



Controllable graphs

Lemma $A(x)$ has no eigenvector orthogonal to h if and only if

$$\langle A, hh^* \rangle = \text{Mat}_{n \times n}(\mathbb{C})$$

The pair (X, h) is **controllable** if

$$\langle A, hh^T \rangle = \text{Mat}_{n \times n}(\mathbb{R}).$$

The graph X is **controllable** if

$$\langle A, J \rangle = \text{Mat}_{n \times n}(\mathbb{R}).$$

Theorem [O'Rourke & Tzur] Almost all graphs are controllable. For almost all graphs, all the pairs $(A, e_a e_a^T)$ ($a \in V(X)$) are controllable.

Lemma X is controllable $\Leftrightarrow \phi(X, t)$ and $\phi(X, -t-1)$ are coprime. The vertex a is controllable iff $\phi(X, t)$ & $\phi(X-a, t)$ are coprime.

Lemma If X is controllable, $\text{Aut}(X) = \langle I \rangle$.

If (X, e_a) is controllable, then $\text{Aut}(X)_a = \langle I \rangle$.

Proof. Every permutation matrix commutes with J , and a permutation matrix P commutes with A if & only if $P \in \text{Aut}(X)$.

So if $P \in \text{Aut}(X)$, then $P \in \text{comm}(\langle A, J \rangle)$

and so $P = I$. □

An isomorphism invariant for controllable graphs.

Assume $|V(X)| = n$ and define

$$W_X = \begin{bmatrix} \underline{1} & \underline{A} \underline{1} & \dots & \underline{A}^{n-1} \underline{1} \end{bmatrix} \quad \text{walk matrix}$$

We can order the rows lexicographically, in this case we say W_X is ordered.

(Note that if W_X is invertible, no two rows of W_X are equal.)

Theorem Let X and Y be controllable graphs with ordered walk matrices W_X and W_Y respectively. Then $X \cong Y$ if and only if $\phi(X, t) = \phi(Y, t)$ and $W_X = W_Y$

Proof. We have

$$A_X W_X = W_X C_{\phi(X)}, \quad A_Y W_Y = W_Y C_{\phi(Y)}$$

If $W_X = W_Y$, then

$$(A_X - A_Y) W_X = W_X (C_{\phi(X)} - C_{\phi(Y)})$$

If W_X is invertible, $A_X = A_Y$.

□

Reminder: if $W = [h \quad Ah \quad \dots \quad A^{n-1}h]$, then

$$AW = [Ah \quad A^2h \quad \dots \quad A^nh]$$

$$= [h \quad Ah \quad \dots \quad A^{n-1}h] \begin{bmatrix} \vdots & 0 & * \\ I_{n-1} & \vdots & \vdots \\ \vdots & \vdots & * \end{bmatrix}$$

companion matrix
of $\phi(x, t)$

$$= W C_{\phi(x, t)}$$

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Theorem If X & Y are controllable and

$$W(X, t) = W(Y, t), \quad A^k \neq 1$$

then $\mathcal{O}(X, t) = \mathcal{O}(Y, t)$.

Proof Set $A = A(X)$, $B = A(Y)$. Define

$$\hat{W}_X = [\underline{1} \quad \underline{A} \quad \dots \quad \underline{A}^n \quad \underline{1}], \quad \hat{W}_Y = [\underline{1} \quad \underline{B} \quad \dots \quad \underline{B}^n \quad \underline{1}]$$

Then

$$(\hat{W}_X^T \hat{W}_X)_{ij} = \underline{1}^T A^{i+j-2} \underline{1}$$

and therefore

$$\hat{W}_X^T \hat{W}_X = \hat{W}_Y^T \hat{W}_Y$$

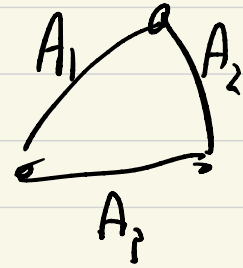
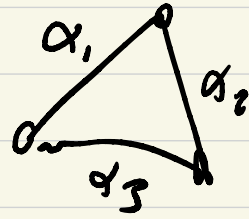
Gram matrices
of columns

Two sets of vectors $\{b_1, \dots, b_k\}$ & $\{c_1, \dots, c_k\}$ are congruent if $\langle b_i, b_j \rangle = \langle c_i, c_j \rangle \quad \forall i, j$

Theorem. The vectors $\{b_1, \dots, b_k\}$ & $\{c_1, \dots, c_k\}$ are congruent if & only if there is an orthogonal matrix Q such that $Qb_i = c_i$ for all i .

So if $B = [b_1, \dots, b_k]$, $C = [c_1, \dots, c_k]$ and $B^T B = C^T C$, then $C = QB$, for some orthogonal Q .

Euclidean geometry



Sketch of proof:

(a) reduce to case where the columns of B and C are linearly independent.

(b) If b_1, \dots, b_j are linearly independent and $\langle x, x \rangle = \langle y, y \rangle$ and $\langle x, b_i \rangle = \langle y, b_i \rangle$ then there exists orthogonal Q s.t. $Qb_i = b_i$ ($i=1, \dots, j$) and $Qx = y$.

To prove (b), show that there is a reflection swapping x & y and fixing b_1, \dots, b_j

↓

- $T_a(u) := u - \frac{2 \langle a, u \rangle}{\langle a, a \rangle} a$

- $T_a(a) = -a, \quad T_a(u) = u$ if $u \in a^\perp$

- T_a is orthogonal

$$a = x - y$$

We had $\hat{W}_x^T \hat{W}_x = \hat{W}_y^T \hat{W}_y$.

It follows that there is an orthogonal matrix Q such that $Q \hat{W}_x = \hat{W}_y$. Therefore

$$QA^k \underline{1} = B^k \underline{1} \quad (0 \leq k \leq n)$$

and $Q \underline{1} = \underline{1}$. Hence

$$QA^n Q^T \underline{1} = B^n \underline{1}$$

and sc QAQ^T & B have the same characteristic polynomial. □

Let $N_i(t)$ be the generating function for walks in X that start at i and never return. Then

$$W_i(X, t) = W_{i,i}(X, t) N_i(t)$$

$$W(X, t) - W(X \setminus i, t) = W_{i,i}(X, t) N_i(t)^2$$

$$\Rightarrow W(X, t) - W(X \setminus i, t) = \frac{W_i(X, t)^2}{W_{i,i}(X, t)} \quad \frac{\phi(X \setminus i, t)}{\phi(X, t)}$$

Corollary $W_i(X, t)$ is determined by $W(X, t)$

$W(X \setminus i, t)$ and $\phi(X \setminus i, t)$; $W(X \setminus i, t)$ is

determined by $\phi(X \setminus i, t)$ & $\phi(\overline{X \setminus i}, t)$

Theorem If X is controllable, it is vertex reconstructible.

Lemma [Hagos] The polynomials $\phi(X \setminus i, t)$ and $\phi(\bar{X} \setminus i, t)$ ($i \in V(X)$) determine $\phi(X, t)$ and $\phi(\bar{X}, t)$.

Proof of theorem. Suppose $V(Y) = V(X)$ and $X \setminus i \cong Y \setminus i$ for all i in $V(X)$. Then X & Y have the same walk matrix W . Now

$$A(X)W = W C_{\phi(X, t)}, \quad A(Y)W = W C_{\phi(Y, t)}$$

$$\Rightarrow A(X) = A(Y)$$