

# **CO350 Linear Programming**

## **Chapter 5: Basic Solutions**

30th May 2005

# Recap

Last week, we learn

- Definition of a basis  $B$  of matrix  $A$ .
  - Definition of basic solution  $x^*$  of  $Ax = b$  determined by basis  $B$ .
  - $x^*$  is a basic solution if and only if  $\{A_j : x_j^* \neq 0\}$  is linearly independent.
  - Definition of basic feasible solution of  $\{Ax = b, x \geq 0\}$ .
  - Definition of convex sets.
  - Definition of extreme points of convex sets.
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## Relating bfs and extreme points

**Theorem 5.3 (Pg 63)** Let  $A$  be  $m$  by  $n$  with rank  $m$ .

Let  $F$  be the set  $\{x : Ax = b, x \geq 0\}$ .

$x^*$  is a bfs of  $\{Ax = b, x \geq 0\}$

$\iff x^*$  is an extreme point of  $F$ .

**Proof:** " $\implies$ " [Contradiction]

Suppose  $x^*$  is a bfs.

$x^*$  is a feasible solution  $\implies x^* \in F$ .

$x^*$  is basic solution  $\implies x^*$  is determined by some basis  $B$ .

Suppose  $x^*$  is not an extreme point of  $F$ .

$x^* \in F \implies x^*$  lie strictly between two vectors in  $F$ .

I.e., there are  $x^1, x^2 \in F$  with  $x^1 \neq x^2$  and  $0 < \lambda < 1$  such that  $x^* = \lambda x^1 + (1 - \lambda)x^2$ .

For each  $j \notin B$ ,  $x_j^* = 0$ .

So  $0 = x_j^* = \lambda x_j^1 + (1 - \lambda)x_j^2$

$x^1, x^2 \geq 0$  and  $0 < \lambda < 1 \implies \lambda x_j^1$  and  $(1 - \lambda)x_j^2 \geq 0$ .

So  $\lambda x_j^1 = (1 - \lambda)x_j^2 = 0$ . Hence  $x_j^1 = x_j^2 = 0$ .

Now  $x_j^1 = x_j^2 = 0$  for all  $j \notin B$ , and also  $Ax^1 = Ax^2 = b$ .

This means that  $x^1$  and  $x^2$  are both basic solutions of  $Ax = b$  determined by  $B$ .

This contradicts  $x^1 \neq x^2$ .

**Theorem 5.3 (Pg 63)** Let  $A$  be  $m$  by  $n$  with rank  $m$ .  
Let  $F$  be the set  $\{x : Ax = b, x \geq 0\}$ .

$x^*$  is a bfs of  $\{Ax = b, x \geq 0\}$

$\iff x^*$  is an extreme point of  $F$ .

**Proof:** “ $\Leftarrow$ ” [Contradiction]

Suppose  $x^*$  is an extreme point of  $F$ .

$x^* \in F \implies Ax^* = b$  and  $x^* \geq 0$ .

Suppose  $x^*$  is not a basic feasible solution.

$x^*$  feasible  $\implies x^*$  is not basic.

So  $\{A_j : x_j^* \neq 0\}$  is a linearly dependent set (Thm 5.1).

Let  $J = \{j : x_j^* \neq 0\}$ .

Linearly dependent: there exists  $d_j$  ( $j \in J$ ) such that not all  $d_j$ 's are zeros and

$$\sum_{j \in J} d_j A_j = 0$$

Fill the remaining  $d_j$ 's with zeros; i.e.  $d_j = 0$  for  $j \notin J$ .

We now have

$$\sum_{j=1}^n d_j A_j = 0$$

i.e.,  $Ad = 0$ .

**Theorem 5.3 (Pg 63)** Let  $A$  be  $m$  by  $n$  with rank  $m$ .  
Let  $F$  be the set  $\{x : Ax = b, x \geq 0\}$ .

$x^*$  is a bfs of  $\{Ax = b, x \geq 0\}$

$\iff x^*$  is an extreme point of  $F$ .

**Proof:** “ $\Leftarrow$ ” (cont'd)

So far we assumed  $x^*$  is an extreme point but not basic and obtained vector  $d \in \mathbf{R}^n$  such that

$$Ad = 0, \text{ and } d_j = 0 \text{ whenever } x_j^* = 0.$$

Let  $x^1 = x^* - \varepsilon d$  and  $x^2 = x^* + \varepsilon d$ , where  $\varepsilon > 0$ .

Notice that  $x^* = \frac{1}{2}x^1 + \frac{1}{2}x^2$ .

For  $j$  such that  $x_j^* = 0$ , we have  $d_j = 0$ . So  $x_j^1 = x_j^2 = 0$ .

For  $j$  such that  $x_j^* > 0$ , we have  $x_j^1 > 0$  and  $x_j^2 > 0$  for  $\varepsilon$  small enough.

Conclusion:  $x^1, x^2 \geq 0$  for  $\varepsilon > 0$  small enough.

Also,  $Ax^1 = Ax^* - \varepsilon Ad = Ax^* = b$

and  $Ax^2 = Ax^* + \varepsilon Ad = Ax^* = b$ .

So  $x^1$  and  $x^2$  are both feasible; i.e.,  $x^1, x^2 \in F$ .

Now  $x^1 \neq x^2$  (because  $x^2 - x^1 = 2\varepsilon d \neq 0$ )

and  $x^* = \frac{1}{2}x^1 + \frac{1}{2}x^2$

contradicts  $x^*$  is an extreme point of  $F$ .

**Theorem 5.3 (Pg 63)** Let  $A$  be  $m$  by  $n$  with rank  $m$ .  
Let  $F$  be the set  $\{x : Ax = b, x \geq 0\}$ .

$x^*$  is a bfs of  $\{Ax = b, x \geq 0\}$

$\iff x^*$  is an extreme point of  $F$ .

A few remarks: (Not in notes)

- The theorem says that **bfs** and **extreme points** are **algebraic** and **geometric** counterparts.
- The assumption “**A has rank  $m$** ” is necessary!  
Without it, we cannot even define a basis of  $A$ .  
In this case, the theorem fails because  $F$  may still have extreme points but there are no bfs.
- In the proof of the second half, we see that  
if  $x^*$  is feasible but not basic, then  
there exists vector  $d \in \mathbf{R}^n$  such that  
 $d \neq 0$ ,  $d_j = 0$  whenever  $x_j^* = 0$ , and  $Ad = 0$ ,  
and there exists  $\varepsilon > 0$  such that  
both  $x^1 = x^* + \varepsilon d$  and  $x^2 = x^* - \varepsilon d$  are feasible.

## Basic feasible solutions for SIF

For the Orange Factory Problem, we used the SEF to discuss basic solutions, but plotted them on a picture that represents the problem in SIF.

### (Defn) **Basic feasible solution for SIF**

$x^*$  is a bfs of  $\{Ax \leq b, x \geq 0\}$  if

$$\begin{bmatrix} x^* \\ s^* \end{bmatrix} = \begin{bmatrix} x^* \\ b - Ax^* \end{bmatrix}$$

is a bfs of  $\{Ax + s = b, x, s \geq 0\}$ .

**Theorem 5.4 (Pg 65)** Let  $F = \{x : Ax \leq b, x \geq 0\}$ .

$x^*$  is a bfs of  $\{Ax \leq b, x \geq 0\}$

$\iff x^*$  is an extreme point of  $F$ .

**Proof:** Exercise

Hint: Relate extreme points of  $F$  and

$$\left\{ \begin{bmatrix} x \\ s \end{bmatrix} : Ax + s = b, x, s \geq 0 \right\}.$$

This is a very good exercise for you.

Come see me if you need more help/hint for this exercise.

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Example

$$A = \begin{bmatrix} -1 & 2 & 2 \\ 1 & 0 & -2 \end{bmatrix} \quad b = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Find all extreme points of  $\{x : Ax \leq b, x \geq 0\}$ .

By Theorem 5.4, this is equivalent to finding all bfs of  $\{Ax \leq b, x \geq 0\}$

By definition, this is equivalent to finding all basic feasible solutions of

$$\begin{aligned} -x_1 + 2x_2 + 2x_3 + x_4 &= 1 \\ x_1 - x_3 + x_5 &= 1 \\ x_1, x_2, x_3, x_4, x_5 &\geq 0 \end{aligned}$$

$$\text{Let } A' = \begin{bmatrix} -1 & 2 & 2 & 1 & 0 \\ 1 & 0 & -2 & 0 & 1 \end{bmatrix}$$

Procedure: Go through each possible basis  $B$  of  $A'$  and decide if the basic solution determined by  $B$  is feasible.



$$A' = \begin{bmatrix} -1 & 2 & 2 & 1 & 0 \\ 1 & 0 & -2 & 0 & 1 \end{bmatrix} \quad b = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Possible candidates for basis:  $\{1, 2\}, \{1, 3\}, \{1, 4\}, \{1, 5\},$   
 $\{2, 3\}, \{2, 4\}, \{2, 5\},$   
 $\{3, 4\}, \{3, 5\},$   
 $\{4, 5\}$

- $B = \{1, 2\}$  is a basis since  $A_B = \begin{bmatrix} -1 & 2 \\ 1 & 0 \end{bmatrix}$  is nonsingular. It determines basic solution  $[1, 1, 0, 0, 0]^T$  which is feasible.
- $B = \{1, 3\}$  is a not basis since  $A_B = \begin{bmatrix} -1 & 2 \\ 1 & -2 \end{bmatrix}$  is singular.
- $B = \{1, 4\}$  is a basis since  $A_B = \begin{bmatrix} -1 & 1 \\ 1 & 0 \end{bmatrix}$  is nonsingular. It determines basic solution  $[1, 0, 0, 2, 0]^T$  which is feasible.
- $B = \{1, 5\}$  is a basis since  $A_B = \begin{bmatrix} -1 & 0 \\ 1 & 1 \end{bmatrix}$  is nonsingular. It determines basic solution  $[-1, 0, 0, 0, 2]^T$  which is not feasible.
- $B = \{2, 3\}$  is a basis since  $A_B = \begin{bmatrix} 2 & 2 \\ 0 & -2 \end{bmatrix}$  is nonsingular. It determines basic solution  $[0, 1, -\frac{1}{2}, 0, 0]^T$  which is not feasible.
- $B = \{2, 4\}$  is a basis since  $A_B = \begin{bmatrix} 2 & 1 \\ 0 & 0 \end{bmatrix}$  is singular.

$$A' = \begin{bmatrix} -1 & 2 & 2 & 1 & 0 \\ 1 & 0 & -2 & 0 & 1 \end{bmatrix} \quad b = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Possible candidates for basis:  $\{1, 2\}, \{1, 3\}, \{1, 4\}, \{1, 5\},$   
 $\{2, 3\}, \{2, 4\}, \{2, 5\},$   
 $\{3, 4\}, \{3, 5\},$   
 $\{4, 5\}$

- $B = \{2, 5\}$  is a basis since  $A_B = \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}$  is nonsingular.  
It determines basic solution  $[0, \frac{1}{2}, 0, 0, 1]^T$  which is feasible.
- $B = \{3, 4\}$  is a basis since  $A_B = \begin{bmatrix} 2 & 1 \\ -2 & 0 \end{bmatrix}$  is nonsingular.  
It determines basic solution  $[0, 0, -\frac{1}{2}, 2, 0]^T$  which is not feasible.
- $B = \{3, 5\}$  is a basis since  $A_B = \begin{bmatrix} 2 & 0 \\ -2 & 1 \end{bmatrix}$  is nonsingular.  
It determines basic solution  $[0, 0, \frac{1}{2}, 0, 2]^T$  which is feasible.
- $B = \{4, 5\}$  is a basis since  $A_B = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$  is nonsingular.  
It determines basic solution  $[0, 0, 0, 1, 1]^T$  which is feasible.

In conclusion, the extreme points are

$$[1, 1, 0]^T, [1, 0, 0]^T, [0, \frac{1}{2}, 0]^T, [0, 0, \frac{1}{2}]^T, [0, 0, 0]^T$$