group. (A Lie group.)

A better (not the official) definition is that a **Lie group** is a closed subgroup of $\text{Mat}_{n \times n}(\mathbb{C})$.

Gates A set of gates (for quantum computing) is set of unitary matrices that generates a dense subgroup Γ of $U(n)$.

What do want from Γ ?

- given a unitary matrix U , a short expression for U as a product of gates.
- an algorithm for finding the expression.

Gates from controllable graphs

Let X be a graph on n vertices,

If $S \subseteq V(X)$ with characteristic vector z

then (X, S) is controllable if the walk matrix

$$M_S(X) = [z \quad Az \quad \dots \quad A^{n-1}z]$$

is invertible.

Theorem If (X, S) is controllable and z is the characteristic vector of S , then the Lie algebra generated A & zz^T is $\text{Mat}_{n \times n}(\mathbb{R})$.

The real Lie algebra generated by iA & izz^T is the algebra of a skew-Hermitian matrices.

Remark: if (X, S) is controllable, the matrices $A^i z z^T A^j$ ($0 \leq i, j \leq n-1$) are a basis for $\text{Mat}_{n \times n}(\mathbb{R})$.

Proof (of theorem) Let $Z = z\bar{z}^r$

We prove by induction on k that, for each k the Lie algebra generated by A & Z contains

$$A^{k-i} Z A^i, \quad (i=0, \dots, k)$$

There are integers c_r such that

$$Z A^r Z = c_r Z$$

We work through the cases $k=0, 1, 2, 3$

(k=0) z z

(k=1) If $z \in \mathcal{L}$, so is $Az - zA$ and

$$\begin{aligned} [z, [A, z]] &= z(Az - zA) - (Az - zA)z \\ &= zAz - z^2A - Az^2 - zAz \end{aligned}$$

Here $zA, z = c, z$ and $z^2 = |s|z$. So $zA + Az \in \mathcal{L}$

Therefore Az & $zA \in \mathcal{L}$. Az zA

(k=2) We have

$$A^2z - A^2z, AzA - zA^2 \Rightarrow A^2z - zA^2 \in \mathcal{L}$$

Then $[z, A^2z - zA^2] = zA^2z - z^2A^2 - A^2z^2 + zA^2z$ and

so $A^2z + zA^2 \in \mathcal{L}$. Consequently, in \mathcal{L} we have: A^2z, AzA, zA^2

$$(k=3) \quad A^3Z - A^2ZA, A^2ZA - AZA^2, AZA^2 - ZA^3 \in \mathcal{L} \rightarrow A^3Z - ZA^3 \in \mathcal{L},$$

Hence we also have

$$[Z, A^3Z - ZA^3] = ZA^3Z - Z^2A^3 - A^3Z^2 + ZA^3Z \rightarrow A^3Z + ZA^3 \in \mathcal{L}.$$

$$\text{T for } A^3Z \in \mathcal{L} \rightarrow A^3Z, A^2ZA, AZA^2, ZA^3$$

Lemma If (X, S) is controllable, the Lie algebra generated by iA & iZ is the Lie algebra of all skew-Hermitian matrices

Proof Define the degree of an element of \mathfrak{L} inductively

degree 0: A, Z

1: $[A, Z]$

$r+1$: $[A, X], [Z, X], \text{deg}(\mathcal{L})=r$

Commutators of even weight are symmetric, those of odd weight are skew-symmetric.

It follows that the even-weight subspace of \mathfrak{g} consists of the real symmetric matrices, the odd-weights give the skew-symmetric matrices.

Consider the Lie algebra generated by iA & iZ . Even weights are skew-Hermitian, odd weights are real and skew-symmetric. So it's the Lie algebra of skew Hermitian matrices

Theorem [Godsil, Severini] If (X, S) is controllable, and s, t are positive reals, the group G generated by

$$\exp(isA), \exp(itZ)$$

is a dense subgroup of $U(n)$.

Proof The closure of G is a Lie group and iA & iZ generate its tangent space...

Remark If $v \in V(X)$, then $(X, \{v\})$ is controllable
if & only if $\phi(X, t)$ & $\phi(X - v, t)$ are coprime.
So the end-vertices of paths are controllable,