SYDE Advanced Math 2, Solutions for Practice Problem Set 3

1: (a) Solve the system $\begin{pmatrix} x'\\y' \end{pmatrix} = \begin{pmatrix} 1 & 2\\ 1 & 0 \end{pmatrix} \begin{pmatrix} x\\y \end{pmatrix}$ and draw the direction field and some solution curves. Solution: Let $A = \begin{pmatrix} 1 & 2\\ 1 & 0 \end{pmatrix}$. Then $\det(A - rI) = \det\begin{pmatrix} 1 - r & 2\\ 1 & -r \end{pmatrix} = r^2 - r - 2 = (r+1)(r-2)$. When r = -1 we have $A - rI = \begin{pmatrix} 2 & 2\\ 1 & 1 \end{pmatrix} \sim \begin{pmatrix} 1 & 1\\ 0 & 0 \end{pmatrix}$ and so an eigenvector is $\mathbf{u} = \begin{pmatrix} 1\\ -1 \end{pmatrix}$. When r = 2 we have $A - rI = \begin{pmatrix} -1 & 2\\ 1 & -2 \end{pmatrix} \sim \begin{pmatrix} 1 & -2\\ 0 & 0 \end{pmatrix}$ so an eigenvector is $\mathbf{v} = \begin{pmatrix} 2\\ 1 \end{pmatrix}$. The solution to the system is $\begin{pmatrix} x\\y \end{pmatrix} = ae^{-t}\begin{pmatrix} 1\\ -1 \end{pmatrix} + be^{2t}\begin{pmatrix} 2\\ 1 \end{pmatrix}$.

To sketch the direction field, note that the isoclines are given by $m = \frac{y'}{x'} = \frac{x}{x+2y}$, that is mx + 2my = x, or equivalently $y = \frac{1-m}{2m}x$. This is the line through (0,0) with slope $\frac{1-m}{2m}$. Some isoclines are shown in yellow, the direction field is shown in green , and some solution curves are shown in blue.



(b) Solve the system $\begin{pmatrix} x'\\y' \end{pmatrix} = \begin{pmatrix} 1 & 2\\ -2 & 1 \end{pmatrix} \begin{pmatrix} x\\y \end{pmatrix}$ and draw the direction field and some solution curves.

Solution: Let $A = \begin{pmatrix} 1 & 2 \\ -2 & 1 \end{pmatrix}$. Then $\det(A - rI) = \det\begin{pmatrix} 1 - r & 2 \\ -2 & 1 - r \end{pmatrix} = r^2 - 2r + 5 = (r - 1)^2 + 4$. The eigenvalues are $r = 1 \pm 2i$. When r = 1 + 2i we have $A - rI = \begin{pmatrix} -2i & 2 \\ -2 & -2i \end{pmatrix} \sim \begin{pmatrix} -i & 1 \\ 0 & 0 \end{pmatrix}$ so an eigenvector is $\mathbf{u} = \begin{pmatrix} 1 \\ i \end{pmatrix}$. A complex solution is

$$\begin{pmatrix} z \\ w \end{pmatrix} = e^{(1+2i)t} \begin{pmatrix} 1 \\ i \end{pmatrix} = e^t (\cos 2t + i \sin 2t) \begin{pmatrix} 1 \\ i \end{pmatrix} = e^t \begin{pmatrix} \cos 2t + i \sin 2t \\ -\sin 2t + i \cos 2t \end{pmatrix}$$

Two independent real solutions are obtained from the real and imaginary parts of the above complex solution. The general solution is

$$\begin{pmatrix} x \\ y \end{pmatrix} = ae^t \begin{pmatrix} \cos 2t \\ -\sin 2t \end{pmatrix} + be^t \begin{pmatrix} \sin 2t \\ \cos 2t \end{pmatrix}.$$

The isoclines are given by $m = \frac{y'}{x'} = \frac{-2x+y}{x+2y}$, that is mx + 2my = -2x + y, or equivalently $y = \frac{2+m}{1-2m}x$. This is the line through (0,0) of slope $\frac{2+m}{1-2m}$. Some isoclines are shown in yellow, the slope field is shown in green, and some solution curves are shown in blue.



2: (a) Find the solution to the system $\begin{pmatrix} x'\\y' \end{pmatrix} = \begin{pmatrix} 1 & -2\\ 2 & -3 \end{pmatrix} \begin{pmatrix} x\\y \end{pmatrix}$ with $\begin{pmatrix} x(0)\\y(0) \end{pmatrix} = \begin{pmatrix} 2\\1 \end{pmatrix}$. Solution: Let $A = \begin{pmatrix} 1 & -2\\ 2 & -3 \end{pmatrix}$. Then $\det(A - rI) = \det\begin{pmatrix} 1 - r & -2\\ 2 & -3 - r \end{pmatrix} = r^2 + 2r + 1 = (r+1)^2$. When r = -1 we have $A - rI = \begin{pmatrix} 2 & -2\\ 2 & -2 \end{pmatrix} \sim \begin{pmatrix} 1 & -1\\ 0 & 0 \end{pmatrix}$ so an eigenvector is $\mathbf{u} = \begin{pmatrix} 1\\ 1 \end{pmatrix}$. Note also that when $\mathbf{v} = \begin{pmatrix} 1\\ 0 \end{pmatrix}$ we have $(A - rI)\mathbf{v} = \begin{pmatrix} 2 & -2\\ 2 & -2 \end{pmatrix} \begin{pmatrix} 1\\ 0 \end{pmatrix} = \begin{pmatrix} 2\\ 2 \end{pmatrix} = 2\mathbf{u}$. Thus the general solution to the system is

$$\begin{pmatrix} x \\ y \end{pmatrix} = ae^{-t} \begin{pmatrix} 1 \\ 1 \end{pmatrix} + be^{-t} \begin{pmatrix} 1 \\ 0 \end{pmatrix} + bte^{-t} \begin{pmatrix} 2 \\ 2 \end{pmatrix} .$$

To get x(0) = 2 we need 2 = a + b and to get y(0) = 1 we need 1 = a, so we must take a = 1 and b = 1, and we obtain the solution

$$\begin{pmatrix} x \\ y \end{pmatrix} = e^{-t} \begin{pmatrix} 2 \\ 1 \end{pmatrix} + te^{-t} \begin{pmatrix} 2 \\ 2 \end{pmatrix}$$

(b) Find the solution to the system $\begin{pmatrix} x'\\y' \end{pmatrix} = \begin{pmatrix} 1 & -2\\4 & 5 \end{pmatrix} \begin{pmatrix} x\\y \end{pmatrix}$ with $\begin{pmatrix} x(0)\\y(0) \end{pmatrix} = \begin{pmatrix} 1\\2 \end{pmatrix}$. Solution: Let $A = \begin{pmatrix} 1 & -2\\4 & 5 \end{pmatrix}$. Then $\det(A - rI) = \det\begin{pmatrix} 1-r & -2\\4 & 5-r \end{pmatrix} = r^2 - 6r + 13 = (r-3)^2 + 4$, The eigenvalues are $r = 3 \pm 2i$. When r = 3 + 2i we have $A - rI = \begin{pmatrix} -2 - 2i & -2\\4 & 2 - 2i \end{pmatrix} \sim \begin{pmatrix} 2 & 1-i\\0 & 0 \end{pmatrix}$ so an eigenvector is $\mathbf{u} = \begin{pmatrix} 1-i\\-2 \end{pmatrix}$. A complex solution is

$$\begin{pmatrix} z \\ w \end{pmatrix} = e^{(3+2i)t} \begin{pmatrix} 1-i \\ -2 \end{pmatrix} = e^{3t} \left(\cos 2t + i\sin 2t\right) \begin{pmatrix} 1-i \\ -2 \end{pmatrix} = e^{3t} \left(\frac{(\cos 2t + \sin 2t) + i(\sin 2t - \cos 2t)}{-2\cos 2t - 2i\sin 2t} \right).$$

Two independent real solutions are given by the real and imaginary parts of this complex solution, so the general solution to the system is

$$\begin{pmatrix} x \\ y \end{pmatrix} = ae^{3t} \begin{pmatrix} \sin 2t + \cos 2t \\ -2\cos 2t \end{pmatrix} + be^{3t} \begin{pmatrix} \sin 2t - \cos 2t \\ -2\sin 2t \end{pmatrix}$$

To get x(0) = 1 we need 1 = a - b and to get y(0) = 2 we need 2 = -2a, so we must have a = -1 and b = -2, and so the solution is

$$\begin{pmatrix} x \\ y \end{pmatrix} = -e^{3t} \begin{pmatrix} \sin 2t + \cos 2t \\ -2\cos 2t \end{pmatrix} - 2e^{3t} \begin{pmatrix} \sin 2t - \cos 2t \\ -2\sin 2t \end{pmatrix} = e^{3t} \begin{pmatrix} \cos 2t - 3\sin 2t \\ 4\sin 2t + 2\cos 2t \end{pmatrix}.$$

3: (a) Solve the system $\begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} 1 & 2 \\ -1 & 4 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} + \begin{pmatrix} 6t+1 \\ e^t \end{pmatrix}.$

Solution: First we solve the associated homogeneous system. Let $A = \begin{pmatrix} 1 & 2 \\ -1 & 4 \end{pmatrix}$.

Then $\det(A - rI) = \det\begin{pmatrix} 1 - r & 2 \\ -1 & 4 - r \end{pmatrix} = r^2 - 5r + 6 = (r - 2)(r - 3)$ so the eigenvalues are r = 2, 3. When r = 2 we have $A - rI = \begin{pmatrix} -1 & 2 \\ -1 & 2 \end{pmatrix} \sim \begin{pmatrix} 1 & -2 \\ 0 & 0 \end{pmatrix}$ so an eigenvector is $\mathbf{u} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$. When r = 3 we have $A - rI = \begin{pmatrix} -2 & 2 \\ -1 & 1 \end{pmatrix} \sim \begin{pmatrix} 1 & -1 \\ 0 & 0 \end{pmatrix}$ so an eigenvector is $\mathbf{v} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$. Thus the general solution to the homogeneous system is

$$\begin{pmatrix} x \\ y \end{pmatrix} = ae^{2t} \begin{pmatrix} 2 \\ 1 \end{pmatrix} + be^{3t} \begin{pmatrix} 1 \\ 1 \end{pmatrix} .$$

We shall find a particular solution to the given non-homogeneous system using variation of parameters. We try $\begin{pmatrix} x_p \\ y_p \end{pmatrix} = X \begin{pmatrix} r \\ s \end{pmatrix}$ where $X = \begin{pmatrix} 2e^{2t} & e^{3t} \\ e^{2t} & e^{3t} \end{pmatrix}$. Putting this in the non-homogeneous system gives $\begin{pmatrix} r' \\ s' \end{pmatrix} = \begin{pmatrix} 2e^{2t} & e^{3t} \\ e^{2t} & e^{3t} \end{pmatrix}^{-1} \begin{pmatrix} 6t+1 \\ e^t \end{pmatrix} = e^{-5t} \begin{pmatrix} e^{3t} & -e^{3t} \\ -e^{2t} & 2e^{2t} \end{pmatrix} \begin{pmatrix} 6t+1 \\ e^t \end{pmatrix}$ $= e^{-5t} \begin{pmatrix} (6t+1)e^{3t} - e^{4t} \\ -(6t+1)e^{2t} + 2e^{3t} \end{pmatrix} = \begin{pmatrix} (6t+1)e^{-2t} - e^{-t} \\ -(6t+1)e^{-3t} + 2e^{-2t} \end{pmatrix}$.

We integrate (using integration by parts) to obtain

$$r = \int (6t+1)e^{-2t} - e^{-t} dt = -\frac{1}{2}(6t+1)e^{-2t} - \frac{3}{2}e^{-2t} + e^{-t} = -(3t+2)e^{-2t} + e^{-t} , \text{ and } s = \int -(6t+1)e^{-3t} + 2e^{-2t} dt = \frac{1}{3}(6t+1)e^{-3t} + \frac{2}{3}e^{-3t} - e^{-t} = (2t+1)e^{-3t} - e^{-2t} .$$

Thus we obtain the particular solution

$$\begin{pmatrix} x_p \\ y_p \end{pmatrix} = \begin{pmatrix} 2e^{2t} & e^{3t} \\ e^{2t} & e^{3t} \end{pmatrix} \begin{pmatrix} -(3t+2)e^{-2t} + e^{-t} \\ (2t+1)e^{-3t} - e^{-2t} \end{pmatrix} = \begin{pmatrix} -2(3t+2) + 2e^t + (2t+1) - e^t \\ -(3t+2) + e^t + (2t+1) - e^t \end{pmatrix} = \begin{pmatrix} -4t - 3 + e^t \\ -t - 1 \end{pmatrix} .$$

The general solution to the given system is

$$\begin{pmatrix} x \\ y \end{pmatrix} = ae^{2t} \begin{pmatrix} 2 \\ 1 \end{pmatrix} + be^{3t} \begin{pmatrix} 1 \\ 1 \end{pmatrix} + \begin{pmatrix} -4t - 3 + e^t \\ -t - 1 \end{pmatrix}.$$

(b) Solve the system $\begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} 3 & -4 \\ 5 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} + \begin{pmatrix} 1 \\ 5e^{3t} - 4 \end{pmatrix}.$

Solution: First we solve the associated homogeneous system. Let $A = \begin{pmatrix} 3 & -4 \\ 5 & -1 \end{pmatrix}$.

Then det(A - rI) = det $\begin{pmatrix} 3 - r & -4 \\ 5 & -1 - r \end{pmatrix}$ = $r^2 - 2r + 17 = (r - 1)^2 + 16$, so the eigenvalues are $r = 1 \pm 4i$. When r = 1 + 4i we have $A - rI = \begin{pmatrix} 2 - 4i & -4 \\ 5 & -2 - 4i \end{pmatrix} \sim \begin{pmatrix} 1 - 2i & -2 \\ 0 & 0 \end{pmatrix}$ so an eigenvector is $\mathbf{u} = \begin{pmatrix} 2 \\ 1 - 2i \end{pmatrix}$. A complex solution is

$$\begin{pmatrix} z \\ w \end{pmatrix} = e^{(1+4i)t} \begin{pmatrix} 2 \\ 1-2i \end{pmatrix} = e^t \left(\cos 4t + i \sin 4t \right) \begin{pmatrix} 2 \\ 1-2i \end{pmatrix} = e^t \left(\frac{2\cos 4t + i \sin 4t}{(2\sin 4t + \cos 4t) + i (\sin 4t - 2\cos 4t)} \right)$$

so the general solution to the associated homogeneous system is

$$\begin{pmatrix} x \\ y \end{pmatrix} = ae^t \begin{pmatrix} 2\cos 4t \\ 2\sin 4t + \cos 4t \end{pmatrix} + be^t \begin{pmatrix} 2\sin 4t \\ \sin 4t - 2\cos 4t \end{pmatrix}$$

We shall find a particular solution to the non-homogeneous system using the method of undetermined coefficients. We try $\begin{pmatrix} x_p \\ y_p \end{pmatrix} = \begin{pmatrix} c \\ d \end{pmatrix} + e^{3t} \begin{pmatrix} r \\ s \end{pmatrix}$. Put this into the system of DEs. The left side is

$$LS = \begin{pmatrix} x_{p'} \\ y_{p'} \end{pmatrix} = \begin{pmatrix} 3re^{3t} \\ 3se^{3t} \end{pmatrix}$$

and the right side is

$$\begin{split} RS &= \begin{pmatrix} 3 & -4 \\ 5 & -1 \end{pmatrix} \begin{pmatrix} x_p \\ y_p \end{pmatrix} + \begin{pmatrix} 1 \\ 5e^{3t} - 4 \end{pmatrix} = \begin{pmatrix} 3 & -4 \\ 5 & -1 \end{pmatrix} \begin{pmatrix} c + re^{3t} \\ d + se^{3t} \end{pmatrix} + \begin{pmatrix} 1 \\ 5e^{3t} - 4 \end{pmatrix} \\ &= \begin{pmatrix} 3c + 3re^{3t} - 4d - 4se^{3t} + 1 \\ 5c + 5pe^{3t} - d - qe^{3t} + 5e^{3t} - 4 \end{pmatrix}. \end{split}$$

In order to have LS = RS we need $3re^{3t} = 3c + 3re^{3t} - 4d - 4se^{3t} + 1 = 0$, that is $(3c - 4d + 1) + (-4s)e^{3t} = 0$, and $3se^{3t} = 5c + 5re^{3t} - d - se^{3t} + 5e^{3t} - 4$, that is $(5c - d - 4) + (5r - 4s + 5)e^{3t} = 0$. Since 1 and e^{3t} are linearly independent, the coefficients must all vanish, so we have 3c - 4d + 1 = 0, 5c - d - 4 = 0, -4s = 0and 5r - 4s + 5 = 0. The first two of these equations give c = 1 and d = 1 and the second two give r = -1and s = 0. Thus we obtain the particular solution

$$\begin{pmatrix} x_p \\ y_p \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} + e^{3t} \begin{pmatrix} -1 \\ 0 \end{pmatrix}$$

The general solution to the given system is

$$\begin{pmatrix} x \\ y \end{pmatrix} = ae^t \begin{pmatrix} 2\cos 4t \\ 2\sin 4t + \cos 4t \end{pmatrix} + be^t \begin{pmatrix} 2\sin 4t \\ \sin 4t - 2\cos 4t \end{pmatrix} + \begin{pmatrix} 1 \\ 1 \end{pmatrix} + e^{3t} \begin{pmatrix} -1 \\ 0 \end{pmatrix} + be^{3t} \begin{pmatrix} -1 \\ 0 \end{pmatrix} + be^{$$

4: Find the solution to the system $\begin{pmatrix} x'\\y'\\z' \end{pmatrix} = \begin{pmatrix} 2 & -2 & 1\\1 & -1 & 1\\2 & -4 & 3 \end{pmatrix} \begin{pmatrix} x\\y\\z \end{pmatrix}$ with $\begin{pmatrix} x(0)\\y(0)\\z(0) \end{pmatrix} = \begin{pmatrix} 1\\2\\1 \end{pmatrix}$.

Solution: Let
$$A = \begin{pmatrix} 2 & -2 & 1 \\ 1 & -1 & 1 \\ 2 & -4 & 3 \end{pmatrix}$$
. Then

$$\det(A - rI) = \det \begin{pmatrix} 2 - r & -2 & 1 \\ 1 & -1 - r & 1 \\ 2 & -4 & 3 - r \end{pmatrix}$$

$$= -(r - 2)(r - 3)(r + 1) - 4 - 4 - 4(r - 2) - 2(r - 3) + 2(r + 1)$$

$$= -(r - 2)(r - 3)(r + 1) - 4r + 8 = -(r - 2)((r - 3)(r + 1) + 4)$$

$$= -(r - 2)(r^2 - 2r + 1) = -(r - 2)(r - 1)^2.$$

When r = 2 we have

$$A - rI = \begin{pmatrix} 0 & -2 & 1 \\ 1 & -3 & 1 \\ 2 & -4 & 1 \end{pmatrix} \sim \begin{pmatrix} 1 & -3 & 1 \\ 0 & 2 & -1 \\ 0 & 2 & -1 \end{pmatrix} \sim \begin{pmatrix} 1 & -3 & 1 \\ 0 & 1 & -\frac{1}{2} \\ 0 & 2 & -1 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & -\frac{1}{2} \\ 0 & 1 & -\frac{1}{2} \\ 0 & 0 & 0 \end{pmatrix}$$
eigenvector is $\mathbf{u} = \begin{pmatrix} 1 \\ 1 \\ 2 \end{pmatrix}$. When $r = 1$ we have
$$A - rI = \begin{pmatrix} 1 & -2 & 1 \\ 1 & -2 & 1 \\ 2 & -4 & 2 \end{pmatrix} \sim \begin{pmatrix} 1 & -2 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

so we have the two independent eigenvectors $\mathbf{v} = \begin{pmatrix} 1\\ 0\\ -1 \end{pmatrix}$ and $\mathbf{w} = \begin{pmatrix} 2\\ 1\\ 0 \end{pmatrix}$. Thus the general solution to the system is

so an

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = ae^{2t} \begin{pmatrix} 1 \\ 1 \\ 2 \end{pmatrix} + be^t \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} + ce^t \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} .$$

To get x(0) = 1 we need a + b + 2c = 1, to get y(0) = 2 we need a + 0b + c = 2, and to get z(0) = 1 we need 2a - b + 0c = 1. We solve these three equations:

$$\begin{pmatrix} 1 & 1 & 2 & | & 1 \\ 1 & 0 & 1 & | & 2 \\ 2 & -1 & 0 & | & 1 \end{pmatrix} \sim \begin{pmatrix} 1 & 1 & 2 & | & 1 \\ 0 & 1 & 1 & | & -1 \\ 0 & 3 & 4 & | & 1 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & 1 & | & 2 \\ 0 & 1 & 1 & | & -1 \\ 0 & 0 & 1 & | & 4 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & 0 & | & -2 \\ 0 & 1 & 0 & | & -5 \\ 0 & 0 & 1 & | & 4 \end{pmatrix} .$$

Thus a = -2, b = -5 and c = 4, so the solution is

$$\begin{pmatrix} x\\ y\\ z \end{pmatrix} = -2e^{2t} \begin{pmatrix} 1\\ 1\\ 2 \end{pmatrix} - 5e^t \begin{pmatrix} 1\\ 0\\ -1 \end{pmatrix} + 4e^t \begin{pmatrix} 2\\ 1\\ 0 \end{pmatrix} = -2e^{2t} \begin{pmatrix} 1\\ 1\\ 2 \end{pmatrix} + e^t \begin{pmatrix} 3\\ 4\\ 5 \end{pmatrix}$$

5: Solve the system
$$\begin{pmatrix} x'\\y'\\z' \end{pmatrix} = \begin{pmatrix} 1 & 1 & -2\\-2 & -2 & 2\\3 & 2 & -3 \end{pmatrix} \begin{pmatrix} x\\y\\z \end{pmatrix} + e^{-2t} \begin{pmatrix} -1\\2\\2\\2 \end{pmatrix}$$
.
Solution: Let $A = \begin{pmatrix} 1 & 1 & -2\\-2 & -2 & 2\\3 & 2 & -3 \end{pmatrix}$. Then
 $\det(A - rI) = \det \begin{pmatrix} 1 - r & 1 & -2\\-2 & -2 - r & 2\\3 & 2 & -3 - r \end{pmatrix}$
$$= -(r - 1)(r + 2)(r + 3) + 6 + 8 + 4(r - 1) - 2(r + 3) - 6(r + 2)$$
$$= -(r - 1)(r + 2)(r + 3) - 4r - 8 = -(r + 2)((r - 1)(r + 3) + 4)$$
$$= -(r + 2)(r^2 + 2r + 1) = -(r + 2)(r + 1)^2.$$

When r = -2 we have

$$A - rI = \begin{pmatrix} 3 & 1 & -2 \\ -2 & 0 & 2 \\ 3 & 2 & -1 \end{pmatrix} \sim \begin{pmatrix} 1 & 1 & 0 \\ -2 & 0 & 2 \\ 3 & 2 & -1 \end{pmatrix} \sim \begin{pmatrix} 1 & 1 & 0 \\ 0 & 2 & 2 \\ 0 & 1 & 1 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

so an eigenvector is $\mathbf{u} = \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}$. When $r = -1$ we have
$$A - rI = \begin{pmatrix} 2 & 1 & -2 \\ -2 & -1 & 2 \\ 3 & 2 & -2 \end{pmatrix} \sim \begin{pmatrix} 1 & 1 & 0 \\ -2 & -1 & 2 \\ 3 & 2 & -2 \end{pmatrix} \sim \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 2 \\ 0 & 1 & 2 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & -2 \\ 0 & 1 & 2 \\ 0 & 1 & 2 \end{pmatrix}$$

so one eigenvector is $\mathbf{v} = \begin{pmatrix} 2 \\ -2 \\ 1 \end{pmatrix}$. We look for a vector \mathbf{w} such that $(A - rI)\mathbf{w} = \mathbf{v}$:

$$\begin{pmatrix} 2 & 1 & -2 & | & 2 \\ -2 & -1 & 2 & | & -2 \\ 3 & 2 & -2 & | & 1 \end{pmatrix} \sim \begin{pmatrix} 1 & 1 & 0 & | & -1 \\ -2 & -1 & 2 & | & -2 \\ 3 & 2 & -2 & | & 1 \end{pmatrix} \sim \begin{pmatrix} 1 & 1 & 0 & | & -1 \\ 0 & 1 & 2 & | & -4 \\ 0 & 1 & 2 & | & -4 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & -2 & | & 3 \\ 0 & 1 & 2 & | & -4 \\ 0 & 0 & 0 & | & 0 \end{pmatrix}$$

and we obtain $\mathbf{w} = \begin{pmatrix} 3 \\ -4 \\ 0 \end{pmatrix}$. Thus the general solution to the associated homogeneous system is

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = ae^{-2t} \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} + be^{-t} \begin{pmatrix} 2 \\ -2 \\ 1 \end{pmatrix} + ce^{-t} \begin{pmatrix} 3 \\ -4 \\ 0 \end{pmatrix} + cte^{-t} \begin{pmatrix} 2 \\ -2 \\ 1 \end{pmatrix}.$$

To find a particular solution to the given non-homogeneous system, we use the method of undetermined coefficients. We try $\mathbf{x} = e^{-2t}\mathbf{p} + te^{-2t}\mathbf{q}$, where $\mathbf{x} = (x_p, y_p, z_p)^T$ and \mathbf{p} and \mathbf{q} are vectors in \mathbb{R}^3 . We put \mathbf{x} into the non-homogeneous system of DEs. The left side is

$$LS = \mathbf{x}' = -2e^{-2t}\mathbf{p} + e^{-2t}\mathbf{q} - 2te^{-2t}\mathbf{q} = e^{-2t}(-2\mathbf{p} + \mathbf{q}) + te^{-2t}(-2\mathbf{q})$$

and, writing $\mathbf{b} = (-1, 2, 2)^T$, the right side is

$$RS = A\mathbf{x} + e^{-2t}\mathbf{b} = A(e^{-2t}\mathbf{p} + te^{-2t}\mathbf{q}) + e^{-2t}\mathbf{b} = e^{-2t}(A\mathbf{p} + \mathbf{b}) + te^{-2t}A\mathbf{q}$$

To get LS = RS we need $-2\mathbf{p} + \mathbf{q} = A\mathbf{p} + \mathbf{b}$ and $-2\mathbf{q} = A\mathbf{q}$. Note that $-2\mathbf{q} = A\mathbf{q} \iff (A + 2I)\mathbf{q} = 0$ so \mathbf{q} must be an eigenvector of r = -2, and so we must have $\mathbf{q} = k\mathbf{u}$ for some $k \in \mathbb{R}$. Also, note that $-2\mathbf{p} + \mathbf{q} = A\mathbf{p} + \mathbf{b} \iff (A + 2I)\mathbf{p} = \mathbf{q} - \mathbf{b}$, so we solve this to find \mathbf{p} :

$$\begin{pmatrix} 3 & 1 & -2 \\ -2 & 0 & 2 \\ 3 & 2 & -1 \\ \end{vmatrix} \begin{vmatrix} k+1 \\ -k-2 \\ k-2 \\ \end{vmatrix} \sim \begin{pmatrix} 1 & 1 & 0 \\ -2 & 0 & 2 \\ 3 & 2 & -1 \\ \end{vmatrix} \begin{vmatrix} -k-2 \\ k-2 \\ k-2 \\ \end{vmatrix} \sim \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ -k-1 \\ 0 & 2 & 2 \\ \end{vmatrix} \sim \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ -k-1 \\ 0 & 2 & 2 \\ \end{vmatrix} \sim \begin{pmatrix} 1 & 0 & -1 \\ -k-1 \\ 0 & 1 & 1 \\ -k-4 \\ \end{vmatrix} \sim \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 1 \\ -k-1 \\ 0 & 0 & 0 \\ \end{vmatrix} \sim \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 1 \\ -k-1 \\ 0 & 0 & 0 \\ \end{vmatrix} \sim \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 1 \\ -k-1 \\ 0 & 0 & 0 \\ \end{vmatrix}$$

To get a solution, we must take k = 2 and we have $\mathbf{q} = k\mathbf{u} = \begin{pmatrix} 2\\ -2\\ 2 \end{pmatrix}$, and $\mathbf{p} = \begin{pmatrix} k\\ -k-1\\ k-2 \end{pmatrix} = \begin{pmatrix} 2\\ -3\\ 0 \end{pmatrix}$. Thus we obtain the particular solution

$$\begin{pmatrix} x_p \\ y_p \\ z_p \end{pmatrix} = e^{-2t} \begin{pmatrix} 2 \\ -3 \\ 0 \end{pmatrix} + te^{-2t} \begin{pmatrix} 2 \\ -2 \\ 2 \end{pmatrix}$$

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The general solution to the given (non-hommogeneous) system is

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = ae^{-2t} \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} + be^{-t} \begin{pmatrix} 2 \\ -2 \\ 1 \end{pmatrix} + ce^{-t} \begin{pmatrix} 3 \\ -4 \\ 0 \end{pmatrix} + cte^{-t} \begin{pmatrix} 2 \\ -2 \\ 1 \end{pmatrix} + e^{-2t} \begin{pmatrix} 2 \\ -3 \\ 0 \end{pmatrix} + te^{-2t} \begin{pmatrix} 2 \\ -2 \\ 2 \end{pmatrix} .$$