

Semidefinite relaxation of the max-cut problem

A. Dudek, K. Ghobadi, E. Kim, S. Lin, R. Spjut, J. Zhu

MSRI Workshop on Continuous Optimization and its Applications

July 17, 2007

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Project Statement

Problem

Find the SDP relaxation of the Max-Cut problem:

- 1 Solve this relaxation using e.g. SeDumi with MATLAB.
- 2 Use randomly generated, weighted, undirected graphs, e.g. `W=sprandsym(60, .5)`.
- 3 Can you strengthen the relaxation by adding additional constraints? (Hint: consider constraints of the type $x_i x_k^2 x_j = x_i x_j$.)

Let $G = (V, E)$ be a graph and let $w : E \rightarrow \mathbb{R}$ be an **edge weight function** on G and set $n = |V|$.

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A Review of Max-cut

$$w_{ij} := \begin{cases} w((i,j)) & \text{if } (i,j) \in E \\ 0 & \text{otherwise} \end{cases}$$

- Let $W = (w_{ij})$, the matrix whose ij -th entry is w_{ij} .
- A **cut** is a partition of V into two sets $C \subset V$ and $V \setminus C$. Its **size** is

$$s(C) := \sum_{i \in C, j \in V \setminus C} w_{ij}$$

- A cut C is **maximal** if $\forall \tilde{C} \in 2^V, s(C) \geq s(\tilde{C})$

Max-Cut Problem

For a weighted graph (V, E, w) find a maximal cut C .

Remark

The Max-Cut problem is NP-hard.

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We reformulate the Max-Cut problem:

Problem: Reformulation of Max-Cut Problem

Given any cut C , define

$$x := (x_1, \dots, x_n)^T, \quad x_i := \begin{cases} 1 & i \in C \\ -1 & i \notin C \end{cases}$$

$$\begin{aligned} \text{Maximize} \quad & t = \frac{1}{2} \sum_{i < j} w_{ij} (1 - x_i x_j) \\ \text{subject to} \quad & x_i \in \{-1, 1\} \quad \forall i \in V. \end{aligned}$$

Let $e := (1, 1, \dots, 1)^T$, where $e \in \mathbb{R}^n$.

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Some Equalities for t

► Skip long string of equalities for t

$$\begin{aligned}
 t &= \frac{1}{2} \sum_{i < j} w_{ij} (1 - x_i x_j) = \frac{1}{4} \left(2 \left(\sum_{i < j} w_{ij} \right) - 2 \left(\sum_{i < j} w_{ij} x_i x_j \right) \right) \\
 &= \frac{1}{4} \left(2 \left(\sum_{i < j} w_{ij} x_i^2 \right) + \left(\sum_i w_{ii} - w_{ii} \right) - 2 \left(\sum_{i < j} w_{ij} x_i x_j \right) \right) \\
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 &= \frac{1}{4} \left(\left(\sum_i \left(\sum_j w_{ij} \right) x_i^2 \right) - x^T W x \right) = \frac{1}{4} \left(\left(\sum_i (We)_i x_i^2 \right) - x^T W x \right) \\
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Reformulation and Relaxation of Max-Cut Problem

- $t = x^T Lx = \text{trace}(x^T Lx) = \text{trace}(x^T (Lx)) = \text{trace}((Lx)x^T) = \text{trace}(LX) = L \bullet X$, where $X = xx^T$ is a real symmetric matrix, $\implies X \succeq 0$.
- $\text{diag}(X) = e \iff x_i^2 = 1 \iff x_i \in \{-1, 1\}$.

Lemma

$$X = X^T \succeq 0, \text{rank}(X) = 1 \iff X = xx^T$$

W is the edge-weight matrix $\rightsquigarrow L = \frac{1}{4} (\text{Diag}(We) - W) \rightsquigarrow$

Problem: Equivalent Reformulation of Max-Cut Problem

Maximize $L \bullet X$
 subject to $\text{diag}(X) = e, \text{rank}(X) = 1$, and $X \succeq 0$.

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subject to $\text{diag}(X) = e, \text{rank}(X) = 1$, and $X \succeq 0$.

Reformulation and Relaxation of Max-Cut Problem

- $t = x^T Lx = \text{trace}(x^T Lx) = \text{trace}(x^T (Lx)) = \text{trace}((Lx)x^T) = \text{trace}(LX) = L \bullet X$, where $X = xx^T$ is a real symmetric matrix, $\implies X \succeq 0$.
- $\text{diag}(X) = e \iff x_i^2 = 1 \iff x_i \in \{-1, 1\}$.

Lemma

$$X = X^T \succeq 0, \text{rank}(X) = 1 \iff X = xx^T$$

W is the edge-weight matrix $\rightsquigarrow L = \frac{1}{4} (\text{Diag}(We) - W) \rightsquigarrow$

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Problem: SDP Relaxation of Max-Cut Problem

Maximize $L \bullet X$
 subject to $\text{diag}(X) = e$ and $X \succeq 0$.

Setting up an Instance

We setup an instance of the Max-Cut problem in MATLAB with the following code:

```
% Fix the dimension (number of vertices in graph)
n=60;

% Generate a weighted graph
W=sprandsym(n, .5); W(1:n+1:n^2)=zeros(1,n);

% Calculate the Laplacian
L=1/4 * (diag(W*ones(n,1))-W);
```

Interfacing with SeDumi

To be consistent with the notation of SeDumi's documentation and interface, substitute “ x ” for “ z ”. The SeDumi primal form is

$$\begin{aligned} & \text{Minimize} && c^T z \\ & \text{subject to} && Az = b, \text{ for } z \in \mathcal{K} \end{aligned}$$

where $c, z, b \in \mathbb{R}^p$, and A is a $p \times p$ matrix. In MATLAB,

```
c=-L(:); % Format the Laplacian to vector form

% Translate constraint diag(X)=e into vector format:
A=sparse(1:n,1:n+1:n^2,ones(1,n),n,n^2);
b=ones(n,1);

% Tell SeDumi that X must be positive semidefinite
K.s=[n];

[X,Y,INFO] = sedumi(A,b,c,K) % Run SeDumi
```

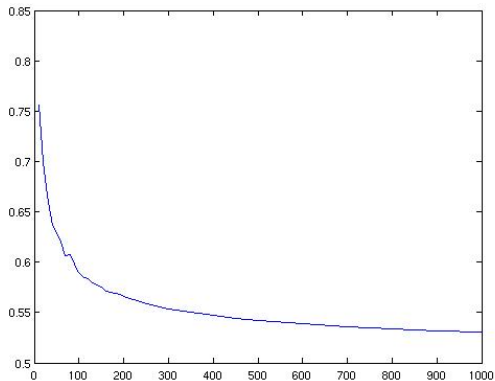
Interfacing with SeDumi

A visual summary of $Az = b$

$$\left(\begin{array}{cccc|cccc|cccc| \dots | ccc}
 \mathbf{1} & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 & 0 & \dots & 0 \\
 0 & 0 & \dots & 0 & 0 & \mathbf{1} & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 & 0 & \dots & 0 \\
 0 & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 & 0 & 0 & \mathbf{1} & \dots & 0 & 0 & \dots & 0 \\
 \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots \\
 0 & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 & 0 & \dots & \mathbf{1}
 \end{array} \right)_{n \times n^2} \dots \left(\begin{array}{c}
 x_{11} \\
 x_{12} \\
 \vdots \\
 x_{1n} \\
 x_{21} \\
 x_{22} \\
 x_{23} \\
 \vdots \\
 x_{2n} \\
 x_{31} \\
 x_{32} \\
 x_{33} \\
 \vdots \\
 x_{3n} \\
 \vdots \\
 x_{n1} \\
 \vdots \\
 x_{nn}
 \end{array} \right)_{n^2 \times 1} = \left(\begin{array}{c}
 1 \\
 1 \\
 1 \\
 \vdots \\
 1
 \end{array} \right)_{n \times 1}$$

Numerical Results: Basic Relaxation $G(n, \frac{1}{2})$

n	Ratio
50	6.292239e-01
60	6.202113e-01
70	6.067923e-01
80	6.074731e-01
90	5.980219e-01
100	5.894269e-01
110	5.849831e-01
120	5.837704e-01
130	5.793048e-01
140	5.777026e-01
150	5.749815e-01
160	5.715093e-01
170	5.702395e-01
180	5.686022e-01
190	5.675917e-01
200	5.654331e-01
250	5.591398e-01
300	5.538571e-01
350	5.506719e-01
400	5.472742e-01
450	5.441005e-01
500	5.422019e-01
600	5.390324e-01
700	5.359528e-01
800	5.337012e-01
900	5.320470e-01
1000	5.303538e-01



Triangle Inequalities

An idea proposed by Poljak and Rendl (1995), and further developed by Helmberg, Rendl, Vanderbei and Wolkowicz (1996):

For each triple, $x_i, x_j, x_k \in \{-1, 1\}$ we have

$$x_{ij} + x_{jk} + x_{ki} \geq -1 \quad (1)$$

$$x_{ij} - x_{jk} - x_{ki} \geq -1 \quad (2)$$

$$-x_{ij} + x_{jk} - x_{ki} \geq -1 \quad (3)$$

$$-x_{ij} - x_{jk} + x_{ki} \geq -1. \quad (4)$$

With (1)-(4), we have the **strengthened** SDP relaxation:

Problem: Strengthened Relaxation of Max-Cut Problem

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Replacing Inequalities (1)-(4) with Equalities for SeDumi's Input Format

Introduce **slack variables** $s_{ijk\ell} \geq 0$ to get equalities for SeDumi.

$$x_{ij} + x_{jk} + x_{ki} - s_{ijk1} = -1$$

$$x_{ij} - x_{jk} - x_{ki} - s_{ijk2} = -1$$

$$-x_{ij} + x_{jk} - x_{ki} - s_{ijk3} = -1$$

$$-x_{ij} - x_{jk} + x_{ki} - s_{ijk4} = -1$$

- Considering (1)-(4) when a pair of i, j, k are the same is redundant.
- So we are concerned with “only” $N := 2n(n-1)(n-2)/3$ slack variables.

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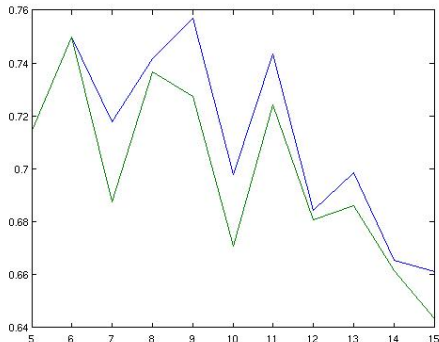
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 & \mathbf{1} & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 & \dots & 0 & \dots & 0 \\
 \mathbf{0}_{n \times N} & 0 & 0 & \dots & 0 & 0 & \mathbf{1} & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 & \dots & 0 & \dots & 0 \\
 & 0 & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 & 0 & 0 & \mathbf{1} & \dots & 0 & \dots & 0 & \dots & 0 \\
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 \hline
 \mathbf{-I}_{N \times N} & 0 & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 & \dots & 0 & \dots & \mathbf{1}
 \end{array} \right) \begin{array}{c}
 s_{1,2,3,1} \\
 s_{1,2,4,1} \\
 \vdots \\
 s_{1,3,4,1} \\
 s_{1,3,5,1} \\
 \vdots \\
 s_{2,3,4,1} \\
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 s_{n-2,n-1,n,1} \\
 \hline
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 \end{array} = \begin{pmatrix} I_{n \times 1} \\ -I_{N \times 1} \end{pmatrix}_{n+N \times 1}$$

Numerical Results: Triangle Relaxation $G(n, \frac{1}{2})$

n	Ratio 1	Ratio 2
5	7.142857e-01	7.142857e-01
6	7.500000e-01	7.500000e-01
7	7.177745e-01	6.875000e-01
8	7.417858e-01	7.368421e-01
9	7.570369e-01	7.272727e-01
10	6.978259e-01	6.709667e-01
11	7.433614e-01	7.241379e-01
12	6.845083e-01	6.808511e-01
13	6.986989e-01	6.862745e-01
14	6.655176e-01	6.615384e-01
15	6.613215e-01	6.433655e-01



Quadruple Equalities

An idea of Goemans developed by Anjos and Wolkowicz (2002):

For each quadruple $x_i, x_j, x_j, x_k \in \{-1, 1\}$ we have:

$$x_i x_j x_j x_k = x_i x_j^2 x_k = x_i x_k. \quad (5)$$

With (5), we have the SDP formulation:

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Second lifting/relaxation

After **lifting**

$$Y = \begin{bmatrix} y & y^T \end{bmatrix}, \text{ where } y = \text{vec}(X)$$

We have the max-cut problem:

$$\begin{aligned} \text{Maximize} \quad & \begin{bmatrix} L & 0 \\ 0 & 0 \end{bmatrix} \bullet Y = L \bullet Y_{11} \\ \text{subject to} \quad & \text{diag}(Y) = e & \text{(S1)} \\ & Y \succeq 0 & \text{(S2)} \\ & Y_{11} = Y_{ii} \quad \forall i = 2, \dots, n & \text{(S3)} \\ & \text{diag}(Y_{ij}) = Y_{ii}^{(i,j)} e & \text{(S4)} \\ & Y_{ij} e_j = Y_{11} e_i \quad \forall j = 2, \dots, n, \quad i < j & \text{(S5)} \\ & \text{rank}(Y) = 1. & \text{(S6)} \end{aligned}$$

Theorem

The second lifting relaxation provides a tighter upper bound.

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Tighter Upper Bound Theorem

- Suppose that X^* is an optimal solution to the first lifting relaxation.
 - If $\text{Rank}(X^*) = 1$, then we have the optimal solution to the original max-cut problem.
 - If $\text{Rank}(X^*) > 1$, we will show that after lifting X^* to $\bar{Y} = (yy^T)$, where $y = \text{vec } X^*$, \bar{Y} is not feasible to the second relaxation.
 - By contradiction, we assume that \bar{Y} is feasible to the second relaxation, then it satisfies (S4) and (S5), which implies that $X_{ik}^* X_{kj}^* = X_{ij}^*$ for all i, j, k .
 - Hence, $X^* = xx^T$, where $x = (X_{1k}^*, X_{2k}^*, \dots, X_{nk}^*)$, which contradicts $\text{Rank } X^* > 1$.
 - Therefore, \bar{Y} is not feasible to the second lifting relaxation.
- On the other hand, if Y is feasible to the second lifting relaxation, by (S1) and (S2), $\text{diag}(Y_{11}) = e$ and $Y_{11} \succeq 0$.
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 - By contradiction, we assume that \bar{Y} is feasible to the second relaxation, then it satisfies (S4) and (S5), which implies that $X_{ik}^* X_{kj}^* = X_{ij}^*$ for all i, j, k .
 - Hence, $X^* = xx^T$, where $x = (X_{1k}^*, X_{2k}^*, \dots, X_{nk}^*)$, which contradicts $\text{Rank } X^* > 1$.
 - Therefore, \bar{Y} is not feasible to the second lifting relaxation.
- On the other hand, if Y is feasible to the second lifting relaxation, by (S1) and (S2), $\text{diag}(Y_{11}) = e$ and $Y_{11} \succeq 0$.
- Then, Y_{11} is feasible to the first lifting relaxation. \square

Numerical Results: Comparison of Algorithms

Comparison of Algorithm Performance

relaxation	n=4	n = 6	n = 8	n = 10
SDP	2.00000000	6.43225787	9.52050490	17.0875592
TRI	1.99999999	5.99999995	8.99999986	16.9999998
QUAD	1.99999999	5.99999988	8.99999900	16.9999996

Thanks!!

Thanks for your attention!

Semidefinite relaxation of the max-cut problem

A. Dudek, K. Ghobadi, E. Kim, S. Lin, R. Spjut, J. Zhu

MSRI Workshop on Continuous Optimization and its Applications

July 17, 2007