

In this report we see why solving the complementary slackness condition by affine scaling direction (ie solve for  $X S + X dS + dX S = 0$  instead of  $X S + X dS + dX S = \mu I$ ) is, in the limit, equivalent to solving an ODE with the central path as the stable manifold.

Suppose we start out with some distance from the central path:

$$E_o := X_o S_o - \mu_o I$$

affine scaling direction with (infinitesimal) step length  $dt$  gives

$$\begin{aligned} & \begin{bmatrix} A & 0 & 0 & 0 \\ 0 & A^T & I & 0 \\ S & 0 & X & 0 \\ 0 & 0 & 0 & I \end{bmatrix} \\ & \begin{bmatrix} dX \\ dy \\ dS \\ d(\mu) \end{bmatrix} \\ & = -dt \begin{bmatrix} A(X) - b \\ A^T y + S - C \\ XS \\ I\mu \end{bmatrix} \end{aligned}$$

or

$$\begin{aligned} & \begin{bmatrix} A & 0 & 0 & 0 \\ 0 & A^T & I & 0 \\ S & 0 & X & 0 \\ 0 & 0 & 0 & I \end{bmatrix} \\ & \begin{bmatrix} \frac{dX}{dt} \\ \frac{dy}{dt} \\ \frac{dS}{dt} \\ \frac{d(\mu)}{dt} \end{bmatrix} \\ & = \begin{bmatrix} -A(X) + b \\ -A^T y - S + C \\ -XS \\ -I\mu \end{bmatrix} \end{aligned}$$

The last equation  $\frac{d(\mu)}{dt} = -\mu$  comes from the previous knowledge that  $\mu(t) = -K e^{(-t)}$

Write out the third equation explicitly:

$$\left[\frac{dX}{dt}\right] S + X \left[\frac{dS}{dt}\right] = -X S$$

subtract  $\frac{d(\mu)}{dt}$  from both sides

$$\left[\frac{dX}{dt}\right] S + X \left[\frac{dS}{dt}\right] - \left[\frac{d(\mu)}{dt}\right] I = -X S - \left[\frac{d(\mu)}{dt}\right] I$$

remembering that  $\frac{d(\mu)}{dt} = -\mu$ , we obtain

$$\begin{aligned} \left[\frac{dX}{dt}\right] S + X \left[\frac{dS}{dt}\right] - \left[\frac{d(\mu)}{dt}\right] I &= -X S + \mu I \\ &= -(X S - \mu I) \end{aligned}$$

The LHS can be written as a perfect derivative

$$\left[\frac{dX}{dt}\right] S + X \left[\frac{dS}{dt}\right] - \left[\frac{d(\mu)}{dt}\right] I = \frac{d(X S - \mu I)}{dt}$$

so

$$\begin{aligned} &\frac{d(X S - \mu I)}{dt} \\ &= -(X S - \mu I) \end{aligned}$$

define

$$E := X S - \mu I$$

we get

$$\frac{dE}{dt} = -E$$

or

$$E = E_0 e^{-t}$$

in other words, the deviation from the central path decays exponentially. Therefore, we conclude that the central path is a stable manifold. This shows that the affine scaling direction is more than a heuristic.