# The Traveling Tournament Problem: Complexity Aspects

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Salomon Bendayan (2022). The Traveling Tournament Problem. UWSpace. http://hdl.handle.net/10012/18553

Traveling Tournament Problem

(Easton, Nemhauser, Trick 2001)

Given *n* teams (*n* is even) and inter-team metric distances (i.e.,  $n \times n$  matrix *D* of inter-team distances satisfying the triangle inequality) find a tournament (i.e., a double round-robin schedule) such that

- each pair of teams i, j plays two games, one at home-venue of i and one at home-venue of j,
- the total distance travelled is minimized (assume "round-trip travel" for each team, that starts & ends at home-venue).

#### Notes:

Number of rounds = number of days = 2(n-1)OBJ: min  $\sum_{\text{TEAM } i}$  (distance traveled by i over 2(n-1) days)

#### TTP: Example with n = 6 teams



TTP: Example with n = 6 teams

Team	1	2	3	4	5	6
Dayl						
<b>1</b>	<b>@5</b>	C4	<u>e6</u>	2	1	3
2	6	5	4	e3	C2	C1
3	2	@1	<u>@</u> 5	@6	3	4
4	<b>@</b> 3	<b>@6</b>	1	5	@4	2
5	4	3	@2	<b>@1</b>	6	<b>@</b> 5
G	5	4	6	<b>C</b> 2	@1	@3
7	<b>@6</b>	<b>@5</b>	C4	3	2	1
8	<u>e</u> 2	1	5	6	@3	@4
9	3	6	@1	୧୨	4	@2
10	C4	C3	2	1	<b>C6</b>	5
Trips by Team1:					Trips	by Team6:
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5	E.	)			GL	·

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# TTP: Questions

Is there a poly-time algorithm for optimally solving TTP?

Is there a PTAS (i.e., poly-time approximation scheme) for solving TTP?

# TTP: Results

 (Bhattacharyya'09, ORL'16) (unrestricted) TTP is NP-hard.
 ( ⇒ ∄ poly-time algorithm, assuming P ≠ NP)

# (BCC) (unrestricted) TTP is APX-hard. (⇒ *A* PTAS, assuming P ≠ NP)

TTP: Results & Open Question

▶ (Bhattacharyya'09, ORL'16) (unrestricted) TTP is NP-hard. (⇒ A poly-time algorithm, assuming P ≠ NP)
▶ (BCC) (unrestricted) TTP is APX-hard. (⇒ A PTAS, assuming P ≠ NP)

- ► (Thielen, Westphal TCS'11) 3-restricted TTP is NP-hard.
- ► (**Open**) 3-restricted TTP is APX-hard?

- Let c > 5 be a constant.
- G is a complete graph on n vertices, with edge costs in {1,2}, v is a designated vertex of G.
- ► G<sup>(c)</sup> is the "one sum" of c copies of G with common vertex v, it has c(n − 1) + 1 vertices.
- G' is the metric completion of  $G^{(c)}$ .



Figure: Small example: G' from G with c = 3.

- ► G is a complete graph on n vertices, with edge costs in {1,2}, v is a designated vertex of G.
- G' is the metric completion of  $G^{(c)}$ , where  $G^{(c)}$  is the "one sum" of c (c > 5) copies of G with common vertex v.
- ▶ Claim: an optimal TSP tour on G has cost  $K \iff$  an optimal TSP tour on G' has cost cK.



Figure: Small example: G' from G with c = 3.

- G is a complete graph on n vertices, with edge costs in {1,2}, v is a designated vertex of G.
   K := cost of optimal TSP tour of G.
- G' is the metric completion of G<sup>(c)</sup>, where G<sup>(c)</sup> is the "one sum" of c (c > 5) copies of G with common vertex v.
   cK := cost of optimal TSP tour of G',
   m := |V(G')| = c(n-1) + 1.
- Construct a new graph *H* by adding vertex *u* to *G'*, and connecting *u* to all vertices of *G'* with edges of cost w<sub>u</sub> = (cK − 1)/2.
- Construct the TTP instance on H by placing 2 teams at v (the central vertex of G'), one team at every other vertex of G', and (m + 1)(10m − 1) teams at u to get n' = 10m(m + 1) teams in total.

#### Lemma

H has a feasible TTP solution of cost  $\leq 20m(m+1)cK$ .

- Construct a new graph H by adding vertex u to G', and connecting u to all vertices of G' with edges of cost w<sub>u</sub>.
- Construct the TTP instance on H by placing 2 teams at v (the central vertex of G'), one team at every other vertex of G', and (m + 1)(10m − 1) teams at u to get n' = 10m(m + 1) teams in total.

#### Lemma

*H* has a feasible *TTP* solution of  $cost \le 20m(m+1)cK$ . Proof.

- Partition the teams into 10m groups, each of size m + 1.
- Group 1 := the m + 1 teams placed on G'.
- DRR schedule consists of batch of intra-group games (with 2m games) followed by batch of inter-group games.

Claim: Cost of DRR schedule  

$$\leq 8m(m+1) + \left( (m+1)2w_u + (10m-1)((m+1)2w_u + mcK) \right).$$

#### TTP: Example with 4 groups



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**Lemma**: *H* has a feasible TTP solution of cost  $\leq 20m(m+1)cK$ . **Proof of lemma**:

- > Partition the teams into 10m groups, each of size m + 1.
- Group 1 := the m + 1 teams placed on G'.
- DRR schedule consists of batch of intra-group games (with 2m games) followed by batch of inter-group games.
  - Intra-group games: All groups, except Group 1, are located at *u* and incur zero cost. Each team in Group 1 plays *m* Away-games and incurs cost ≤ (2c<sub>max</sub>)m = 8m (c<sub>max</sub> = max<sub>e∈G'</sub>(c<sub>e</sub>) = 4). Group 1 has (m + 1) teams, hence, total cost ≤ (2c<sub>max</sub>)m(m + 1) = 8m(m + 1).

Bhattacharyya/BCC construction: uTTP is NP-hard: Proof of lemma

- Partition the teams into 10m groups, each of size m + 1. Group 1 := the m + 1 teams placed on G'.
- DRR schedule consists of batch of intra-group games (with 2m games) followed by batch of inter-group games.
  - Intra-group games:
  - ▶ Inter-group games, Part 1: Construct an "outer" Single Round-Robin (SRR) schedule on the 10*m* groups. Each "outer" game between Groups *i*, *j* maps to (m + 1) games where each team of Group *i* plays against all (m + 1) teams of Group *j* (i.e., edge-coloring of  $K_{m+1,m+1}$  by (m + 1)colors), and

Group *i* plays @Home  $\iff$  each team of Group *i* plays @Home. **Cost analysis**: Assume: Group 1 plays none of its games @Home (each of the (m + 1) teams of Group 1 visits vertex *u*, plays all its games at *u*, then returns to *G'*). Total cost:  $\leq (m + 1)2w_u$ .

Inter-group games, Part 2:

#### Bhattacharyya/BCC construction: uTTP is NP-hard Lemma: H has a feasible TTP solution of cost $\leq 20m(m+1)cK$ . Proof of lemma:

- Partition the teams into 10m groups, each of size m + 1.
- Group 1 := the m + 1 teams placed on G'.
- DRR schedule consists of batch of intra-group games (with 2m games) followed by batch of inter-group games.
  - Intra-group games:
  - Inter-group games, Part 1:
  - Inter-group games, Part 2: Similar to Part 1, but flip Home-Away designations for the "outer" Single Round-Robin (SRR) schedule on the 10*m* groups.
     Cost analysis: Assume: Group 1 plays Home (each of the teams at vertex *u* visits the vertices of *G'* according to an optimal TSP tour of *G'*, then returns to *u*).
     Cost incurred by each group at vertex *u*: (*m*+1)2*w<sub>u</sub>* + (*m*+1)*cK* − *cK*.
     Total cost: ≤ (10*m* − 1)(2*w<sub>u</sub>*(*m*+1)+m*cK*).

# Lemma

H has a feasible TTP solution of  $cost \leq 20m(m+1)cK$ .

#### Proof of lemma:

- ▶ Partition the teams into 10m groups, each of size m + 1.
- Group 1 := the m + 1 teams placed on G'.
- DRR schedule consists of batch of intra-group games (with 2m games) followed by batch of inter-group games.
  - Intra-group games:
    - $Cost \leq 8m(m+1).$
  - Inter-group games, Part 1:
    - $Cost \leq (m+1)2w_u$ .
  - Inter-group games, Part 2:

 $\mathsf{Cost} \leq (10m-1)(2w_u(m+1)+mcK).$ 

► Claim: Cost of DRR schedule  $\leq 8m(m+1) + \left( (m+1)2w_u + (10m-1)((m+1)2w_u + mcK) \right).$ 

Recall: Input graph G has edge-costs of 1 or 2. K := cost of an optimal TSP tour of G.

#### Lemma

H has a feasible TTP solution of  $cost \leq 20m(m+1)cK$ .

#### Lemma

Suppose the cost of an optimal TSP tour of G is  $\geq K + 1$ . Then, any feasible TTP solution of H has cost > 20m(m+1)cK.

# L-reductions . . . for APX-hardness

L-reduction from optimization problem  $\Pi_1$  to optimization problem  $\Pi_2$ :

#### Intent (informal): $\alpha$ -approximation algorithm $\implies f(\alpha)$ -approximation algorithm for $\Pi_2$ for $\Pi_1$ , for some linear function f()

Suppose there is an L-reduction from  $\Pi_1$  to  $\Pi_2$ , and suppose  $\Pi_1$  has **no**  $\beta$ -approximation algorithm (for some  $\beta \ge 1$ ), then

 $\Pi_2$  has **no**  $f^{-1}(\beta)$ -approximation algorithm.

# L-reductions . . . for APX-hardness

L-reduction from optimization problem  $\Pi_1$  to optimization problem  $\Pi_2$ :

# Definition

Given two optimization problems  $\Pi_1$  and  $\Pi_2$ , we say we have an L-reduction from  $\Pi_1$  to  $\Pi_2$  if for some parameters a, b > 0:

- 1. For each instance  $I_1$  of  $\Pi_1$  we can compute in polynomial time an instance  $I_2$  of  $\Pi_2$ .
- 2.  $OPT(I_2) \leq a \cdot OPT(I_1)$ .
- 3. Given a solution of value  $V_2$  to  $I_2$ , we can compute in polynomial time a solution of value  $V_1$  to  $I_1$  such that

$$|\operatorname{OPT}(I_1) - V_1| \le b \cdot |\operatorname{OPT}(I_2) - V_2|$$

# L-reductions ... for APX-hardness

Fact:

- Suppose there is an L-reduction, with parameters a, b, from minimization problem Π<sub>1</sub> to minimization problem Π<sub>2</sub>, and
- ▶ suppose there is an  $\alpha$ -approximation algorithm for  $\Pi_2$ ,
- then there is an  $(1 + ab(\alpha 1))$ -approximation algorithm for  $\Pi_1$ .
- Instance  $I_1$  of  $\Pi_1 \implies$  instance  $I_2$  of  $\Pi_2$ .
- Compute solution  $S_2$  to  $I_2$  of value  $V_2 \leq \alpha \operatorname{OPT}(I_2)$ .
- "Map"  $S_2$  to a solution  $S_1$  of  $I_1$  of value  $V_1$  such that

$$\begin{split} V_1 &\leq \operatorname{OPT}(I_1) + b(V_2 - \operatorname{OPT}(I_2)) \\ &\leq \operatorname{OPT}(I_1) + b(\alpha \operatorname{OPT}(I_2) - \operatorname{OPT}(I_2)) \\ &= \operatorname{OPT}(I_1)(1 + ab(\alpha - 1)) \end{split}$$

- L-reduction from  $\Pi_1$  to  $\Pi_2$ , where
- ▶  $\Pi_1$  is the " $m(m+1) \otimes TSP$ " on input graph *G* which has edge-costs of 1 or 2.

OBJ = m(m+1) times cost of an optimal TSP tour of G, where m = c(n-1) + 1 and n = |V(G)|.

 $\blacktriangleright$   $\Pi_2$  is TTP on the graph *H*.

(Recall: G' is the metric-completion of  $G^{(c)}$ , where  $G^{(c)}$  is the "one-sum" of c > 5 copies of G with common vertex v. H is obtained from G' by adding a new vertex u, adding the edges ux, for all vertices x of G', and taking the cost of each new edge to be  $w_u = (cK - 1)/2$ .)

- L-reduction from  $\Pi_1$  to  $\Pi_2$ , where
- $\Pi_1$  is the " $m(m+1) \otimes TSP$ " on G (edge-costs  $\in \{1, 2\}$ ). OBJ = m(m+1) times cost of an optimal TSP tour of G.
- $\blacktriangleright$   $\Pi_2$  is TTP on the graph *H*.

Recall the three conditions for an L-reduction with parameters a, b > 0:

- 1. For each instance  $I_1$  of  $\Pi_1$  we can compute in polynomial time an instance  $I_2$  of  $\Pi_2$ .
- 2.  $\operatorname{OPT}(I_2) \leq a \cdot \operatorname{OPT}(I_1)$ .
- 3. Given a solution of value  $V_2$  to  $I_2$ , we can compute in polynomial time a solution of value  $V_1$  to  $I_1$  such that

$$|\operatorname{OPT}(I_1) - V_1| \le b \cdot |\operatorname{OPT}(I_2) - V_2|$$

- L-reduction from  $\Pi_1$  to  $\Pi_2$ , where
- $\Pi_1$  is the " $m(m+1) \otimes TSP$ " on G (edge-costs  $\in \{1, 2\}$ ). OBJ = m(m+1) times cost of an optimal TSP tour of G.

$$\blacktriangleright$$
  $\Pi_2$  is TTP on the graph *H*.

Recall the third conditions for an L-reduction with parameters a, b > 0:

Given a solution of value  $V_2$  to  $I_2$ , we can compute in polynomial time a solution of value  $V_1$  to  $I_1$  such that

$$|\operatorname{OPT}(I_1) - V_1| \le b \cdot |\operatorname{OPT}(I_2) - V_2|$$

#### Lemma

Given a TTP schedule S of H with additive slack  $\Delta$  (i.e.,  $cost(S) - OPT_{TTP}(H) \leq \Delta$ ), one can construct a TSP tour T of G with additive slack  $\leq 10\Delta$ (i.e.,  $cost(T) - OPT_{TSP}(G) \leq 10\Delta$ ).

- L-reduction from  $\Pi_1$  to  $\Pi_2$ , where
- $\Pi_1$  is the " $m(m+1) \otimes TSP$ " on G (edge-costs  $\in \{1, 2\}$ ). OBJ = m(m+1) times cost of an optimal TSP tour of G.
- $\blacktriangleright \Pi_2 \text{ is TTP on the graph } H.$

#### Lemma

Given a TTP schedule S of H with additive slack  $\Delta$  (i.e.,  $cost(S) - OPT_{TTP}(H) \leq \Delta$ ),

one can construct a TSP tour T of G with additive slack  $\leq 10\Delta$  (i.e.,  $cost(T) - OPT_{TSP}(G) \leq 10\Delta$ ).

# Claim

Given an **optimal** TTP schedule S of H,

one can construct a TSP tour T of G that is optimal.

# Claim

Given a **non-optimal** TTP schedule S of H,

one can construct a TSP tour T of G such that

 $cost(T) - OPT_{TSP}(G) \leq 10 (cost(S) - OPT_{TTP}(H)).$ 

TTP: Results & Open Question

(BCC) (unrestricted) TTP is APX-hard.
 (⇒ *A* PTAS, assuming P ≠ NP)

- (Open) 3-restricted TTP is APX-hard? (Thielen, Westphal TCS'11) proved 3-restricted TTP is NP-hard.
- Prove Hardness-of-Approximation results for other variants of TTP.
- Design improved approximation algorithms for variants of TTP.
- Concorde-Plus to optimally solve TTP instances with 100 teams?